# Some common fixed point theorems in dislocated metric spaces 

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#### Abstract

Our purpose in this paper is to establish some new common fixed point theorems for four self-mappings of a dislocated metric space. © 2015 All rights reserved.


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## 1. Introduction

In 2012, Panthi and Jha [3] have established the following result.
Theorem 1.1. ([3]) Let $A, B, T$ and $S$ be four continuous self-mappings of a complete d-metric space $(X, d)$ such that

1. $T X \subset A X$ and $S X \subset B X$;
2. The pairs $(S, A)$ and $(T, B)$ are weakly compatible;
3. $d(S x, T y) \leq \alpha[d(A x, T y)+d(B y, S x)]+\beta[d(A x, S x)+d(B y, T y)]+\gamma d(A x, B y)$
for all $x, y \in X$ where $\alpha, \beta, \gamma \geq 0$ satisfying $\alpha+\beta+\gamma<\frac{1}{4}$.
Then $A, B, T$ and $S$ have a unique common fixed point in $X$.
[^0]Our purpose, here, is to prove that this theorem can be improved without any continuity requirement. Further, we will point out that if one supposes that $\gamma>0$, then one can replace condition $\alpha+\beta+\gamma<\frac{1}{4}$ by $\alpha+\beta+\gamma \leq \frac{1}{4}$. Recall that the notion of dislocated metric, introduced in 2000 by Hitzler and Seda [1], is characterized by the fact that self distance of a point need not be equal to zero and has useful applications in topology, logical programming and in electronics engineering. For further details on dislocated metric spaces, see, for example [2, 4]. We begin by recalling some basic concepts of the theory of dislocated metric spaces.

Definition 1.2. Let $X$ be a non empty set and let $d: X \times X \rightarrow[0, \infty)$ be a function satisfying the following conditions

1. $d(x, y)=d(y, x)$
2. $d(x, y)=d(y, x)=0$ implies $x=y$
3. $d(x, y)=d(x, z)+d(z, y)$ forall $x, y, z \in X$.

Then $d$ is called dislocated metric(or simply d-metric) on $X$.
Definition 1.3. A sequence $\left(x_{n}\right)$ in a d-metric space $(X, d)$ is called a Cauchy sequence if for given $\epsilon>0$, there exists $n_{0} \in N$ such that for all $m, n \geq n_{0}$, we have $d\left(x_{m}, x_{n}\right)<\epsilon$.

Definition 1.4. A sequence in a d-metric space converges if there exists $x \in X$ such that $d\left(x_{n}, x\right) \rightarrow 0$.
Definition 1.5. A d-metric space $(X, d)$ is called complete if every Cauchy sequence is convergent.
Remark 1.6. It is easy to verify that in a dislocated metric space, we have the following technical properties:

- A subsequence of a Cauchy sequence in d-metric space is a Cauchy sequence.
- A Cauchy sequence in d-metric space which possesses a convergent subsequence, converges.
- Limits in a d-metric space are unique.

Definition 1.7. Let $A$ and $S$ be two self-mappings of a d-metric space ( $X, d$ ).
$A$ and $S$ are said to be weakly compatible if they commute at their coincident point; that is, $A x=S x$ for some $x \in X$ implies $A S x=S A x$.

## 2. Main results

Theorem 2.1. Let $A, B, T$ and $S$ be four self-mappings of a d-metric space $(X, d)$ such that

1. $T X \subset A X$ and $S X \subset B X$;
2. The pairs $(S, A)$ and $(T, B)$ are weakly compatible;
3. For all $x, y \in X$ and $\alpha, \beta, \gamma \geq 0$ satisfying $\alpha+\beta+\gamma<\frac{1}{4}$, we have

$$
\begin{equation*}
d(S x, T y) \leq \alpha[d(A x, T y)+d(B y, S x)]+\beta[d(A x, S x)+d(B y, T y)]+\gamma d(A x, B y) \tag{2.1}
\end{equation*}
$$

4. The range of one of the mappings $A, B, S$ or $T$ is a complete subspace of $X$.

Then $A, B, T$ and $S$ have a unique common fixed point in $X$.

