# Coupled fixed point results for ( $\varphi, \mathrm{G}$ )-contractions of type (b) in b-metric spaces endowed with a graph 

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#### Abstract

The purpose of this paper is to present some existence results for coupled fixed points of generalized contraction type operators in b-metric spaces endowed with a directed graph. Our results generalize the results obtained by Gnana Bhaskar and Lakshmikantham in [T. Gnana Bhaskar, V. Lakshmikantham, Nonlinear Anal., 65 (2006), 1379-1393]. Data dependence, well-posednes and Ulam-Hyres stability of the fixed point problem are also studied. © 2017 All rights reserved.


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## 1. Preliminaries

In fixed point theory, the importance of study of coupled fixed points is due to their applications to a wide variety of problems. Gnana Bhaskar and Lakshmikantham [8] gave some existence results for coupled fixed point for a mixed monotone type mapping in a metric space endowed with partial order, using a contraction type assumption on the mapping.

The purpose of this paper is to generalize these results using the context of b-metric spaces endowed with a graph. This new research direction in the theory of fixed points was initiated by Jachymski [11], and Gwóźdź-Lukawska and Jachymski [9]. Other results for single-valued and multi-valued operators in such metric spaces were given by Beg et al. in [1], Vetro and Vetro [19], and Chifu and Petrusel in [5].

Our results also generalize and extend some fixed point and coupled fixed point theorems in partially ordered complete metric spaces and b-metric spaces given by Harjani and Sadarangani [10], Nieto and Rodríguez-López [14, 16], Nieto et al. [15], Jleli et al. [13], O'Regan and Petruşel [17], Ran and Reurings [18], Gnana Bhaskar and Lakshmikantham [8], and Chifu and Petrusel in [6].

Let us recall now some essential definitions and fundamental results. We begin with the definition of a b-metric space.

Definition 1.1 ([7]). Let $X$ be a nonempty set and let $s \geqslant 1$ be a given real number. A functional $d$ : $X \times X \rightarrow[0, \infty)$ is said to be a b-metric if the following conditions are satisfied:

[^0]1. $d(x, y)=0$ if and only if $x=y$;
2. $d(x, y)=d(y, x)$;
3. $d(x, z) \leqslant s[d(x, y)+d(y, z)]$,
for all $x, y, z \in X$. In this case the pair $(X, d)$ is called a $b$-metric space.
Remark 1.2. The class of b-metric spaces is larger than the class of metric spaces since ab-metric space is a metric space when $s=1$. For more details and examples on b-metric spaces, see e.g., [2].

The following example will be useful for our results.
Example 1.3. Let $(X, d)$ be a b-metric space, with constant $s \geqslant 1$, and let $Z=X \times X$. The functional $\tilde{\mathrm{d}}: \mathrm{Z} \times \mathrm{Z} \rightarrow$ $[0, \infty)$, defined by

$$
\widetilde{d}((x, y),(u, v))=d(x, u)+d(y, v)
$$

is a b-metric with the same constant $s \geqslant 1$ for all $(x, y),(u, v) \in Z$. Moreover if $(X, d)$ is a complete $b$-metric space, then $(Z, \widetilde{d})$ is a complete $b$-metric space, too.

Definition 1.4. A mapping $\varphi:[0, \infty) \rightarrow[0, \infty)$ is called a comparison function if it is increasing and $\varphi^{n}(\mathrm{t}) \rightarrow 0$ as $\mathrm{n} \rightarrow \infty$ for any $\mathrm{t} \in[0, \infty)$.

We recall the following essential result.
Lemma $1.5([4])$. If $\varphi:[0, \infty) \rightarrow[0, \infty)$ is a comparison function, then:
(1) each iterate $\varphi^{k}$ of $\varphi$ (where $k \geqslant 1$ ) is also a comparison function;
(2) $\varphi$ is continuous at 0 ;
(3) $\varphi(t)<t$ for any $t>0$.

Berinde [4] introduced the concept of (c)-comparison function in the following way.
Definition 1.6 ([4]). A function $\varphi:[0, \infty) \rightarrow[0, \infty)$ is said to be a (c)-comparison function if
(1) $\varphi$ is increasing;
(2) there exist $k_{0} \in \mathbb{N}, a \in(0,1)$ and a convergent series of nonnegative terms $\sum_{k=1}^{\infty} v_{k}$ such that $\varphi^{k+1}(t) \leqslant a \varphi^{k}(t)+v_{k}$ for $k \geqslant k_{0}$ and any $t \in[0, \infty)$.

The notion of a (c)-comparison function was improved as a (b)-comparison function by Berinde [3], in order to extend some fixed point results to the class of b-metric spaces.

Definition 1.7 ([3]). Let $s \geqslant 1$ be a real number. A mapping $\varphi:[0, \infty) \rightarrow[0, \infty)$ is called a (b)-comparison function if the following conditions are fulfilled:
(1) $\varphi$ is monotone increasing;
(2) there exist $k_{0} \in \mathbb{N}, a \in(0,1)$ and a convergent series of nonnegative terms $\sum_{k=1}^{\infty} v_{k}$ such that $s^{k+1} \varphi^{k+1}(t) \leqslant a s^{k} \varphi^{k}(t)+v_{k}$ for $k \geqslant k_{0}$ and any $t \in[0, \infty)$.

It is obvious that the concept of (b)-comparison function reduces to that of (c)-comparison function when $s=1$.

The following lemma has a crucial role in the proof of our main result.
Lemma $1.8([2])$. If $\varphi:[0, \infty) \rightarrow[0, \infty)$ is a (b)-comparison function, then we have the following:
(1) the series $\sum_{k=0}^{\infty} s^{k} \varphi^{k}(t)$ converges for any $t \in[0, \infty)$;
(2) the function $S_{b}:[0, \infty) \rightarrow[0, \infty)$ defined by $S_{b}(t)=\sum_{k=0}^{\infty} s^{k} \varphi^{k}(t), t \in[0, \infty)$, is increasing and continuous at 0 .

We note that any (b)-comparison function is a comparison function due to the above lemma.
Let $(X, d)$ be a metric space and $\Delta$ be the diagonal of $X \times X$. Let $G$ be a directed graph, such that the set $\mathrm{V}(\mathrm{G})$ of its vertices coincides with X and $\Delta \subseteq \mathrm{E}(\mathrm{G})$, where $\mathrm{E}(\mathrm{G})$ is the set of the edges of the graph. Assume also that $G$ has no parallel edges and, thus, one can identify $G$ with the pair ( $V(G), E(G)$ ).

Throughout the paper we shall say that $G$ with the above mentioned properties satisfies standard conditions.

Let us denote by $G^{-1}$ the graph obtained from $G$ by reversing the direction of edges. Thus,

$$
E\left(G^{-1}\right)=\{(x, y) \in X \times X:(y, x) \in E(G)\}
$$

Let us consider the function $F: X \times X \rightarrow X$.
Definition 1.9. An element $(x, y) \in X \times X$ is called coupled fixed point of the mapping $F$, if $F(x, y)=x$ and $F(y, x)=y$.

