# Strong convergence of Krasnoselski-Mann iteration for a countable family of asymptotically nonexpansive mappings in CAT (0) spaces 

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#### Abstract

Based on a specific way of choosing the indices and a new concept, namely, an analogue of inner product, a modified Krasnoselski-Mann iteration scheme is proposed for approximating common fixed points of a countable family of asymptotically nonexpansive mappings; and a strong convergence theorem is established in the framework of CAT ( 0 ) spaces. Our results greatly improve and extend those of the authors whose related researches just involve a single mapping and the weaker $\Delta$-convergence. (c)2017 All rights reserved.


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## 1. Introduction

Let $(X, d)$ be a metric space and $x, y \in X$ with $l=d(x, y)$. A geodesic path from $x$ to $y$ is an isometry $c:[0, l] \rightarrow X$ such that $c(0)=X$ and $c(l)=y$. The image of a geodesic path is called a geodesic segment, denoted by $[x, y]$ as it is unique. A metric space $X$ is a (uniquely) geodesic space if every two points of $X$ are joined by only one geodesic segment. A geodesic triangle $\triangle\left(x_{1}, x_{2}, x_{3}\right)$ in a geodesic space $X$ consists of three points $x_{1}, x_{2}, x_{3}$ of $X$ and three geodesic segments joining each pair of vertices. A comparison triangle of a geodesic triangle $\triangle\left(x_{1}, x_{2}, x_{3}\right)$ is the triangle $\bar{\Delta}\left(x_{1}, x_{2}, x_{3}\right):=\triangle\left(\bar{x}_{1}, \bar{x}_{2}, \bar{x}_{3}\right)$ in the Euclidean space $\mathbb{R}^{2}$ such that $d\left(x_{i}, x_{j}\right)=d_{\mathbb{R}^{2}}\left(\bar{x}_{i}, \bar{x}_{j}\right)$ for all $i, j=1,2,3$, where $\bar{x}_{i}$ is called the comparison vertex of $x_{i}, i=1,2,3$.

A geodesic space $X$ is a CAT(0) space if for each geodesic triangle $\triangle:=\triangle\left(x_{1}, x_{2}, x_{3}\right)$ in $X$ and its comparison triangle $\bar{\triangle}:=\triangle\left(\bar{x}_{1}, \bar{x}_{2}, \bar{x}_{3}\right)$ in $\mathbb{R}^{2}$, the $\operatorname{CAT}(0)$ inequality

$$
\mathrm{d}(\mathrm{x}, \mathrm{y}) \leqslant \mathrm{d}_{\mathbb{R}^{2}}(\bar{x}, \bar{y})
$$

is satisfied by all $x, y \in \triangle$ and their comparison points $\bar{x}, \bar{y} \in \bar{\triangle}$. The meaning of the $\operatorname{CAT}(0)$ inequality is that a geodesic triangle in X is at least thin as its comparison triangle in the Euclidean plane. A thorough

[^0]discussion of these spaces and their important role in various branches of mathematics are given in $[1,2]$. The complex Hilbert ball with the hyperbolic metric is an example of a CAT(0) space (see [10]).

Fixed point theory in a CAT(0) space was first studied by Kirk (see [13, 15]) who showed that every nonexpansive (single-valued) mapping defined on a bounded closed convex subset of a complete CAT(0) space always has a fixed point. Since then the fixed point theory for single-valued and multivalued mappings in CAT(0) spaces has been rapidly developed and much papers have appeared (see, e.g., [3, 58, 11, 12, 14, 17, 22-24]).

In 2008, Kirk and Panyanak [16] used the concept of $\Delta$-convergence introduced by Lim [18] to prove the CAT(0) space analogs of some Banach space results which involve weak convergence, and Dhompongsa and Panyanak [9] obtained $\Delta$-convergence theorems for the Picard, Mann and Ishikawa iterations in the CAT(0) space setting.

In 2010, Nanjaras and Panyanak [19] proved the demiclosed principle for asymptotically nonexpansive mappings in $\mathrm{CAT}(0)$ spaces. As a consequence, they also obtained a $\Delta$-convergence theorem of the Krasnoselski-Mann iteration for asymptotically nonexpansive mappings in this setting.

Inspired and motivated by those studies mentioned above, in this paper, by using a specific way of choosing the indices of the involved mappings and a new concept, namely, an analogue of inner product, we propose a modified Krasnoselski-Mann iteration scheme for approximating common fixed points of a countable family of asymptotically nonexpansive mappings and obtain a strong convergence theorem in CAT(0) space. The result improves and extends that of Nanjaras and Panyanak [19] whose related research involves just a single mapping and the weaker $\Delta$-convergence.