Proof. Let $x_{0}$ be an arbitrary point in $X$. Choose $x_{1} \in X$ such that $B x_{1}=S x_{0}$. Choose $x_{2} \in X$ such that $A x_{2}=T x_{1}$. Continuing in this fashion, choose $x_{n} \in X$ such that $S x_{2 n}=B x_{2 n+1}$ and $T x_{2 n+1}=A x_{2 n+2}$ for $n=0,1,2, \ldots$. To simplify, we consider the sequence $\left(y_{n}\right)$ defined by $y_{2 n}=S x_{2 n}$ and $y_{2 n+1}=T x_{2 n+1}$ for $n=0,1,2, \ldots$
We claim that $\left(y_{n}\right)$ is a Cauchy sequence. Indeed, by using (2.1) for $n \geq 1$, we have

$$
\begin{aligned}
d\left(y_{2 n+1}, y_{2 n}\right) & = \\
\leq & d\left(S x_{2 n}, T x_{2 n+1}\right) \\
\leq & \alpha\left[d\left(A x_{2 n}, T x_{2 n+1}\right)+d\left(B x_{2 n+1}, S x_{2 n}\right)\right] \\
& \quad+\beta\left[d\left(A x_{2 n}, S x_{2 n}\right)+d\left(B x_{2 n+1}, T x_{2 n+1}\right)\right]+\gamma d\left(A x_{2 n}, B x_{2 n+1}\right) \\
\leq & \alpha\left[d\left(y_{2 n-1}, y_{2 n+1}\right)+d\left(y_{2 n}, y_{2 n}\right)\right] \\
& \quad+\beta\left[d\left(y_{2 n-1}, y_{2 n}\right)+d\left(y_{2 n}, y_{2 n+1}\right)\right]+\gamma d\left(y_{2 n-1}, y_{2 n}\right) \\
\leq & \alpha\left[d\left(y_{2 n-1}, y_{2 n}\right)+d\left(y_{2 n}, y_{2 n+1}\right)+d\left(y_{2 n}, y_{2 n+1}\right)+d\left(y_{2 n+1}, y_{2 n}\right)\right] \\
& \quad+\beta\left[d\left(y_{2 n-1}, y_{2 n}\right)+d\left(y_{2 n}, y_{2 n+1}\right)\right]+\gamma d\left(y_{2 n-1}, y_{2 n}\right) \\
\leq & (\alpha+\beta+\gamma) d\left(y_{2 n-1}, y_{2 n}\right)+(3 \alpha+\beta) d\left(y_{2 n}, y_{2 n+1}\right) .
\end{aligned}
$$

Therefore

$$
d\left(y_{2 n}, y_{2 n+1}\right) \leq h d\left(y_{2 n-1}, y_{2 n}\right)
$$

where $h=\frac{\alpha+\beta+\gamma}{1-3 \alpha-\beta} \in\left[0,1\left[\right.\right.$. Hence $\left(y_{n}\right)$ is a Cauchy sequence in $X$ and therefore, according to Remarks 1.1, $\left(S x_{2 n}\right),\left(B x_{2 n+1}\right),\left(T x_{2 n+1}\right)$ and $\left(A x_{2 n+2}\right)$ are also Cauchy sequence.