We shall denote by $C F i x(F)$ the set of all coupled fixed points of mapping $F$, i.e.,

$$
\operatorname{CFix}(F)=\{(x, y) \in X \times X: F(x, y)=x \text { and } F(y, x)=y\}
$$

Definition 1.10 ([6]). We say that $F: X \times X \rightarrow X$ is edge preserving if

$$
(x, u) \in E(G) \text { and }(y, v) \in E\left(G^{-1}\right) \Rightarrow(F(x, y), F(u, v)) \in E(G)
$$

and

$$
(F(y, x), F(v, u)) \in E\left(G^{-1}\right)
$$

Definition 1.11 ([6]). The operator $F: X \times X \rightarrow X$ is called G-continuous if for all $(x, y) \in X \times X,\left(x^{*}, y^{*}\right) \in$ $X \times X$ and for any sequence $\left(n_{i}\right)_{i \in \mathbb{N}}$ of positive integers, with $F^{n_{i}}(x, y) \rightarrow x^{*}, F^{n_{i}}(y, x) \rightarrow y^{*}$, as $i \rightarrow \infty$, and $\left(F^{n_{i}}(x, y), F^{n_{i}+1}(x, y)\right) \in E(G),\left(F^{n_{i}}(y, x), F^{n_{i}+1}(y, x)\right) \in E\left(G^{-1}\right)$, we have that

$$
\begin{aligned}
& F\left(F^{n_{i}}(x, y), F^{n_{i}}(y, x)\right) \rightarrow F\left(x^{*}, y^{*}\right) \\
& F\left(F^{n_{i}}(y, x), F^{n_{i}}(x, y)\right) \rightarrow F\left(y^{*}, x^{*}\right)
\end{aligned}, \text { as } i \rightarrow \infty .
$$

Definition 1.12 ([6]). Let $(X, d)$ be a b-metric space, with constant $s \geqslant 1$, and $G$ be a directed graph. We say that the triple $(X, d, G)$ has the property $\left(A_{1}\right)$, if for any sequence $\left(x_{n}\right)_{n \in \mathbb{N}} \subset X$ with $x_{n} \rightarrow x$, as $n \rightarrow \infty$, and $\left(x_{n}, x_{n+1}\right) \in E(G)$, for $n \in \mathbb{N}$, we have that $\left(x_{n}, x\right) \in E(G)$.

Definition 1.13 ([6]). Let ( $X, d$ ) be a b-metric space, with constant $s \geqslant 1$, and $G$ be a directed graph. We say that the triple $(X, d, G)$ has the property $\left(A_{2}\right)$, if for any sequence $\left(x_{n}\right)_{n \in \mathbb{N}} \subset X$ with $x_{n} \rightarrow x$, as $n \rightarrow \infty$, and $\left(x_{n}, x_{n+1}\right) \in E\left(G^{-1}\right)$, for $n \in \mathbb{N}$, we have that $\left(x_{n}, x\right) \in E\left(G^{-1}\right)$.

## 2. Existence and data dependence results for coupled fixed point problems

Let $(X, d)$ be a $b$-metric space, with constant $s \geqslant 1$, endowed with a directed graph $G$ satisfying the standard conditions. We consider the set denoted by $(X \times X)^{F}$ and defined as:

$$
(X \times X)^{F}=\left\{(x, y) \in X \times X:(x, F(x, y)) \in E(G) \text { and }(y, F(y, x)) \in E\left(G^{-1}\right)\right\}
$$

Proposition 2.1 ([6]). If $\mathrm{F}: \mathrm{X} \times \mathrm{X} \rightarrow \mathrm{X}$ is edge preserving, then:
(i) $(x, u) \in E(G)$ and $(y, v) \in E\left(G^{-1}\right)$ implies $\left(F^{n}(x, y), F^{n}(u, v)\right) \in E(G)$ and $\left(F^{n}(y, x), F^{n}(v, u)\right) \in$ $\mathrm{E}\left(\mathrm{G}^{-1}\right)$ for all $\mathrm{n} \in \mathbb{N}$;
(ii) $(x, y) \in(X \times X)^{F}$ implies $\left(F^{n}(x, y), F^{n+1}(x, y)\right) \in E(G)$ and $\left(F^{n}(y, x), F^{n+1}(y, x)\right) \in E\left(G^{-1}\right)$ for all $n \in \mathbb{N}$;
(iii) $(x, y) \in(X \times X)^{F}$ implies $\left(F^{n}(x, y), F^{n}(y, x)\right) \in(X \times X)^{F}$ for all $n \in \mathbb{N}$.

Definition 2.2. The mapping $F: X \times X \rightarrow X$ is called $(\varphi, G)$-contraction of type (b) if:
(i) F is edge preserving;
(ii) there exists $\varphi:[0, \infty) \rightarrow[0, \infty)$ a (b)-comparison function such that

$$
\begin{gathered}
d(F(x, y), F(u, v))+d(F(y, x), F(v, u)) \leqslant \varphi(d(x, u)+d(y, v)), \\
\text { for all }(x, u) \in E(G),(y, v) \in E\left(G^{-1}\right) .
\end{gathered}
$$

Lemma 2.3. Let $(\mathrm{X}, \mathrm{d})$ be a b-metric space, with constant $\mathrm{s} \geqslant 1$, endowed with a directed graph G and let $\mathrm{F}: \mathrm{X} \times \mathrm{X} \rightarrow \mathrm{X}$ be a $(\varphi, \mathrm{G})$-contraction of type (b). Then,

$$
d\left(F^{n}(x, y), F^{n}(u, v)\right)+d\left(F^{n}(y, x), F^{n}(v, u)\right) \leqslant \varphi^{n}(d(x, u)+d(y, v)),
$$

for all $(\mathrm{x}, \mathrm{u}) \in \mathrm{E}(\mathrm{G}),(\mathrm{y}, v) \in \mathrm{E}\left(\mathrm{G}^{-1}\right), \mathrm{n} \in \mathbb{N}$.
Proof. Let $(x, u) \in \mathrm{E}(\mathrm{G}),(\mathrm{y}, v) \in \mathrm{E}\left(\mathrm{G}^{-1}\right)$. Because F is edge preserving we have

$$
(F(x, y), F(u, v)) \in E(G) \text { and }(F(y, x), F(v, u)) \in E\left(G^{-1}\right) .
$$

From Proposition 2.1 (i) it follows that

$$
\left(F^{n}(x, y), F^{n}(u, v)\right) \in E(G) \text { and }\left(F^{n}(y, x), F^{n}(v, u)\right) \in E\left(G^{-1}\right) .
$$

Since $F$ is a $(\varphi, G)$-contraction of type (b), we obtain

$$
\begin{aligned}
\mathrm{d}\left(\mathrm{~F}^{2}(x, y), \mathrm{F}^{2}(u, v)\right)+\mathrm{d}\left(\mathrm{~F}^{2}(\mathrm{y}, \mathrm{x}), \mathrm{F}^{2}(v, u)\right)= & \mathrm{d}(\mathrm{~F}(\mathrm{~F}(\mathrm{x}, \mathrm{y}), \mathrm{F}(\mathrm{y}, \mathrm{x})), \mathrm{F}(\mathrm{~F}(\mathrm{u}, v), \mathrm{F}(v, u))) \\
& +\mathrm{d}(\mathrm{~F}(\mathrm{~F}(\mathrm{y}, \mathrm{x}), \mathrm{F}(\mathrm{x}, \mathrm{y})), \mathrm{F}(\mathrm{~F}(v, u), \mathrm{F}(u, v))) \\
\leqslant & \varphi(\mathrm{d}(\mathrm{~F}(\mathrm{x}, \mathrm{y}), \mathrm{F}(\mathrm{u}, v))+\mathrm{d}(\mathrm{~F}(\mathrm{y}, \mathrm{x}), \mathrm{F}(v, u))) \\
\leqslant & \varphi(\varphi(\mathrm{d}(\mathrm{x}, \mathrm{u})+\mathrm{d}(\mathrm{y}, v))) \\
\leqslant & \varphi^{2}(\mathrm{~d}(\mathrm{x}, \mathrm{u})+\mathrm{d}(\mathrm{y}, v)) .
\end{aligned}
$$