## 2. Preliminaries

In this paper, we write $(1-t) x \oplus t y$ for the the unique point $z$ in the geodesic segment joining from $x$ to $y$ such that

$$
\begin{equation*}
\mathrm{d}(z, x)=\operatorname{td}(x, y), d(z, y)=(1-t) d(x, y), \forall t \in[0,1] \tag{2.1}
\end{equation*}
$$

We also denote by $[x, y]$ the geodesic segment joining from $x$ to $y$, that is, $[x, y]:=\{(1-t) x \oplus t y: t \in[0,1]\}$. A subset $C$ of a $C A T(0)$ space is convex if $[x, y] \subset C$ for all $x, y \in C$.

In the sequel we shall need the following preliminaries.
Let $X$ be a uniquely geodesic space equipped with two operations $\circ$ and $\oplus$, respectively defined by:

## Definition 2.1.

(1) For any $\alpha \in \mathbb{R}$ and any $x \in X, \alpha \circ x$ stands for the unique point $u \in X$ such that

$$
\bar{u}=\alpha \bar{x}
$$

where ${ }^{-}$is the comparison vertex in the comparison triangle $\triangle(\ulcorner, \bar{\theta}, \cdot):=\triangle(\ulcorner, \overrightarrow{0}, \cdot \cdot)$ of $\triangle(\cdot, \theta, \cdot)$; and $\theta$ denotes a fixed $x_{0} \in X$.
(2) For any $x, y \in X, x \oplus y$ stands for the unique point $v \in X$ such that

$$
\bar{v}=\bar{x}+\bar{y}
$$

where $\bar{v}$ is the comparison vertex in the comparison triangles $\triangle(\bar{x}, \bar{\theta}, \bar{v})$ and $\triangle(\bar{y}, \bar{\theta}, \bar{v})$ of $\triangle(x, \theta, v)$ and $\triangle(y, \theta, v)$.

We then have the following conclusion:
Proposition 2.2. A uniquely geodesic space $X$ equipped with two operations $\circ$ and $\oplus$ forms a vector space whenever its power is no larger than $\boldsymbol{\Sigma}$, namely, the cardinality of continuum. Such a space is called a geodesic vector space.

This follows from the fact that it is reasonable to define the mappings $x \mapsto \bar{x}$ and $v \mapsto \bar{v}$ as injections, determined respectively by the mappings $\triangle(x, \theta, x) \mapsto \triangle(\bar{x}, \bar{\theta}, \bar{x})$ and $(\triangle(x, \theta, v), \triangle(y, \theta, v)) \mapsto$ $(\triangle(\bar{x}, \bar{\theta}, \bar{v}), \triangle(\bar{y}, \bar{\theta}, \bar{v}))$, since $X$ is equivalent to $\mathbb{R}^{2}$.

By the uniqueness of the negative element of any member of geodesic vector $X$, an operation $\ominus$ is defined by

$$
x \ominus y=x \oplus((-1) \circ y), \forall x, y \in X
$$

Since a $C A T(0)$ space is a uniquely geodesic space, then a $C A T(0)$ space, equipped with two operations - and $\oplus$, is called a $C A T(0)$ vector space whenever it possesses the cardinality of continuum.

Let $X$ be a CAT(0) vector space, with respect to which the following definition is given.
Definition 2.3. An analogue of inner product $\langle\cdot, \cdot\rangle: X \times X \rightarrow \mathbb{R}$ is defined by

$$
\langle x, y\rangle=\langle\bar{x}, \bar{y}\rangle_{\mathbb{R}^{2}}
$$

where $\bar{x}, \bar{y}$ are the comparison vertices in the comparison triangle $\triangle(\bar{x}, \bar{\theta}, \bar{y})$ of $\triangle(x, \theta, y)$.
It is obvious from the definition of the function $\langle\cdot, \cdot\rangle$ that it has the following properties: for any $x, y, z \in X$ and any $\alpha \in \mathbb{R}$,
(1) $\langle x, x\rangle \geqslant 0,\langle x, x\rangle=0 \Leftrightarrow x=\theta$;
(2) $\langle x, y\rangle=\langle y, x\rangle$;
(3) $\langle\alpha \circ x, y\rangle=\alpha\langle x, y\rangle$;
(4) $\langle x \oplus y, z\rangle=\langle x, z\rangle+\langle y, z\rangle$.

Then a distance $\rho$ on $X$ can be defined by

$$
\rho(x, y):=\sqrt{\langle x \ominus y, x \ominus y\rangle}
$$

which coincides with the original distance $d$ on $X$, since the distance $d_{\mathbb{R}^{2}}$ on $\mathbb{R}^{2}$ is just induced by $\langle\cdot, \cdot\rangle_{\mathbb{R}^{2}}$ and $d(x, y)=d_{\mathbb{R}^{2}}(\bar{x}, \bar{y})$.