Suppose that $S X$ is a complete subspace of $X$, then the sequence $\left(S x_{2 n}\right)$ converges to some $S a$ such that $a \in X$. According to Remark (1.6), $\left(y_{n}\right),\left(B x_{2 n+1}\right),\left(T x_{2 n+1}\right)$ and $\left(A x_{2 n+2}\right)$ converge to Sa. Since $S X \subset B X$, there exists $u \in X$ such that $S a=B u$. We show that $B u=T u$. In fact, by using (2.1), we have

$$
d\left(S x_{2 n}, T u\right) \leq \alpha\left[d\left(S x_{2 n}, T u\right)+d\left(B u, S x_{2 n}\right)\right]+\beta\left[d\left(A x_{2 n}, S x_{2 n}\right)+d(B u, T u)\right]+\gamma d\left(A x_{2 n}, B u\right)
$$

and therefore, on letting $n$ to infty, we get

$$
\begin{aligned}
d(B u, T u) & \leq \alpha[d(B u, T u)+d(B u, B u)]+\beta[d(B u, B u)+d(B u, T u)]+\gamma d(B u, B u) \\
& \leq(\alpha+\beta+\gamma) d(B u, B u)+(\alpha+\beta) d(B u, T u) \\
& \leq 2(\alpha+\beta+\gamma) d(B u, T u)+(\alpha+\beta) d(B u, T u) \\
& \leq(3 \alpha+3 \beta+2 \gamma) d(B u, T u)
\end{aligned}
$$

which implies that

$$
(1-3 \alpha-3 \beta-2 \gamma) d(B u, T u) \leq 0
$$

and therefore $d(B u, T u)=0$, since $(1-3 \alpha-3 \beta-2 \gamma)<0$, which implies that $T u=B u$. Since $T X \subset A X$, there exists $v \in X$ such that $T u=A v$. We show that $S v=A v$. Indeed, by using (2.1), we have

$$
\begin{aligned}
d(S v, A v) & =d(S v, T u) \\
& \leq \alpha[d(A v, T u)+d(B u, S v)]+\beta[d(A v, S v)+d(B u, T u)]+\gamma d(A v, B u) \\
& \leq \alpha[d(A v, A v)+d(A v, S v)]+\beta[d(A v, S v)+d(A v, A v)]+\gamma d(A v, A v) \\
& \leq \alpha[d(A v, S v)+d(S v, A v)+d(A v, S v)]+\beta[d(A v, S v)+d(A v, S v)+d(S v, A v)] \\
& \leq \gamma[d(A v, S v)+d(S v, A v)] \\
& \leq(3 \alpha+3 \beta+2 \gamma) d(A v, S v)
\end{aligned}
$$

which implies that

$$
(1-3 \alpha-3 \beta-2 \gamma) d(A v, S v) \leq 0
$$

and therefore $d(A v, S v)=0$, since $1-3 \alpha-3 \beta-2 \gamma<0$, which implies that $A v=S v$. Hence $B u=T u=$ $A v=S v$.
The weak compatibility of $S$ and $A$ implies that $A S v=S A v$, from which it follows that $A A v=A S v=$
$S A v=S S v$.
The weak compatibility of $B$ and $T$ implies that $B T u=T B u$, from which it follows that $B B u=B T u=$ $T B u=T T u$.
Let us show that $B u$ is a fixed point of $T$. Indeed, from (2.1), we get

$$
\begin{aligned}
d(B u, T B u) & =d(S v, T B u) \\
& \leq \alpha[d(A v, T B u)+d(B B u, S v)]+\beta[d(A v, S v)+d(B B u, T B u)]+\gamma d(A v, B B u) \\
& \leq \alpha[d(B u, T B u)+d(T B u, B u)]+\beta[d(B u, B u)+d(T B u, T B u)]+\gamma d(B u, T B u) \\
& \leq 2 \alpha d(B u, T B u)+\beta[d(B u, T B u)+d(T B u, B u)+d(T B u, B u)+d(B u, T B u)] \\
& \leq+\gamma d(B u, T B u) \\
& \leq(2 \alpha+4 \beta+\gamma) d(B u, T B u)
\end{aligned}
$$

and therefore $d(B u, T B u)=0$, since $1-2 \alpha-4 \beta-\gamma<0$, which implies that $T B u=B u$. Hence $B u$ is a fixed point of $T$. It follows that $B B u=T B u=B u$, which implies that $B u$ is a fixed point of $B$.
On the other hand, in view of (2.1), we have