Hence, by induction, we reach the conclusion.
Lemma 2.4. Let $(\mathrm{X}, \mathrm{d})$ be a b-metric space, with constant $\mathrm{s} \geqslant 1$, endowed with a directed graph G and let $\mathrm{F}: \mathrm{X} \times \mathrm{X} \rightarrow \mathrm{X}$ be a $(\varphi, \mathrm{G})$-contraction of type $(\mathrm{b})$. Then, given $(\mathrm{x}, \mathrm{y}) \in(\mathrm{X} \times \mathrm{X})^{\mathrm{F}}$, there exists $\mathrm{r}(\mathrm{x}, \mathrm{y}) \geqslant 0$ such that

$$
d\left(F^{n}(x, y), F^{n+1}(x, y)\right)+d\left(F^{n}(y, x), F^{n+1}(y, x)\right) \leqslant \varphi^{n}(r(x, y)) \text { for all } n \in \mathbb{N} .
$$

Proof. Let $(x, y) \in(X \times X)^{F}$. It follows that $(x, F(x, y)) \in E(G)$ and $(y, F(y, x)) \in E\left(G^{-1}\right)$.
If in Lemma 2.3 we consider $u=F(x, y)$ and $v=F(y, x)$ we shall obtain

$$
\begin{aligned}
& d\left(F^{n}(x, y), F^{n}(F(x, y), F(y, x))\right)+d\left(F^{n}(y, x), F^{n}(F(y, x), F(x, y))\right) \\
& \quad \leqslant \varphi^{n}(d(x, F(x, y))+d(y, F(y, x))) \text { for all } n \in \mathbb{N},
\end{aligned}
$$

which is

$$
d\left(F^{n}(x, y), F^{n+1}(x, y)\right)+d\left(F^{n}(y, x), F^{n+1}(y, x)\right) \leqslant \varphi^{n}(d(x, F(x, y))+d(y, F(y, x))) \text { for all } n \in \mathbb{N} .
$$

If we consider $r(x, y):=d(x, F(x, y))+d(y, F(y, x))$, then

$$
d\left(F^{n}(x, y), F^{n+1}(x, y)\right)+d\left(F^{n}(y, x), F^{n+1}(y, x)\right) \leqslant \varphi^{n}(r(x, y)) \text { for all } n \in \mathbb{N}
$$

Lemma 2.5. Let $(\mathrm{X}, \mathrm{d})$ be a complete $b$-metric space with constant $s \geqslant 1$, endowed with a directed graph G and let $F: X \times X \rightarrow X$ be a $(\varphi, G)$-contraction of type (b). Then for each $(x, y) \in(X \times X)^{F}$, there exist $\chi^{*}(x) \in X$ and $y^{*}(y) \in X$ such that $\left(F^{n}(x, y)\right)_{n \in \mathbb{N}}$ converges to $x^{*}(x)$ and $\left(F^{n}(y, x)\right)_{n \in \mathbb{N}}$ converges to $y^{*}(y)$, as $n \rightarrow \infty$.
Proof. Let $(x, y) \in(X \times X)^{F}$. It follows that $(x, F(x, y)) \in E(G)$ and $(y, F(y, x)) \in E\left(G^{-1}\right)$. Let $Z=X \times X$ and consider the b-metric given by Example 1.3, $\tilde{\mathrm{d}}: Z \times Z \rightarrow[0, \infty)$, defined by

$$
\tilde{d}((x, y),(u, v))=d(x, u)+d(y, v) \text { for all }(x, y),(u, v) \in Z .
$$

Consider also, the operator $\mathrm{T}: \mathrm{Z} \rightarrow \mathrm{Z}$, defined by

$$
T(x, y)=(F(x, y), F(y, x)) \text { for all }(x, y) \in Z
$$

For $(x, y)$ and $(u, v) \in(X \times X)^{F}$, we have

$$
\widetilde{d}(T(x, y), T(u, v))=d(F(x, y), F(u, v))+d(F(y, x), F(v, u)) .
$$

If $u=F(x, y)$ and $v=F(y, x)$, then $(u, v) \in(X \times X)^{F}$ and $T(u, v)=T^{2}(x, y)$. Hence

$$
\widetilde{d}\left(T(x, y), T^{2}(x, y)\right)=d\left(F(x, y), F^{2}(x, y)\right)+d\left(F(y, x), F^{2}(y, x)\right) .
$$

By induction we shall obtain

$$
\tilde{d}\left(T^{n}(x, y), T^{n+1}(x, y)\right)=d\left(F^{n}(x, y), F^{n+1}(x, y)\right)+d\left(F^{n}(y, x), F^{n+1}(y, x)\right) .
$$

From Lemma 2.4, we have

$$
\tilde{d}\left(T^{n}(x, y), T^{n+1}(x, y)\right) \leqslant \varphi^{n}(r(x, y)) \text { for all } n \in \mathbb{N}
$$

Now we shall prove that $\left(T^{n}(x, y)\right)_{n \in \mathbb{N}}$ is a Cauchy sequence. We have

$$
\begin{aligned}
\tilde{d}\left(T^{n}(x, y), T^{n+p}(x, y)\right) \leqslant & \stackrel{ }{s}\left(T^{n}(x, y), T^{n+1}(x, y)\right)+s^{2} \tilde{d}\left(T^{n+1}(x, y), T^{n+2}(x, y)\right) \\
& +\cdots+s^{p-1} \widetilde{d}\left(T^{n+p-2}(x, y), T^{n+p-1}(x, y)\right) \\
& +s^{p} \widetilde{d}\left(T^{n+p-1}(x, y), T^{n+p}(x, y)\right) \\
\leqslant & s \varphi^{n}(r(x, y))+s^{2} \varphi^{n+1}(r(x, y))+\ldots+s^{p-1} \varphi^{n+p-2}(r(x, y)) \\
& +s^{p} \varphi^{n+p-1}(r(x, y)) \\
= & \frac{1}{s^{n-1}} \sum_{k=n}^{n+p-1} s^{k} \varphi^{k}(r(x, y)) .
\end{aligned}
$$

Let $S_{n}=\sum_{k=0}^{n} s^{k} \varphi^{k}(r(x, y))$. Hence we have

$$
\tilde{\mathrm{d}}\left(T^{n}(x, y), T^{n+p}(x, y)\right) \leqslant \frac{1}{s^{n-1}}\left(S_{n+p-1}-S_{n-1}\right) \leqslant \frac{1}{s^{n-1}} \sum_{k=0}^{\infty} s^{k} \varphi^{k}(r(x, y)) .
$$

From Lemma 1.8 we have that the series is convergent. In this way, we shall obtain

$$
\widetilde{d}\left(T^{n}(x, y), T^{n+p}(x, y)\right) \leqslant \frac{1}{s^{n-1}} \sum_{k=0}^{\infty} s^{k} \varphi^{k}(r(x, y)) \rightarrow 0, \text { as } n \rightarrow \infty .
$$

In conclusion the sequence $\left(T^{n}(x, y)\right)_{n \in \mathbb{N}}$ is a Cauchy sequence.
Since $(X, d)$ is a complete $b$-metric space, from Example 1.3, we have that $(Z, \widetilde{d})$ is a complete b-metric space, and hence there exists $\left(x^{*}(x), y^{*}(y)\right) \in X \times X$ such that $T^{n}(x, y) \rightarrow\left(x^{*}(x), y^{*}(y)\right)$, as $n \rightarrow \infty$. This is equivalent to $\left(F^{n}(x, y), F^{n}(y, x)\right) \rightarrow\left(x^{*}(x), y^{*}(y)\right)$, as $n \rightarrow \infty$.

Hence, there exist $x^{*}(x) \in X$ and $y^{*}(y) \in X$ such that $\left(F^{n}(x, y)\right)_{n \in \mathbb{N}}$ and $\left(F^{n}(y, x)\right)_{n \in \mathbb{N}}$ converge to $x^{*}(x)$ and $y^{*}(y)$, respectively, as $n \rightarrow \infty$.