Next, we define a function $\phi: X \times X \rightarrow \mathbb{R}^{+}$by

$$
\phi(x, y):=d^{2}(x, y)
$$

which obviously has the following property:

$$
\begin{equation*}
\phi(y, x)=\phi(z, x)+\phi(y, z)+2\langle z \ominus y, x \ominus z\rangle, \forall x, y, z \in X \tag{2.2}
\end{equation*}
$$

Lemma 2.4 ([20]). Let $\left\{a_{n}\right\},\left\{\delta_{n}\right\}$, and $\left\{b_{n}\right\}$ be sequences of nonnegative real numbers satisfying

$$
a_{n+1} \leqslant\left(1+\delta_{n}\right) a_{n}+b_{n}, \forall n \in \mathbb{N}
$$

If $\sum_{n=1}^{\infty} \delta_{n}<\infty$ and $\sum_{n=1}^{\infty} b_{n}<\infty$, then $\lim _{n \rightarrow \infty} a_{n}$ exists.
Lemma 2.5 ([21]). A geodesic space X is a CAT(0) space if and only if the following inequality

$$
\mathrm{d}^{2}((1-\mathrm{t}) \mathrm{x} \oplus \mathrm{t} y, z) \leqslant(1-\mathrm{t}) \mathrm{d}^{2}(\mathrm{x}, \mathrm{z})+\mathrm{td}^{2}(\mathrm{y}, \mathrm{z})-\mathrm{t}(1-\mathrm{t}) \mathrm{d}^{2}(\mathrm{x}, \mathrm{y})
$$

is satisfied by all $x, y, z \in X$ and all $t \in[0,1]$. In particular, if $x, y, z$ are points in a $\operatorname{CAT}(0)$ space and $t \in[0,1]$, then

$$
\mathrm{d}((1-\mathrm{t}) \mathrm{x} \oplus \mathrm{t} y, z) \leqslant(1-\mathrm{t}) \mathrm{d}(\mathrm{x}, \mathrm{z})+\mathrm{td}(\mathrm{y}, z)
$$

Let $\left\{x_{n}\right\}$ be a bounded sequence in a $\operatorname{CAT}(0)$ space $X$. For $x \in X$, we set

$$
r\left(x,\left\{x_{n}\right\}\right)=\limsup _{n \rightarrow \infty} d\left(x, x_{n}\right)
$$

The asymptotic radius $r\left(\left\{x_{n}\right\}\right)$ of $\left\{x_{n}\right\}$ is given by

$$
r\left(\left\{x_{n}\right\}\right)=\inf \left\{r\left(x,\left\{x_{n}\right\}\right): x \in K\right\}
$$

and the asymptotic center $\mathcal{A}\left(\left\{x_{n}\right\}\right)$ of $\left\{x_{n}\right\}$ is the set

$$
A\left(\left\{x_{n}\right\}\right)=\left\{x \in K: r\left(x,\left\{x_{n}\right\}\right)=r\left(\left\{x_{n}\right\}\right)\right\}
$$

It is known (see, e.g., [8]) that in a CAT(0) space, $A\left(\left\{x_{n}\right\}\right)$ consists of exactly one point. We now give the definition of $\Delta$-convergence.

Definition 2.6 ([16, 18]). A sequence $\left\{x_{n}\right\}$ in a $\operatorname{CAT}(0)$ space $X$ is said to $\Delta$-converge to $x \in X$ if $x$ is the unique asymptotic center of $\left\{u_{n}\right\}$ for every subsequence $\left\{u_{n}\right\}$ of $\left\{x_{n}\right\}$. In this case one writes $\Delta$ $\lim _{n \rightarrow \infty} x_{n}=x$ and calls $x$ the $\Delta$-limit of $\left\{x_{n}\right\}$.