$$
\begin{aligned}
d(S B u, B u) & =d(S B u, T B u) \\
& \leq \alpha[d(A B u, T B u)+d(B B u, S B u)]+\beta[d(A B u, S B u)+d(B B u, T B u)]+\gamma d(A B u, B B u) \\
& \leq \alpha[d(S B u, B u)+d(B u, S B u)]+\beta[d(B u, B u)+d(B u, B u)]+\gamma d(B u, B u) \\
& \leq 2 \alpha d(B u, S B u)+\beta[d(B u, S B u)+d(S B u, B u)+d(B u, S B u)+d(S B u, B u)] \\
& \quad+\gamma[d(B u, S B u)+d(S B u, B u)] \\
& \leq(2 \alpha+4 \beta+2 \gamma) d(B u, S B u)
\end{aligned}
$$

and therefore $d(B u, S B u)=0$, since $1-2 \alpha-4 \beta-2 \gamma<0$, which implies that $S B u=B u$. Hence $B u$ is a fixed point of $S$. It follows that $A B u=S B u=B u$, which implies that $B u$ is also a fixed point of $S$. Thus $B u$ is a common fixed point of $S, T, A$ and $B$.
Finally to prove uniqueness, suppose that there exists $u, v \in X$ such that $S u=T u=A u=B u$ and $S u=T u=A u=B v$. If $d(u, v) \neq 0$, then, by using (2.1), we get

$$
\begin{aligned}
d(u, v) & =d(S u, T v) \\
& \leq \alpha[d(A u, T v)+d(B v, S u)]+\beta[d(A u, S u)+d(B v, T v)]+\gamma d(A u, B v) \\
& \leq \alpha[d(u, v)+d(u, v)]+\beta[d(u, u)+d(v, v)]+\gamma d(u, v) \\
& \leq(2 \alpha+4 \beta+\gamma) d(u, v)
\end{aligned}
$$

from which it follows that $(1-2 \alpha-4 \beta-\gamma) d(u, v) \leq 0$ which is a contradiction since $1-2 \alpha-4 \beta-\gamma<0$. Hence $d(u, v)=0$ and therefore $u=v$.
The proof is similar when $T X$ or $A X$ or $B x$ is a complete subspace of $X$. This completes the proof.
For $A=B$ and $S=T$ in (2.1), we have the following result.
Corollary 2.2. Let $(X, d)$ be a d-metric space. Let $A$ and $T$ be two self-mappings of $X$ such that

1. $T X \subset A X$
2. The pair $(T, A)$ is weakly compatible and
3. $d(T x, T y) \leq \alpha[d(A x, T y)+d(A y, T x)]+\beta[d(A x, T x)+d(A y, T y)]+\gamma d(A x, A y)$ for all $x, y \in X$ where $\alpha, \beta, \gamma \geq 0$ satisfying $\alpha+\beta+\gamma<\frac{1}{4}$
4. $T X$ or $A X$ is a complete subspace of $X$.

Then $A$ and $T$ have a unique common fixed point in $X$.
For $A=B=I d_{X}$ in (2.1), we get the following corollary.
Corollary 2.3. Let $(X, d)$ be a d-metric space. Let $T$ and $S$ be two self-mappings of $X$ such that

1. $d(S x, T y) \leq \alpha[d(x, T y)+d(y, S x)]+\beta[d(x, S x)+d(y, T y)]+\gamma d(x, y)$
for all $x, y \in X$ where $\alpha, \beta, \gamma \geq 0$ satisfying $\alpha+\beta+\gamma<\frac{1}{4}$
2. $T X$ or $S X$ is a complete subspace of $X$.