Now we shall prove the main results of this section.
Theorem 2.6. Let $(X, d)$ be a complete b-metric space with constant $s \geqslant 1$, endowed with a directed graph $G$ and let $\mathrm{F}: \mathrm{X} \times \mathrm{X} \rightarrow \mathrm{X}$ be a $(\varphi, \mathrm{G})$-contraction of type (b). Suppose that:
(i) $F$ is G-continuous; or
(ii) the triple $(X, d, G)$ has the properties $\left(A_{1}\right)$ and $\left(A_{2}\right)$.

In these conditions $\mathrm{CFix}(\mathrm{F}) \neq \varnothing$ if and only if $(\mathrm{X} \times \mathrm{X})^{\mathrm{F}} \neq \varnothing$.
Proof. Suppose that $\operatorname{CFix}(F) \neq \varnothing$. Let $\left(x^{*}, y^{*}\right) \in \operatorname{CFix}(F)$. We have $\left(x^{*}, F\left(x^{*}, y^{*}\right)\right)=\left(x^{*}, x^{*}\right) \in \Delta \subset E(G)$ and $\left(y^{*}, F\left(y^{*}, x^{*}\right)\right)=\left(y^{*}, y^{*}\right) \in \Delta \subset E\left(G^{-1}\right)$.

Hence $\left(x^{*}, F\left(x^{*}, y^{*}\right)\right) \in E(G)$ and $\left(y^{*}, F\left(y^{*}, x^{*}\right)\right) \in E\left(G^{-1}\right)$ which means that $\left(x^{*}, y^{*}\right) \in(X \times X)^{F}$ and thus $(X \times X)^{F} \neq \varnothing$.

Suppose now that $(X \times X)^{F} \neq \varnothing$. Let $(x, y) \in(X \times X)^{F}$. It follows that $(x, F(x, y)) \in E(G)$ and $(y, F(y, x)) \in E\left(G^{-1}\right)$.

Let $\left(n_{i}\right)_{i \in \mathbb{N}}$ be a sequence of positive integers. From Proposition 2.1 (ii), we know that

$$
\begin{align*}
& \left(F^{n_{i}}(x, y), F^{n_{i}+1}(x, y)\right) \in E(G) \\
& \left(F^{n_{i}}(y, x), F^{n_{i}+1}(y, x)\right) \in E\left(G^{-1}\right) \tag{2.1}
\end{align*}
$$

Moreover from Lemma 2.5, there exist $x^{*}(x) \in X$ and $y^{*}(y) \in X$ such that

$$
\begin{align*}
c^{n_{i}}(x, y) & \rightarrow x^{*}(x),  \tag{2.2}\\
F^{n_{i}}(y, x) & \rightarrow y^{*}(y),
\end{align*}
$$

We shall prove that $F\left(x^{*}, y^{*}\right)=x^{*}$ and $F\left(y^{*}, x^{*}\right)=y^{*}$. Suppose that (i) takes place. Since $F$ is Gcontinuous we shall obtain that

$$
\begin{aligned}
c F\left(F^{n_{i}}(x, y), F^{n_{i}}(y, x)\right) & \rightarrow F\left(x^{*}, y^{*}\right), \\
F\left(F^{n_{i}}(y, x), F^{n_{i}}(x, y)\right) & \rightarrow F\left(y^{*}, x^{*}\right),
\end{aligned}
$$

Now

$$
\begin{aligned}
d\left(F\left(x^{*}, y^{*}\right), x^{*}\right)+d\left(F\left(y^{*}, x^{*}\right), y^{*}\right) \leqslant & s\left[d\left(F\left(x^{*}, y^{*}\right), F^{n_{i}+1}(x, y)\right)+d\left(F^{n_{i}+1}(x, y), x^{*}\right)\right] \\
& +s\left[d\left(F\left(y^{*}, x^{*}\right), F^{n_{i}+1}(y, x)\right)+d\left(F^{n_{i}+1}(y, x), y^{*}\right)\right]
\end{aligned}
$$

Using the G-continuity of $F$ and the convergence of $\left(F^{n}(x, y)\right)_{n \in \mathbb{N}}$, we obtain that $d\left(F\left(x^{*}, y^{*}\right), x^{*}\right)+$ $d\left(F\left(y^{*}, x^{*}\right), y^{*}\right)=0$, i.e., $F\left(x^{*}, y^{*}\right)=x^{*}$ and $F\left(y^{*}, x^{*}\right)=y^{*}$.

Thus $\left(x^{*}, y^{*}\right)$ is a coupled fixed point of the mapping $F$, so $C F i x(F) \neq \varnothing$.
Suppose now that (ii) takes place. From (2.1) and (2.2), using properties $\left(A_{1}\right)$ and $\left(A_{2}\right)$ of the triple ( $\mathrm{X}, \mathrm{d}, \mathrm{G}$ ), we shall obtain that

$$
\left(F^{n}(x, y), x^{*}\right) \in E(G), \quad\left(F^{n}(y, x), y^{*}\right) \in E\left(G^{-1}\right)
$$

We have

$$
\begin{aligned}
d\left(F\left(x^{*}, y^{*}\right), x^{*}\right)+d\left(F\left(y^{*}, x^{*}\right), y^{*}\right) \leqslant & s\left[d\left(F^{n+1}(x, y), F\left(x^{*}, y^{*}\right)\right)+d\left(F^{n+1}(x, y), x^{*}\right)\right] \\
& +s\left[d\left(F^{n+1}(y, x), F\left(y^{*}, x^{*}\right)\right)+d\left(F^{n+1}(y, x), y^{*}\right)\right] \\
= & s\left[d\left(F\left(F^{n}(x, y), F^{n}(y, x)\right), F\left(x^{*}, y^{*}\right)\right)+d\left(F^{n+1}(x, y), x^{*}\right)\right] \\
& +s\left[d\left(F\left(F^{n}(y, x), F^{n}(x, y)\right), F\left(y^{*}, x^{*}\right)\right)+d\left(F^{n+1}(y, x), y^{*}\right)\right] \\
\leqslant & s \varphi\left(d\left(F^{n}(x, y), x^{*}\right)+d\left(F^{n}(y, x), y^{*}\right)\right)+\operatorname{sd}\left(F^{n+1}(x, y), x^{*}\right) \\
& +\operatorname{sd}\left(F^{n+1}(y, x), y^{*}\right) \rightarrow 0, \text { as } n \rightarrow \infty .
\end{aligned}
$$

Hence $d\left(F\left(x^{*}, y^{*}\right), x^{*}\right)+d\left(F\left(y^{*}, x^{*}\right), y^{*}\right)=0$, which means that $F\left(x^{*}, y^{*}\right)=x^{*}$ and $F\left(y^{*}, x^{*}\right)=y^{*}$. Thus, $\left(x^{*}, y^{*}\right) \in \operatorname{CFix}(F)$.

Let us suppose now that for every $(x, y),(u, v) \in X \times X$, there exists $(z, w) \in X \times X$ such that

$$
\begin{equation*}
(x, z) \in E(G),(y, w) \in E\left(G^{-1}\right), \quad(u, z) \in E(G),(v, w) \in E\left(G^{-1}\right) \tag{2.3}
\end{equation*}
$$

Theorem 2.7. Adding condition (2.3) to the hypotheses of Theorem 2.6 we obtain the uniqueness of the coupled fixed point of $F$.