Recall that a mapping $\mathrm{T}: \mathrm{C} \rightarrow \mathrm{C}$ is called asymptotically nonexpansive if there exists a sequence $\left\{\mu_{n}\right\} \subset[0, \infty)$ satisfying $\mu_{n} \rightarrow 0$ as $n \rightarrow \infty$ such that

$$
\mathrm{d}\left(\mathrm{~T}^{\mathrm{n}} x, \mathrm{~T}^{\mathrm{n}} \mathrm{y}\right) \leqslant\left(1+\mu_{\mathrm{n}}\right) \mathrm{d}(\mathrm{x}, \mathrm{y}), \forall \mathrm{x}, \mathrm{y} \in \mathrm{C}, \forall \mathrm{n} \in \mathbb{N}
$$

Lemma 2.7 ([9]). Let $K$ be a closed convex subset of a complete $C A T(0)$ space $X$, and let $\mathrm{T}: \mathrm{K} \rightarrow \mathrm{X}$ be $a$ nonexpansive mapping. Suppose $\left\{x_{n}\right\}$ is a bounded sequence in $K$ such that $\lim _{n \rightarrow \infty} d\left(x_{n}, T x_{n}\right)=0$ and $\left\{d\left(x_{n}, v\right)\right\}$ converges for all $v \in \mathrm{~F}(\mathrm{~T})$, then $\omega_{w}\left(x_{n}\right) \subset \mathrm{F}(\mathrm{T})$. Here $\omega_{w}\left(x_{n}\right):=\cup \mathcal{A}\left(\left\{x_{n}\right\}\right)$ where the union is taken over all subsequences $\left\{u_{n}\right\}$ of $\left\{x_{n}\right\}$. Moreover, $\omega_{w}\left(x_{n}\right)$ consists of exactly one point.

We now turn to a wider class of spaces, namely, the class of hyperbolic spaces, which contains the class of CAT(0) spaces (see Lemma 2.11).

Definition 2.8 ([17]). A hyperbolic space is a triple $(X, d, W)$ where $(X, d)$ is a metric space and $W$ : $X \times X \times[0,1] \rightarrow X$ is such that
(W1) $d(z, W(x, y, \alpha)) \leqslant(1-\alpha) d(z, x)+\alpha d(z, y)$;
(W2) $d(W(x, y, \alpha), W(x, y, \beta))=|\alpha-\beta| d(x, y)$;
(W3) $W(x, y, \alpha)=W(y, x, 1-\alpha)$;
(W4) $d(W(x, z, \alpha), W(y, w, \alpha))=(1-\alpha) d(x, y)+\alpha d(z, y)$ for all $x, y, z, w \in X, \alpha, \beta \in[0,1]$.
It follows from (W1) that for each $x, y \in X$ and $\alpha \in[0,1]$,

$$
\begin{equation*}
d(x, W(x, y, \alpha)) \leqslant \alpha d(x, y), \quad d(y, W(x, y, \alpha)) \leqslant(1-\alpha) d(x, y) \tag{2.3}
\end{equation*}
$$

Comparing (2.3) with (2.1), we can also use the notation $(1-\alpha) x \oplus \alpha y$ for $W(x, y, \alpha)$ in a hyperbolic space (X, d, W) .

Definition 2.9 ([17]). The hyperbolic space $(X, d, W)$ is called uniformly convex if for any $r>0$ and $\epsilon \in(0,2]$ there exists a $\delta \in(0,1]$ such that for all $a, x, y \in X$,

$$
\left.\begin{array}{rl}
d(x, a) & \leqslant r \\
d(y, a) & \leqslant r \\
d(x, y) & \leqslant \epsilon r
\end{array}\right\} \Rightarrow d\left(\frac{1}{2} x \oplus \frac{1}{2} y, a\right) \leqslant(1-\delta) r
$$

A mapping $\eta:(0, \infty) \times(0,2] \rightarrow(0,1]$ providing such a $\delta:=\eta(r, \epsilon)$ for given $r>0$ and $\epsilon \in(0,2]$ is called a modulus of uniform convexity.

Lemma 2.10 ([17]). Let ( $\mathrm{X}, \mathrm{d}, \mathrm{W}$ ) be a uniformly convex hyperbolic with modulus of uniform convexity $\eta$. For any $r>0, \epsilon \in(0,2], \lambda \in[0,1]$, and $a, x, y \in X$,

$$
\left.\begin{array}{l}
d(x, a) \leqslant r \\
d(y, a) \leqslant r \\
d(x, y) \leqslant \epsilon r
\end{array}\right\} \Rightarrow d((1-\lambda) x \oplus \lambda y, a) \leqslant(1-2 \lambda(1-\lambda) \eta(r, \epsilon)) r
$$

Lemma 2.11 ([17]). Assume that $X$ is a $C A T(0)$ space. Then $X$ is uniformly convex, and

$$
\eta(r, \epsilon)=\frac{\epsilon^{2}}{8}
$$

is a modulus of uniform convexity.

Lemma 2.12 ([4]). The unique solutions to the positive integer equation

$$
n=i_{n}+\frac{\left(m_{n}-1\right) m_{n}}{2}, m_{n} \geqslant i_{n}, n=1,2,3, \ldots
$$

are

$$
i_{n}=n-\frac{\left(m_{n}-1\right) m_{n}}{2}, m_{n}=-\left[\frac{1}{2}-\sqrt{2 n+\frac{1}{4}}\right], n=1,2,3, \ldots,
$$

where $[x]$ denotes the maximal integer that is not larger than $x$.