Then $T$ and $S$ have a unique common fixed point in $X$.
For $S=T=I d_{X}$ in 2.1), we have the following result.
Corollary 2.4. Let $(X, d)$ be a complete d-metric space. Let $A$ and $B$ be two surjective self-mappings of $X$ such that

$$
d(x, y) \leq \alpha[d(A x, y)+d(B y, x)]+\beta[d(A x, x)+d(B y, y)]+\gamma d(A x, B y)
$$

for all $x, y \in X$ where $\alpha, \beta, \gamma \geq 0$ satisfying $\alpha+\beta+\gamma<\frac{1}{4}$. Then $A$ and $B$ have a unique common fixed point in $X$.

Remark 2.5. Following the procedure used in the proof of Theorem in 2.1, we have the next new result in which we replace the condition $\alpha+\beta+\gamma<\frac{1}{4}$ by $\alpha+\beta+\gamma \leq \frac{1}{4}$

Theorem 2.6. Let $A, B, T$ and $S$ be four self-mappings of a d-metric space $(X, d)$ such that

1. $T X \subset A X$ and $S X \subset B X$
2. The pairs $(S, A)$ and $(T, B)$ are weakly compatible and
3. For all $x, y \in X, \quad \alpha, \beta \geq 0$ and $\gamma>0$ satisfying $\alpha+\beta+\gamma \geq \frac{1}{4}$, we have

$$
\begin{equation*}
d(S x, T y) \leq \alpha[d(A x, T y)+d(B y, S x)]+\beta[d(A x, S x)+d(B y, T y)]+\gamma d(A x, B y) \tag{2.2}
\end{equation*}
$$

4. The range of one of the mappings $A, B, S$ or $T$ is a complete subspace of $X$.

Then $A, B, T$ and $S$ have a unique common fixed point in $X$.
Proof. For $\alpha, \beta \geq 0$ and $\gamma>0$ satisfying $\alpha+\beta+\gamma<\frac{1}{4}$, we apply Theorem 2.1. For $\alpha, \beta \geq 0$ and $\gamma>0$ satisfying $\alpha+\beta+\gamma=\frac{1}{4}$, we consider, as in Theorem 2.1 , an arbitrary point $x_{0}$ in $X$ and the sequence $\left(x_{n}\right)$ defined in $X$ by $S x_{2 n}=B x_{2 n+1}$ and $T x_{2 n+1}=A x_{2 n+2}$ for $n=0,1,2, \ldots$ To simplify, we consider the sequence $\left(y_{n}\right)$ defined by $y_{2 n}=S x_{2 n}$ and $y_{2 n+1}=T x_{2 n+1}$ for $n=0,1,2, \ldots$.
We claim that $\left(y_{n}\right)$ is a Cauchy sequence. Indeed, by using 2.2 for $n \geq 1$, we have

$$
\begin{aligned}
d\left(y_{2 n+1}, y_{2 n}\right) & =d\left(S x_{2 n}, T x_{2 n+1}\right) \\
\leq & \alpha\left[d\left(A x_{2 n}, T x_{2 n+1}\right)+d\left(B x_{2 n+1}, S x_{2 n}\right)\right] \\
& +\beta\left[d\left(A x_{2 n}, S x_{2 n}\right)+d\left(B x_{2 n+1}, T x_{2 n+1}\right)\right]+\gamma d\left(A x_{2 n}, B x_{2 n+1}\right) \\
\leq & \alpha\left[d\left(y_{2 n-1}, y_{2 n+1}\right)+d\left(y_{2 n}, y_{2 n}\right)\right] \\
& +\beta\left[d\left(y_{2 n-1}, y_{2 n}\right)+d\left(y_{2 n}, y_{2 n+1}\right)\right]+\gamma d\left(y_{2 n-1}, y_{2 n}\right) \\
\leq & \alpha\left[d\left(y_{2 n-1}, y_{2 n}\right)+d\left(y_{2 n}, y_{2 n+1}\right)+d\left(y_{2 n}, y_{2 n+1}\right)+d\left(y_{2 n+1}, y_{2 n}\right)\right] \\
& +\beta\left[d\left(y_{2 n-1}, y_{2 n}\right)+d\left(y_{2 n}, y_{2 n+1}\right)\right]+\gamma d\left(y_{2 n-1}, y_{2 n}\right) \\
\leq & (\alpha+\beta+\gamma) d\left(y_{2 n-1}, y_{2 n}\right)+(3 \alpha+\beta) d\left(y_{2 n}, y_{2 n+1}\right) \\
\leq & \frac{1}{4} d\left(y_{2 n-1}, y_{2 n}\right)+(3 \alpha+\beta) d\left(y_{2 n}, y_{2 n+1}\right) .
\end{aligned}
$$