Proof. Let us suppose that there exist $\left(x^{*}, y^{*}\right),\left(u^{*}, v^{*}\right) \in X \times X$ two coupled fixed points of F . From (2.3) we have that there exists $(z, w) \in X \times X$ such that

$$
\left(x^{*}, z\right) \in \mathrm{E}(\mathrm{G}),\left(\mathrm{y}^{*}, w\right) \in \mathrm{E}\left(\mathrm{G}^{-1}\right), \quad\left(\mathrm{u}^{*}, z\right) \in \mathrm{E}(\mathrm{G}),\left(v^{*}, w\right) \in \mathrm{E}\left(\mathrm{G}^{-1}\right) .
$$

Using Lemma 2.3, we shall have

$$
\begin{aligned}
\mathrm{d}\left(\mathrm{x}^{*}, \mathrm{u}^{*}\right)+\mathrm{d}\left(y^{*}, v^{*}\right)= & \mathrm{d}\left(\mathrm{~F}^{\mathrm{n}}\left(\mathrm{x}^{*}, y^{*}\right), \mathrm{F}^{\mathrm{n}}\left(\mathrm{u}^{*}, v^{*}\right)\right)+\mathrm{d}\left(\mathrm{~F}^{\mathrm{n}}\left(\mathrm{y}^{*}, x^{*}\right), \mathrm{F}^{\mathrm{n}}\left(v^{*}, \mathrm{u}^{*}\right)\right) \\
\leqslant & \mathrm{s}\left[\mathrm{~d}\left(\mathrm{~F}^{\mathrm{n}}\left(\mathrm{x}^{*}, y^{*}\right), \mathrm{F}^{\mathrm{n}}(z, w)\right)+\mathrm{d}\left(\mathrm{~F}^{\mathrm{n}}(z, w), \mathrm{F}^{\mathrm{n}}\left(\mathrm{u}^{*}, v^{*}\right)\right)\right] \\
& +\mathrm{s}\left[\mathrm{~d}\left(\mathrm{~F}^{\mathrm{n}}\left(\mathrm{y}^{*}, \mathrm{x}^{*}\right), \mathrm{F}^{\mathrm{n}}(w, z)\right)+\mathrm{d}\left(\mathrm{~F}^{\mathrm{n}}(w, z), \mathrm{F}^{\mathrm{n}}\left(v^{*}, \mathrm{u}^{*}\right)\right)\right] \\
\leqslant & \left.\varphi^{\mathrm{n}}\left(\mathrm{~d}\left(x^{*}, z\right)+\mathrm{d}\left(\mathrm{y}^{*}, w\right)\right)+\varphi^{\mathrm{n}}\left(\mathrm{~d}\left(u^{*}, z\right)+\mathrm{d}\left(v^{*}, w\right)\right)\right) \rightarrow 0, \text { as } n \rightarrow \infty .
\end{aligned}
$$

Hence $\mathrm{d}\left(x^{*}, u^{*}\right)+\mathrm{d}\left(y^{*}, v^{*}\right)=0$ and thus we obtain that $x^{*}=u^{*}$ and $y^{*}=v^{*}$.
Remark 2.8. It is obvious that if $\left(x^{*}, u^{*}\right) \in \mathrm{E}(\mathrm{G})$ and $\left(y^{*}, v^{*}\right) \in \mathrm{E}\left(\mathrm{G}^{-1}\right)$, then $x^{*}=u^{*}$ and $y^{*}=v^{*}$.
Theorem 2.9. In the conditions of Theorem 2.6, if $\left(x^{*}, y^{*}\right) \in \operatorname{CFix}(F)$ with $\left(x^{*}, y^{*}\right) \in E(G)$, then $x^{*}=y^{*}$.
Proof. Since $\left(x^{*}, y^{*}\right) \in E(G)$, then $\left(y^{*}, x^{*}\right) \in E\left(G^{-1}\right)$. By the fact that $F$ is a $(\varphi, G)$-contraction of type (b), we have

$$
\begin{aligned}
2 \mathrm{~d}\left(x^{*}, y^{*}\right) & =\mathrm{d}\left(\mathrm{~F}\left(\mathrm{x}^{*}, \mathrm{y}^{*}\right), \mathrm{F}\left(\mathrm{y}^{*}, x^{*}\right)\right)+\mathrm{d}\left(\mathrm{~F}\left(\mathrm{y}^{*}, \mathrm{x}^{*}\right), \mathrm{F}\left(x^{*}, y^{*}\right)\right) \\
& \leqslant \varphi\left(\mathrm{d}\left(x^{*}, y^{*}\right)+\mathrm{d}\left(\mathrm{y}^{*}, x^{*}\right)\right)=\varphi\left(2 \mathrm{~d}\left(x^{*}, \mathrm{y}^{*}\right)\right) .
\end{aligned}
$$

From the properties of $\varphi$, we obtain that $d\left(x^{*}, y^{*}\right)=0$ and thus $x^{*}=y^{*}$.
Remark 2.10. It is obvious that if we consider a function $f: X \rightarrow X, f(x)=F(x, x)$ all these results concerning the coupled fixed point of the mapping $F$ result in the existence and uniqueness results for the fixed point of $f$.

In what follows we shall give a data-dependence result.
Theorem 2.11 (data dependence). Let ( $\mathrm{X}, \mathrm{d}$ ) be a complete $b$-metric space with constant $s \geqslant 1$, endowed with a directed graph G and let $\mathrm{F}_{\mathrm{i}}: \mathrm{X} \times \mathrm{X} \rightarrow \mathrm{X}, \mathrm{i} \in\{1,2\}$ be two mappings. Assume that the following conditions are satisfied:
(i) $F_{1}$ is a $(\varphi, \mathrm{G})$-contraction of type (b);
(ii) $\mathrm{F}_{1}$ is G-continuous;
or
(ii*) the triple $(X, d, G)$ has the properties $\left(A_{1}\right)$ and $\left(A_{2}\right)$;
(iii) for every $(\mathrm{x}, \mathrm{y}),(\mathrm{u}, v) \in \mathrm{X} \times \mathrm{X}$, there exists ( $z, w) \in \mathrm{X} \times \mathrm{X}$ such (2.3) holds;
(iv) $\operatorname{CFix}\left(\mathrm{F}_{2}\right) \neq \varnothing$;
(v) there exists $\eta>0$ such that

$$
d\left(F_{1}(x, y), F_{2}(x, y)\right) \leqslant \eta, \forall(x, y) \in X \times X
$$

In these conditions, if $\left(x^{*}, y^{*}\right)$ denotes the unique coupled fixed point of $\mathrm{F}_{1}$, then

$$
\begin{aligned}
\mathrm{d}\left(\mathrm{x}^{*}, \overline{\mathrm{x}}\right)+\mathrm{d}\left(\mathrm{y}^{*}, \overline{\mathrm{y}}\right) & \leqslant \sup \left\{\mathrm{t} \in \mathbb{R}_{+} \mid \mathrm{t}-\mathrm{s} \varphi(\mathrm{t}) \leqslant 2 \mathrm{sq}\right\}, \\
\forall(\overline{\mathrm{x}}, \overline{\mathrm{y}}) & \in \mathrm{CFix}\left(\mathrm{~F}_{2}\right) \text { and }\left(\mathrm{x}^{*}, \overline{\mathrm{x}}\right) \in \mathrm{E}(\mathrm{G}),\left(\mathrm{y}^{*}, \overline{\mathrm{y}}\right) \in \mathrm{E}\left(\mathrm{G}^{-1}\right) .
\end{aligned}
$$

Proof. Let $\left(x^{*}, y^{*}\right) \in X \times X$ be the unique coupled fixed point of $F_{1}$. It follows that

$$
\left\{\begin{array}{l}
x^{*}=F_{1}\left(x^{*}, y^{*}\right), \\
y^{*}=F_{1}\left(y^{*}, x^{*}\right) .
\end{array}\right.
$$