## 3. Main results

Theorem 3.1. Let $X$ be a complete $C A T(0)$ vector space and $C$ a closed convex nonempty subset of $X$. Let $\left\{T_{i}\right\}_{i=1}^{\infty}$ : $\mathrm{C} \rightarrow \mathrm{C}$ be a sequence of nonexpansive mappings with a sequence $\left\{\mu_{n}^{(i)}\right\}$ satisfying $\sum_{i=1}^{\infty} \sum_{n=1}^{\infty} \mu_{n}^{(i)}<\infty$ and the interior of $\mathrm{F}:=\cap_{i=1}^{\infty} \mathrm{F}\left(\mathrm{T}_{\mathrm{i}}\right) \neq \emptyset$. Starting from an arbitrary $\mathrm{x}_{1} \in \mathrm{C}$, define $\left\{\mathrm{x}_{\mathrm{n}}\right\}$ by

$$
\begin{equation*}
x_{n+1}=\left(1-\alpha_{n}\right) x_{n} \oplus \alpha_{n}\left(T_{n}^{*}\right)^{m_{n}} x_{n}, \forall n \in \mathbb{N}, \tag{3.1}
\end{equation*}
$$

where $\left\{\alpha_{n}\right\} \subset[\epsilon, 1-\epsilon]$ for some $\epsilon>0$ and $T_{n}^{*}=T_{i_{n}}$ with $i_{n}$ and $m_{n}$ being the solutions to the positive integer equation: $\mathfrak{n}=\mathfrak{i}_{n}+\frac{\left(m_{n}-1\right) m_{n}}{2}\left(m_{n} \geqslant \mathfrak{i}_{n}, n=1,2, \ldots\right)$, that is, for each $n \in \mathbb{N}$, there exist unique $\mathfrak{i}_{n}$ and $\mathfrak{m}_{n}$ such that

$$
\begin{aligned}
\mathfrak{i}_{1} & =1, \mathfrak{i}_{2}=1, \mathfrak{i}_{3}=2, \mathfrak{i}_{4}=1, \mathfrak{i}_{5}=2, \mathfrak{i}_{6}=3, \mathfrak{i}_{7}=1, \mathfrak{i}_{8}=2, \ldots \\
\mathfrak{m}_{1} & =1, \mathfrak{m}_{2}=2, m_{3}=2, m_{4}=3, m_{5}=3, m_{6}=3, m_{7}=4, m_{8}=4, \ldots .
\end{aligned}
$$

Then $\left\{x_{n}\right\}$ converges strongly to a common fixed point $x^{*}$ of the mappings $\left\{T_{i}\right\}_{i=1}^{\infty}$.
Proof. We divide the proof into several steps.
(I) $\lim _{n \rightarrow \infty} d\left(x_{n}, q\right)$ exists, $\forall q \in F$.

From (3.1), we have

$$
\begin{aligned}
d\left(x_{n+1}, q\right) & =d\left(\left(1-\alpha_{n}\right) x_{n} \oplus \alpha_{n}\left(T_{n}^{*}\right)^{m_{n}} x_{n}, q\right) \\
& \leqslant\left(1-\alpha_{n}\right) d\left(x_{n}, q\right)+\alpha_{n} d\left(\left(T_{n}^{*}\right)^{m_{n}} x_{n},\left(T_{n}^{*}\right)^{m_{n}} q\right) \\
& \leqslant\left(1-\alpha_{n}\right) d\left(x_{n}, q\right)+\alpha_{n}\left(1+\mu_{m_{n}}^{\left(i_{n}\right)}\right) d\left(x_{n}, q\right) \\
& \leqslant\left(1+\mu_{m_{n}}^{\left(i_{n}\right)}\right) d\left(x_{n}, q\right) .
\end{aligned}
$$

Note that $\sum_{n=1}^{\infty} \mu_{m_{n}}^{\left(i_{n}\right)}=\sum_{i=1}^{\infty} \sum_{n=i}^{\infty} \mu_{n}^{(i)} \leqslant \sum_{i=1}^{\infty} \sum_{n=1}^{\infty} \mu_{n}^{(i)}<\infty$. So by Lemma 2.4 we conclude $\lim _{n \rightarrow \infty} d\left(x_{n}, q\right)$ exists and hence $\left\{x_{n}\right\}$ and $\left\{\left(T_{n}^{*}\right)^{m_{n}} x_{n}\right\}$ are bounded.
(II) $x_{n} \rightarrow x^{*} \in C$ as $n \rightarrow \infty$.