Therefore $d\left(y_{2 n}, y_{2 n+1}\right) \leq h d\left(y_{2 n-1}, y_{2 n}\right)$, where $h=\frac{1}{4(1-3 \alpha-\beta)} \in\left[0,1\left[\right.\right.$. Hence $\left(y_{n}\right)$ is a Cauchy sequence in $X$ and therefore, according to Remarks 1.1, $\left(S x_{2 n}\right),\left(B x_{2 n+1}\right),\left(T x_{2 n+1}\right)$ and $\left(A x_{2 n+2}\right)$ are also Cauchy sequence.
Suppose that $S X$ is a complete subspace of $X$, then the sequence $\left(S x_{2 n}\right)$ converges to some $S a$ such
that $a \in X$. According to Remark (1.6), $\left(y_{n}\right),\left(B x_{2 n+1}\right),\left(T x_{2 n+1}\right)$ and $\left(A x_{2 n+2}\right)$ converge to $S a$. Since $S X \subset B X$, there exists $u \in X$ such that $S a=B u$. We show that $B u=T u$. In fact, in view of by using (2.1), we have

$$
d\left(S x_{2 n}, T u\right) \leq \alpha\left[d\left(S x_{2 n}, T u\right)+d\left(B u, S x_{2 n}\right)\right]+\beta\left[d\left(A x_{2 n}, S x_{2 n}\right)+d(B u, T u)\right]+\gamma d\left(A x_{2 n}, B u\right)
$$

and therefore, on letting $n$ to infty, we get

$$
\begin{aligned}
d(B u, T u) & \leq \alpha[d(B u, T u)+d(B u, B u)]+\beta[d(B u, B u)+d(B u, T u)]+\gamma d(B u, B u) \\
& \leq(\alpha+\beta+\gamma) d(B u, B u)+(\alpha+\beta) d(B u, T u) \\
& \leq 2(\alpha+\beta+\gamma) d(B u, T u)+(\alpha+\beta) d(B u, T u) \\
& \leq(3 \alpha+3 \beta+2 \gamma) d(B u, T u) \\
& \leq\left(\frac{3}{4}-\gamma\right) d(B u, T u)
\end{aligned}
$$

which implies that $\left(\frac{1}{4}+\gamma\right) d(B u, T u) \leq 0$. Therefore $d(B u, T u)=0$, which implies that $T u=B u$. Since $T X \subset A X$, there exists $v \in X$ such that $T u=A v$. We show that $S v=A v$. In fact, by using 2.2 , we have

$$
\begin{aligned}
d(S v, A v) & =d(S v, T u) \\
& \leq \alpha[d(A v, T u)+d(B u, S v)]+\beta[d(A v, S v)+d(B u, T u)]+\gamma d(A v, B u) \\
& \leq \alpha[d(A v, A v)+d(A v, S v)]+\beta[d(A v, S v)+d(A v, A v)]+\gamma d(A v, A v) \\
& \leq \alpha[d(A v, S v)+d(S v, A v)+d(A v, S v)]+\beta[d(A v, S v)+d(A v, S v)+d(S v, A v)] \\
& \leq \gamma[d(A v, S v)+d(S v, A v)] \\
& \leq(3 \alpha+3 \beta+2 \gamma) d(A v, S v) \\
& \leq\left(\frac{3}{4}-\gamma\right) d(A v, S v)
\end{aligned}
$$