Since CFix $\left(F_{2}\right) \neq \varnothing$, let $(\bar{x}, \bar{y}) \in \operatorname{CFix}\left(F_{2}\right)$ with $\left(x^{*}, \bar{x}\right) \in E(G),\left(y^{*}, \bar{y}\right) E\left(G^{-1}\right)$. Let $Z=X \times X$ and consider the functional $\widetilde{d}: Z \times Z \rightarrow[0, \infty)$ defined by

$$
\widetilde{d}((x, y),(u, v))=d(x, u)+d(y, v) \text { for all }(x, y),(u, v) \in Z .
$$

We have

$$
\begin{aligned}
& \widetilde{\mathrm{d}}\left(\left(x^{*}, y^{*}\right),(\bar{x}, \bar{y})\right)=\widetilde{\mathrm{d}}\left(\left(\mathrm{~F}_{1}\left(x^{*}, y^{*}\right), \mathrm{F}_{1}\left(y^{*}, x^{*}\right)\right),\left(\mathrm{F}_{2}(\bar{x}, \bar{y}), F_{2}(\bar{y}, \bar{x})\right)\right) \\
& =d\left(F_{1}\left(x^{*}, y^{*}\right), F_{2}(\bar{x}, \bar{y})\right)+d\left(F_{1}\left(y^{*}, x^{*}\right), F_{2}(\bar{y}, \bar{x})\right) \\
& \leqslant s\left[d\left(F_{1}\left(x^{*}, y^{*}\right), F_{1}(\bar{x}, \bar{y})\right)+d\left(F_{1}(\bar{x}, \bar{y}), F_{2}(\bar{x}, \bar{y})\right)\right] \\
& +s\left[d\left(F_{1}\left(y^{*}, x^{*}\right), F_{1}(\bar{y}, \bar{x})\right)+d\left(F_{1}(\bar{y}, \bar{x}), F_{2}(\bar{y}, \bar{x})\right)\right] \\
& \leqslant s \varphi\left(d\left(x^{*}, \bar{x}\right)+d\left(y^{*}, \bar{y}\right)\right)+2 s \eta .
\end{aligned}
$$

Hence $d\left(x^{*}, \bar{x}\right)+d\left(y^{*}, \bar{y}\right) \leqslant \sup \left\{t \in \mathbb{R}_{+} \mid t-s \varphi(t) \leqslant 2 s \eta\right\}, \forall\left(x^{*}, y^{*}\right) \in \operatorname{CFix}\left(F_{1}\right)$ and $(\bar{x}, \bar{y}) \in \operatorname{CFix}\left(F_{2}\right)$.

Remark 2.12. In the light of the recent approach in [12], it is an open question to give similar results in the context of K-metric spaces.

## 3. Well-posedness and Ulam-Hyers stability

Let $\mathrm{F}: \mathrm{X} \times \mathrm{X} \rightarrow \mathrm{X}$. Consider now the following coupled fixed point problem

$$
\left\{\begin{array}{l}
x=F(x, y),  \tag{P1}\\
y=F(y, x),
\end{array}\right.
$$

Definition 3.1. Let ( $\mathrm{X}, \mathrm{d}$ ) be a complete b-metric space with constant $s \geqslant 1$. By definition, the coupled fixed point problem (P1) is said to be well-posed if:
(i) $\operatorname{CFix}(\mathrm{F})=\left\{\left(\mathrm{x}^{*}, \mathrm{y}^{*}\right)\right\}$;
(ii) for any sequence $\left(x_{n}, y_{n}\right)_{n \in \mathbb{N}}$ in $X \times X$ for which $d\left(x_{n}, F\left(x_{n}, y_{n}\right)\right) \rightarrow 0$ and respectively $d\left(y_{n}, F\left(y_{n}\right.\right.$, $\left.\left.x_{n}\right)\right) \rightarrow 0$ as $n \rightarrow \infty$, we have that $x_{n} \rightarrow x^{*}$ and $y_{n} \rightarrow y^{*}$, as $n \rightarrow \infty$.

Theorem 3.2. Suppose that the operator $\mathrm{F}: \mathrm{X} \times \mathrm{X} \rightarrow \mathrm{X}$ verifies all hypotheses of Theorem 2.7 and for any sequence $\left(x_{n}, y_{n}\right)_{n \in \mathbb{N}}$ in $X \times X$ having property that $d\left(x_{n}, F\left(x_{n}, y_{n}\right)\right) \rightarrow 0$ and respectively $d\left(y_{n}, F\left(y_{n}, x_{n}\right)\right) \rightarrow 0$ as $n \rightarrow \infty$, we have $\left(x_{n}, x^{*}\right) \in E(G)$ and $\left(y_{n}, y^{*}\right) \in E\left(G^{-1}\right)$. If the mapping $\psi:[0, \infty) \rightarrow \mathbb{R}, \psi(t)=t-s \varphi(t)$, is such that $\psi(\mathrm{t}) \geqslant 0, \forall \mathrm{t} \in \mathbb{R}_{+}$and $\psi(0)=0$ implies that $\mathrm{t}=0$, then the coupled fixed point problem ( P 1$)$ is well-posed.

Proof. By Theorem 2.7, it follows that the coupled fixed point problem (P1) has a unique solution ( $x^{*}, y^{*}$ ), i.e., CFix $(F)=\left\{\left(x^{*}, y^{*}\right)\right\}$.

Let $\left(x_{n}, y_{n}\right)_{n \in \mathbb{N}} \subset X \times X$ be a sequence which verifies the following properties:
(a) $d\left(x_{n}, F\left(x_{n}, y_{n}\right)\right) \rightarrow 0$ and respectively $d\left(y_{n}, F\left(y_{n}, x_{n}\right)\right) \rightarrow 0$ as $n \rightarrow \infty$;
(b) $\left(x_{n}, x^{*}\right) \in E(G)$ and $\left(y_{n}, y^{*}\right) \in E\left(G^{-1}\right)$.

Let $Z=X \times X$ and consider the functional $\tilde{d}: Z \times Z \rightarrow[0, \infty)$ defined by

$$
\tilde{d}((x, y),(u, v))=d(x, u)+d(y, v) \text { for all }(x, y),(u, v) \in Z
$$

We have

$$
\begin{aligned}
\tilde{d}\left(\left(x_{n}, y_{n}\right),\left(x^{*}, y^{*}\right)\right)= & \tilde{d}\left(\left(x_{n}, y_{n}\right),\left(F\left(x^{*}, y^{*}\right), F\left(y^{*}, x^{*}\right)\right)\right) \\
\leqslant & s \widetilde{d}\left(\left(x_{n}, y_{n}\right),\left(F\left(x_{n}, y_{n}\right), F\left(y_{n}, x_{n}\right)\right)\right) \\
& +\operatorname{s\tilde {d}}\left(\left(F\left(x_{n}, y_{n}\right), F\left(y_{n}, x_{n}\right)\right),\left(F\left(x^{*}, y^{*}\right), F\left(y^{*}, x^{*}\right)\right)\right) \\
\leqslant & s \widetilde{d}\left(\left(x_{n}, y_{n}\right),\left(F\left(x_{n}, y_{n}\right), F\left(y_{n}, x_{n}\right)\right)\right)+s \varphi\left(\widetilde{d}\left(\left(x_{n}, y_{n}\right),\left(x^{*}, y^{*}\right)\right)\right) .
\end{aligned}
$$

Hence

$$
\widetilde{d}\left(\left(x_{n}, y_{n}\right),\left(x^{*}, y^{*}\right)\right)-s \varphi\left(\widetilde{d}\left(\left(x_{n}, y_{n}\right),\left(x^{*}, y^{*}\right)\right)\right) \leqslant s \tilde{d}\left(\left(x_{n}, y_{n}\right),\left(F\left(x_{n}, y_{n}\right), F\left(y_{n}, x_{n}\right)\right)\right)
$$

Since the mapping $\psi:[0, \infty) \rightarrow \mathbb{R}, \psi(t)=t-s \varphi(t)$, is such that $\psi(t) \geqslant 0, \forall t \in \mathbb{R}_{+}$and $\psi(0)=0$ implies that $t=0$, then, letting $n \rightarrow \infty$, we get that $\left(x_{n}, y_{n}\right) \rightarrow\left(x^{*}, y^{*}\right)$.