For any $q \in F$, we have, by Lemma 2.5,

$$
\begin{align*}
d^{2}\left(x_{n+1}, q\right) & =d^{2}\left(\left(1-\alpha_{n}\right) x_{n} \oplus \alpha_{n}\left(T_{n}^{*}\right)^{m_{n}} x_{n}, q\right) \\
& \leqslant\left(1-\alpha_{n}\right) d^{2}\left(x_{n}, q\right)+\alpha_{n} d^{2}\left(\left(T_{n}^{*}\right)^{m_{n}} x_{n}, q\right)-\alpha_{n}\left(1-\alpha_{n}\right) d^{2}\left(x_{n},\left(T_{n}^{*}\right)^{m_{n}} x_{n}\right) \\
& \leqslant\left(1-\alpha_{n}\right) d^{2}\left(x_{n}, q\right)+\alpha_{n}\left(1+\mu_{m_{n}}^{\left(i_{n}\right)}\right) d^{2}\left(x_{n}, q\right)-\alpha_{n}\left(1-\alpha_{n}\right) d^{2}\left(x_{n},\left(T_{n}^{*}\right)^{m_{n}} x_{n}\right)  \tag{3.2}\\
& \leqslant\left(1+\mu_{m_{n}}^{\left(i_{n}\right)}\right) d^{2}\left(x_{n}, q\right) \\
& =d^{2}\left(x_{n}, q\right)+v_{m_{n}}^{\left(i_{n}\right)},
\end{align*}
$$

where $v_{m_{n}}^{\left(\mathfrak{i}_{n}\right)}:=\mu_{m_{n}}^{\left(\mathfrak{i}_{n}\right)} d^{2}\left(x_{n}, q\right)$, and so $\sum_{n=1}^{\infty} v_{m_{n}}^{\left(\mathfrak{i}_{n}\right)}<\infty$. Furthermore, it follows from (2.2) that

$$
\phi\left(p, x_{n}\right)=\phi\left(x_{n+1}, x_{n}\right)+\phi\left(p, x_{n+1}\right)+2\left\langle x_{n+1} \ominus p, x_{n} \ominus x_{n+1}\right\rangle, \forall p \in X .
$$

This implies that

$$
\begin{equation*}
\left\langle x_{n+1} \ominus p, x_{n} \ominus x_{n+1}\right\rangle+\frac{1}{2} \phi\left(x_{n+1}, x_{n}\right)=\frac{1}{2}\left(\phi\left(p, x_{n}\right)-\phi\left(p, x_{n+1}\right)\right) . \tag{3.3}
\end{equation*}
$$

Moreover, since the interior of $F$ is nonempty, there exists a $p^{*} \in F$ and $r>0$ such that ( $p^{*} \oplus r \circ h$ ) $\in F$ whenever $\sqrt{\langle h, h\rangle} \leqslant 1$. Thus, from (3.2) and (3.3) we obtain

$$
\begin{equation*}
0 \leqslant\left\langle x_{n+1} \ominus\left(p^{*} \oplus r \circ h\right), x_{n} \ominus x_{n+1}\right\rangle+\frac{1}{2} \phi\left(x_{n+1}, x_{n}\right)+\frac{1}{2} v_{m_{n}}^{\left(i_{n}\right)} . \tag{3.4}
\end{equation*}
$$

Then from (3.3) and (3.4) we obtain

$$
r\left\langle h, x_{n} \ominus x_{n+1}\right\rangle \leqslant\left\langle x_{n+1} \ominus p^{*}, x_{n} \ominus x_{n+1}\right\rangle+\frac{1}{2} \phi\left(x_{n+1}, x_{n}\right)+\frac{1}{2} v_{m_{n}}^{\left(i_{n}\right)}=\frac{1}{2}\left(\phi\left(p^{*}, x_{n}\right)-\phi\left(p^{*}, x_{n+1}\right)\right)+\frac{1}{2} v_{m_{n}}^{\left(i_{n}\right)},
$$

and hence

$$
\left\langle h, x_{n} \ominus x_{n+1}\right\rangle \leqslant \frac{1}{2 r}\left(\phi\left(p^{*}, x_{n}\right)-\phi\left(p^{*}, x_{n+1}\right)\right)+\frac{1}{2 r} v_{m_{n}}^{\left(i_{n}\right)} .
$$