In what follows we shall give an Ulam-Hyers stability result for the coupled fixed point problem (P1).
Definition 3.3. Let $(X, d)$ be a complete b-metric space with constant $s \geqslant 1$, and let $\widetilde{d}$ be any b-metric on $Z=X \times X$ generated by $d$. By definition, the coupled fixed point problem (P1) is said to be Ulam-Hyers stable if there exists $\psi: \mathbb{R}_{+} \rightarrow \mathbb{R}_{+}$, increasing, continuous in 0 with $\psi(0)=0$, such that for each $\varepsilon \in \mathbb{R}_{+}^{*}$ and for each solution $\left(u^{*}, v^{*}\right) \in X \times X$ of the inequality $\widetilde{d}((x, y),(F(x, y), F(y, x))) \leqslant \varepsilon$, there exists a solution $\left(x^{*}, y^{*}\right) \in X \times X$ of the coupled fixed point problem (P1) such that

$$
\widetilde{\mathrm{d}}\left(\left(x^{*}, \mathrm{y}^{*}\right),\left(u^{*}, v^{*}\right)\right) \leqslant \psi(\varepsilon)
$$

Theorem 3.4. Assume that all the hypotheses of Theorem 2.7 take place. If the mapping $\gamma:[0, \infty) \rightarrow \mathbb{R}, \gamma(\mathrm{t})=$ $\mathrm{t}-\mathrm{s} \varphi(\mathrm{t})$ is such that $\gamma(\mathrm{t}) \geqslant 0, \forall \mathrm{t} \in \mathbb{R}_{+}$and $\gamma(0)=0$ implies that $\mathrm{t}=0$, then the coupled fixed point problem (P1) is Ulam-Hyers stable.

Proof. By Theorem 2.7 we get that $\operatorname{CFix}(F)=\left\{\left(x^{*}, y^{*}\right)\right\}$. Let $\varepsilon>0$ and let $\left(u^{*}, v^{*}\right) \in X \times X$ such that $\widetilde{d}$ $\left(\left(u^{*}, v^{*}\right),\left(F\left(u^{*}, v^{*}\right), F\left(v^{*}, u^{*}\right)\right)\right) \leqslant \varepsilon$ and $\left(x^{*}, u^{*}\right) \in \mathrm{E}(\mathrm{G}),\left(y^{*}, v^{*}\right) \in \mathrm{E}\left(\mathrm{G}^{-1}\right)$.

Let $Z=X \times X$ and consider the functional $\widetilde{d}: Z \times Z \rightarrow[0, \infty)$ defined by

$$
\tilde{d}((x, y),(u, v))=d(x, u)+d(y, v) \text { for all }(x, y),(u, v) \in Z
$$

We have

$$
\begin{aligned}
\tilde{\mathrm{d}}\left(\left(u^{*}, v^{*}\right),\left(x^{*}, y^{*}\right)\right) & =\widetilde{\mathrm{d}}\left(\left(u^{*}, v^{*}\right),\left(\mathrm{F}\left(x^{*}, y^{*}\right), F\left(y^{*}, x^{*}\right)\right)\right) \\
& \leqslant \operatorname{s\tilde {d}}\left(\left(u^{*}, v^{*}\right),\left(F\left(u^{*}, v^{*}\right), F\left(v^{*}, u^{*}\right)\right)\right) \operatorname{sd}\left(\left(F\left(u^{*}, v^{*}\right), F\left(v^{*}, u^{*}\right)\right),\left(F\left(x^{*}, y^{*}\right), F\left(y^{*}, x^{*}\right)\right)\right) \\
& \leqslant \operatorname{s\varepsilon }+\operatorname{s\varphi }\left(\widetilde{\mathrm{d}}\left(\left(u^{*}, v^{*}\right),\left(x^{*}, y^{*}\right)\right)\right)
\end{aligned}
$$

Hence

$$
\widetilde{\mathrm{d}}\left(\left(u^{*}, v^{*}\right),\left(x^{*}, y^{*}\right)\right)-\mathrm{s} \varphi\left(\widetilde{\mathrm{~d}}\left(\left(u^{*}, v^{*}\right),\left(x^{*}, y^{*}\right)\right)\right) \leqslant s \varepsilon .
$$

Thus we obtain that

$$
\tilde{\mathrm{d}}\left(\left(u^{*}, v^{*}\right),\left(x^{*}, y^{*}\right)\right) \leqslant \psi(\varepsilon)
$$

where

$$
\psi(\varepsilon):=\sup \left\{t \in \mathbb{R}_{+} \mid \mathrm{t}-\mathrm{s} \varphi(\mathrm{t}) \leqslant \mathrm{s} \varepsilon\right\} .
$$

Since the mapping $\gamma:[0, \infty) \rightarrow \mathbb{R}, \gamma(\mathrm{t})=\mathrm{t}-\mathrm{s} \varphi(\mathrm{t})$ is such that $\gamma(\mathrm{t}) \geqslant 0, \forall \mathrm{t} \in \mathbb{R}_{+}$and $\gamma(0)=0$ implies that $\mathrm{t}=0$, then the coupled fixed point problem ( P 1 ) is Ulam-Hyers stable.

## 4. Applications

In what follows we shall give an application for Theorem 2.6. Let us consider the following problem:

$$
\left\{\begin{align*}
x^{\prime \prime}(t) & =f(t, x(t), y(t))  \tag{4.1}\\
y^{\prime \prime}(t) & =f(t, y(t), x(t)), \\
x(0) & =x^{\prime}(1)=y(0)=y^{\prime}(1)
\end{align*} \quad t \in[0,1]\right.
$$

Notice now that the problem (4.1) is equivalent with the following integral system

$$
\begin{cases}x(t)= & \int_{0}^{1} K(t, s) f(s, x(s), y(s)) d s  \tag{4.2}\\ y(t)= & \int_{0}^{1} K(s, t) f(s, y(s), x(s)) d s\end{cases}
$$

where

$$
K(t, s)= \begin{cases}t, & t \leqslant s \\ s, & t>s\end{cases}
$$

The purpose of this section is to give existence and uniqueness results for the solution of the system (4.2) using Theorem 2.6.

Let us consider $X:=C\left([0,1], \mathbb{R}^{n}\right)$ endowed with the following b-metric with $s=2$

$$
d(x, y)=\max _{t \in[0,1]}(x(t)-y(t))^{2}
$$

Consider also the graph $G$ defined by the partial order relation, i.e.,

$$
x, y \in X, x \leqslant y \Leftrightarrow x(t) \leqslant y(t) \text { for any } t \in[0,1]
$$

Since $(X, \leqslant)$ is a lattice, we get that $(X, G)$ has the property $(2.3)$. Hence $(X, d)$ is a complete $b$-metric space endowed with a directed graph $G$.

If we consider $E(G)=\{(x, y) \in X \times X: x \leqslant y\}$, then the diagonal $\Delta$ of $X \times X$ is included in $E(G)$. On the other hand $E\left(G^{-1}\right)=\{(x, y) \in X \times X: y \leqslant x\}$. Moreover $(X,\|\cdot\|, G)$ has the properties $\left(A_{1}\right)$ and $\left(A_{2}\right)$. In this case $(X \times X)^{F}=\{(x, y) \in X \times X: x \leqslant F(x, y)$ and $F(y, x) \leqslant y\}$.

Theorem 4.1. Consider the system (4.1). Suppose:
(i) $\mathrm{f}:[0,1] \times \mathbb{R}^{n} \times \mathbb{R}^{n} \rightarrow \mathbb{R}^{n}$ is continuous;
(ii) for all $x, y, u, v \in \mathbb{R}^{n}$ with $x \leqslant u, v \leqslant y$ we have $f(t, x, y) \leqslant f(t, u, v)$ for all $t \in[0,1]$;
(iii) there exists $\widetilde{\varphi}:[0, \infty) \rightarrow[0, \infty) a(b)$-comparison function and $\alpha, \beta \in(0, \infty)$, with $\max \{\alpha, \beta\}<1$, such that

$$
(f(t, x, y)-f(t, u, v))^{2} \leqslant \widetilde{\varphi}\left(\alpha(x-u)^{2}+\beta(y-v)^{2}\right) \text { for each } t \in[0,1], x, y, u, v \in \mathbb{R}^{n}, x \leqslant u, v \leqslant y
$$

(iv) there exists $\left(x_{0}, y_{0}\right) \in X \times X$ such that

$$
\left\{\begin{array}{l}
x_{0}(t) \leqslant \int_{0}^{1} K(t, s) f\left(s, x_{0}(s), y_{0}(s)\right) d s \\
y_{0}(t) \geqslant \\
t \in[0,1] \text {. } K(t, s) f\left(s, y_{0}(s), x_{0}(s)\right) d s
\end{array}\right.
$$

Then, there exists a unique solution of the integral system (4.2).
Proof. Let $\mathrm{F}: \mathrm{X} \times \mathrm{X} \rightarrow \mathrm{X},(\mathrm{x}, \mathrm{y}) \longmapsto \mathrm{F}(\mathrm{x}, \mathrm{y})$, where

$$
\begin{equation*}
F(x, y)(t)=\int_{0}^{1} K(t, s) f(s, x(s), y(s)) d s, t \in[0,1] \tag{4.3}
\end{equation*}
$$

In this way, the system (4.2) can be written as

$$
\left\{\begin{array}{l}
x=F(x, y)  \tag{4.4}\\
y=F(y, x)
\end{array}\right.
$$

It can be seen from (4.4), that a solution of this system is a coupled fixed point of the mapping $F$.
We shall verify if the conditions of Theorem 2.6 are fulfilled.
Let $x, y, u, v \in X$ such that $x \leqslant u$ and $v \leqslant y$. Using (ii), we have

$$
\begin{aligned}
& F(x, y)(t)=\int_{0}^{1} K(t, s) f(s, x(s), y(s)) d s \leqslant \int_{0}^{1} K(t, s) f(s, u(s), v(s)) d s=F(u, v)(t) \text { for each } t \in[0,1] \\
& F(v, u)(t)=\int_{0}^{1} K(t, s) f(s, v(s), u(s)) d s \leqslant \int_{0}^{1} K(t, s) f(s, y(s), x(s)) d s=F(y, x)(t) \text { for each } t \in[0,1]
\end{aligned}
$$

Hence, if $x \leqslant u$ and $v \leqslant y$, then $F(x, y) \leqslant F(u, v)$ and $F(v, u) \leqslant F(y, x)$, which according to the definition of $E(G)$, it shows that $F$ is edge preserving. On the other hand, by Cauchy-Buniakovski-Schwarz inequality, we have

$$
\begin{aligned}
(F(x, y)(t)-F(u, v)(t))^{2} & \leqslant\left[\int_{0}^{1} K(t, s)(f(s, x(s), y(s))-f(s, u(s), v(s))) d s\right]^{2} \\
& \leqslant \int_{0}^{1} K^{2}(t, s) d s \int_{0}^{1}(f(s, x(s), y(s))-f(s, u(s), v(s)))^{2} \text { ds for each } t \in[0,1]
\end{aligned}
$$

We have

$$
\int_{0}^{1} \mathrm{~K}^{2}(\mathrm{t}, \mathrm{~s}) \mathrm{d} s=\int_{0}^{\mathrm{t}} \mathrm{~s}^{2} \mathrm{~d} s+\int_{\mathrm{t}}^{1} \mathrm{t}^{2} \mathrm{~d} s=\mathrm{t}^{2}\left(1-\frac{2}{3} \mathrm{t}\right) \leqslant \frac{1}{3} \text { for each } \mathrm{t} \in[0,1]
$$

Hence

$$
\begin{aligned}
(F(x, y)(t)-F(u, v)(t))^{2} & \leqslant \frac{1}{3} \int_{0}^{1}(f(s, x(s), y(s))-f(s, u(s), v(s)))^{2} d s \\
& \leqslant \frac{1}{3} \int_{0}^{1} \widetilde{\varphi}\left(\alpha(x(s)-u(s))^{2}+\beta(y(s)-v(s))^{2}\right) d s \\
& \leqslant \frac{1}{3} \widetilde{\varphi}(\alpha d(x, u)+\beta d(y, v)) \\
& \leqslant \frac{1}{3} \widetilde{\varphi}(\max \{\alpha, \beta\}(d(x, u)+d(y, v)))
\end{aligned}
$$

Hence

$$
\begin{equation*}
d(F(x, y), F(u, v)) \leqslant \frac{1}{3} \widetilde{\varphi}(\max \{\alpha, \beta\}(d(x, u)+d(y, v))), x \leqslant u, v \leqslant y \tag{4.5}
\end{equation*}
$$

In a similar way, we obtain

$$
\begin{equation*}
d(F(y, x), F(v, u)) \leqslant \frac{1}{3} \widetilde{\varphi}(\max \{\alpha, \beta\}(d(x, u)+d(y, v))), x \leqslant u, v \leqslant y \tag{4.6}
\end{equation*}
$$

By (4.5) and (4.6) we have

$$
d(F(x, y), F(u, v))+d(F(y, x), F(v, u)) \leqslant \frac{2}{3} \widetilde{\varphi}(\max \{\alpha, \beta\}(d(x, u)+d(y, v))), x \leqslant u, v \leqslant y
$$

Let us consider the function $\varphi:[0, \infty) \rightarrow[0, \infty), \varphi(t)=\frac{2}{3} \widetilde{\varphi}(k t), 0 \leqslant k<1$, which is a (b)-comparison function. Then, we have

$$
d(F(x, y), F(u, v))+d(F(y, x), F(v, u)) \leqslant \varphi(d(x, u)+d(y, v)), x \leqslant u, v \leqslant y
$$

Thus we have that $F$ is a $(\varphi, G)$-contraction of type (b). Condition (iv) from Theorem 4.1 shows that there exists $\left(x_{0}, y_{0}\right) \in X \times X$ such that $x_{0} \leqslant F\left(x_{0}, y_{0}\right)$ and $F\left(y_{0}, x_{0}\right) \leqslant y_{0}$ which implies that $(X \times X)^{F} \neq \varnothing$.

On the other hand, because of (i) and of the fact that $(X,\|\cdot\|, G)$ has the properties $\left(A_{1}\right)$ and $\left(A_{2}\right)$ we have that either (i) or (ii) from Theorem 2.6 is fulfilled.

In this way, we have that $F: X \times X \rightarrow X$, defined by (4.3), verifies the conditions of Theorems 2.6 and 2.7. Thus, there exists $\left(x^{*}, y^{*}\right) \in X \times X$ which is a coupled fixed point of the mapping $F$ and, as a consequence, a solution of the problem (4.1).

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