Since $h$ with $\sqrt{\langle h, h\rangle} \leqslant 1$ is arbitrary, we have, by taking $h=\frac{1}{d\left(x_{n}, x_{n+1}\right)} \circ\left(x_{n} \ominus x_{n+1}\right)$,

$$
\begin{equation*}
d\left(x_{n}, x_{n+1}\right) \leqslant \frac{1}{2 r}\left(\phi\left(p^{*}, x_{n}\right)-\phi\left(p^{*}, x_{n+1}\right)\right)+\frac{1}{2 r} v_{m_{n}}^{\left(i_{n}\right)} . \tag{3.5}
\end{equation*}
$$

So, if $n>m$, then we have

$$
\begin{align*}
d\left(x_{m}, x_{n}\right) \leqslant \sum_{j=m}^{n-1} d\left(x_{j}, x_{j+1}\right) & \leqslant \frac{1}{2 r} \sum_{j=m}^{n-1}\left(\phi\left(p^{*}, x_{j}\right)-\phi\left(p^{*}, x_{j+1}\right)\right)+\frac{1}{2 r} \sum_{j=m}^{n-1} v_{m_{j}}^{\left(i_{j}\right)} \\
& =\frac{1}{2 r}\left(\phi\left(p^{*}, x_{m}\right)-\phi\left(p^{*}, x_{n}\right)\right)+\frac{1}{2 r} \sum_{j=m}^{n-1} v_{m_{j}}^{\left(i_{j}\right)} . \tag{3.6}
\end{align*}
$$

But we know that $\left\{\phi\left(\mathfrak{p}^{*}, \chi_{n}\right)\right\}$ converges, and $\sum_{n=1}^{\infty} \nu_{\mathfrak{m}_{n}}^{\left(\mathfrak{i}_{n}\right)}<\infty$. Therefore, we obtain from (3.6) that $\left\{\chi_{n}\right\}$ is a Cauchy sequence. Since $X$ is complete there exists an $x^{*} \in X$ such that $x_{n} \rightarrow x^{*} \in X$ as $n \rightarrow \infty$. Thus, since $\left\{x_{n}\right\} \subset C$ and $C$ is closed and convex, then $x^{*} \in C$, that is,

$$
\begin{equation*}
x_{n} \rightarrow x^{*} \in C(n \rightarrow \infty) . \tag{3.7}
\end{equation*}
$$

(III) $x^{*}$ is one of members of $F$.

Since $\left\{\alpha_{n}\right\} \subset[\epsilon, 1-\epsilon]$, we have, from (3.2),

$$
\epsilon^{2} d^{2}\left(x_{n},\left(T_{n}^{*}\right)^{m_{n}} x_{n}\right) \leqslant d^{2}\left(x_{n}, q\right)-d^{2}\left(x_{n+1}, q\right)+v_{m_{n}}^{\left(i_{n}\right)}
$$

so that

$$
\epsilon^{2} \sum_{n=1}^{\infty} d^{2}\left(x_{n},\left(T_{n}^{*}\right)^{m_{n}} x_{n}\right) \leqslant d^{2}\left(x_{1}, q\right)+\sum_{n=1}^{\infty} v_{m_{n}}^{\left(i_{n}\right)}<\infty .
$$

This implies that

$$
\begin{equation*}
\lim _{n \rightarrow \infty} d\left(x_{n},\left(T_{n}^{*}\right)^{m_{n}} x_{n}\right)=0 \tag{3.8}
\end{equation*}
$$

It follows from (3.5) that

$$
\lim _{n \rightarrow \infty} d\left(x_{n+1}, x_{n}\right)=0
$$

which implies that, by induction, for any nonnegative integer $j$,

$$
\begin{equation*}
\lim _{n \rightarrow \infty} d\left(x_{n+j}, x_{n}\right)=0 \tag{3.9}
\end{equation*}
$$

Next, for any $i \in \mathbb{N}$, we consider the corresponding subsequence $\left\{x_{k}^{(i)}\right\}_{k \in \Gamma_{i}}$ of $\left\{x_{n}\right\}$, where $k \in \Gamma_{i}:=$ $\left\{k \in \mathbb{N}: k=i_{k}+\frac{\left(j_{k}-1\right) \mathfrak{j}_{k}}{2}, \mathfrak{j}_{k} \geqslant \mathfrak{i}_{k}, \mathfrak{j}_{k} \in \mathbb{N}\right\}$. For example, by Lemma 2.12 and the definition of $\Gamma_{1}$, we have $\Gamma_{1}=\{1,2,4,7,11,16, \ldots\}$ and $\mathfrak{i}_{1}=\mathfrak{i}_{2}=\mathfrak{i}_{4}=\mathfrak{i}_{7}=\mathfrak{i}_{11}=\mathfrak{i}_{16}=\cdots=1$. For simplicity, $\left\{x_{k}^{(i)}\right\}_{k \in \Gamma_{i}}{ }^{\prime}$ $\left\{\left(T_{k}^{*}\right)^{(i)}\right\}_{k \in \Gamma_{i}}$, and $\left\{\mathfrak{j}_{k}^{(i)}\right\}_{k \in \Gamma_{i}}$ are written as $\left\{x_{n}^{\prime}\right\},\left\{T_{n}^{\prime}\right\}$, and $\left\{m_{n}\right\}$, respectively. Since $m_{n} \geqslant 2$ whenever $\mathrm{n} \geqslant 2$, we have, for each $n \in \mathbb{N}$,

$$
\begin{aligned}
d\left(x_{n}^{\prime}, T_{n}^{\prime} x_{n}^{\prime}\right) \leqslant & d\left(x_{n+1}^{\prime}, x_{n}^{\prime}\right)+d\left(x_{n+1}^{\prime},\left(T_{n+1}^{\prime}\right)^{m_{n+1}} x_{n+1}^{\prime}\right) \\
& +d\left(\left(T_{n+1}^{\prime}\right)^{m_{n+1}} x_{n+1}^{\prime},\left(T_{n+1}^{\prime}\right)^{m_{n+1}} x_{n}^{\prime}\right)+d\left(\left(T_{n+1}^{\prime}\right)^{m_{n+1}} x_{n}^{\prime}, T_{n}^{\prime} x_{n}^{\prime}\right) \\
\leqslant & d\left(x_{n+1}^{\prime}, x_{n}^{\prime}\right)+d\left(x_{n+1}^{\prime},\left(T_{n+1}^{\prime}\right)^{m_{n+1}} x_{n+1}^{\prime}\right) \\
& +\left(1+\mu_{m_{n+1}}^{(i)}\right) d\left(x_{n+1}^{\prime}, x_{n}^{\prime}\right)+d\left(\left(T_{n+1}^{\prime}\right)^{m_{n+1}} x_{n}^{\prime}, T_{n}^{\prime} x_{n}^{\prime}\right)
\end{aligned}
$$

Note that $\left\{m_{n}\right\}_{n \in \Gamma_{i}}=\{i, i+1, i+2, \ldots\}$, i.e., $m_{n+1}-1=m_{n}, \mu_{1}^{\left(i_{k}\right)}=\mu_{1}^{(i)}$, and $T_{n}^{\prime}=T_{i}=T_{n+1}^{\prime}$ whenever $k \in \Gamma_{i}$. Then from (3.8), we have, as $n \rightarrow \infty$,

$$
\begin{aligned}
d\left(\left(T_{n+1}^{\prime}\right)^{m_{n+1}} x_{n}^{\prime}, T_{n}^{\prime} x_{n}^{\prime}\right) & =d\left(\left(T_{n+1}^{\prime}\right)\left(\left(T_{n+1}^{\prime}\right)^{m_{n+1}-1} x_{n}^{\prime}\right), T_{n}^{\prime} x_{n}^{\prime}\right) \\
& \leqslant\left(1+\mu_{1}^{(i)}\right) d\left(\left(T_{n+1}^{\prime}\right)^{m_{n+1}-1} x_{n}^{\prime}, x_{n}^{\prime}\right) \\
& =\left(1+\mu_{1}^{(i)}\right) d\left(\left(T_{n}^{\prime}\right)^{m_{n}} x_{n}^{\prime}, x_{n}^{\prime}\right) \rightarrow 0
\end{aligned}
$$

Then it follows from (3.8) and (3.9) that

$$
\lim _{n \rightarrow \infty} d\left(x_{n}^{\prime}, T_{n}^{\prime} x_{n}^{\prime}\right)=0
$$

That is, for each $i \in \mathbb{N}$, there exists a subsequence $\left\{x_{n}^{(i)}\right\}$ of $\left\{x_{n}\right\}$ such that

$$
\lim _{n \rightarrow \infty} d\left(x_{n}^{(i)},\left(\left(T_{n}^{*}\right)^{(i)} x_{n}^{(i)}\right)=0\right.
$$

Since $\left(T_{n}^{*}\right)^{(i)}=T_{i}$, we have, for each $i \in \mathbb{N}$,

$$
\lim _{n \rightarrow \infty} d\left(x_{n}^{(i)}, T_{i} x_{n}^{(i)}\right)=0
$$

Thus, from (3.7), since for any $i \in \mathbb{N}, x_{n}^{(i)} \rightarrow x^{*}$ as $n \rightarrow \infty$ and $T_{i}$ is continuous, we obtain $x^{*} \in F\left(T_{i}\right)$, i.e., $x^{*} \in \cap_{i=1}^{\infty} F\left(T_{i}\right)$. The proof is completed.

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