which implies that $\left(\frac{1}{4}+\gamma\right) d(A v, S v) \leq 0$. Therefore $d(A v, S v)=0$, which implies that $A v=S v$. Hence $B u=T u=A v=S v$.
The weak compatibility of $S$ and $A$ implies that $A S v=S A v$, from which it follows that $A A v=A S v=$ $S A v=S S v$.
The weak compatibility of $B$ and $T$ implies that $B T u=T B u$, from which it follows that $B B u=B T u=$ $T B u=T T u$.
Let us show that $B u$ is a fixed point of $T$. Indeed, by using (2.2), we have

$$
\begin{aligned}
d(B u, T B u) & =d(S v, T B u) \\
& \leq \alpha[d(A v, T B u)+d(B B u, S v)]+\beta[d(A v, S v)+d(B B u, T B u)]+\gamma d(A v, B B u) \\
& \leq \alpha[d(B u, T B u)+d(T B u, B u)]+\beta[d(B u, B u)+d(T B u, T B u)]+\gamma d(B u, T B u) \\
& \leq 2 \alpha d(B u, T B u)+\beta[d(B u, T B u)+d(T B u, B u)+d(T B u, B u)+d(B u, T B u)] \\
& \leq(2 \alpha+4 \beta+\gamma) d(B u, T B u)
\end{aligned}
$$

and therefore $d(B u, T B u)=0$, since $1-2 \alpha-4 \beta-\gamma \geq 1-4\left(\frac{1}{4}-\gamma\right)-\gamma=3 \gamma>0$, which implies that $T B u=B u$. Hence $B u$ is a fixed point of $T$. It follows that $B B u=T B u=B u$, which implies that $B u$ is a fixed point of $B$.
On the other hand, by using 2.2 , we have

$$
\begin{aligned}
d(S B u, B u) & =d(S B u, T B u) \\
& \leq \alpha[d(A B u, T B u)+d(B B u, S B u)]+\beta[d(A B u, S B u)+d(B B u, T B u)]+\gamma d(A B u, B B u) \\
& \leq \alpha[d(S B u, B u)+d(B u, S B u)]+\beta[d(B u, B u)+d(B u, B u)]+\gamma d(B u, B u) \\
& \leq 2 \alpha d(B u, S B u)+\beta[d(B u, S B u)+d(S B u, B u)+d(B u, S B u)+d(S B u, B u)] \\
& \leq(2 \alpha+4 \beta+2 \gamma) d(B u, S B u)
\end{aligned}
$$

and therefore $d(B u, S B u)=0$, since $1-2 \alpha-4 \beta-2 \gamma \geq 1-4\left(\frac{1}{4}-\gamma\right)-2 \gamma=2 \gamma>0$, which implies that $S B u=B u$. Hence $B u$ is a fixed point of $S$. It follows that $A B u=S B u=B u$, which implies that $B u$ is also a fixed point of $S$. Thus $B u$ is a common fixed point of $S, T, A$ and $B$.
Finally to prove uniqueness, suppose that there exists $u, v \in X$ such that $S u=T u=A u=B u$ and $S u=T u=A u=B v$. If $d(u, v) \neq 0$, then by using (2.2), we get

$$
\begin{aligned}
d(u, v) & =d(S u, T v) \\
& \leq \alpha[d(A u, T v)+d(B v, S u)]+\beta[d(A u, S u)+d(B v, T v)]+\gamma d(A u, B v) \\
& \leq \alpha[d(u, v)+d(u, v)]+\beta[d(u, u)+d(v, v)]+\gamma d(u, v) \\
& \leq(2 \alpha+4 \beta+\gamma) d(u, v)
\end{aligned}
$$

from which it follows that $(1-2 \alpha-4 \beta-\gamma) d(u, v) \leq 0$ which is a contradiction since $1-2 \alpha-4 \beta-\gamma<0$. Hence $d(u, v)=0$ and therefore $u=v$.
The proof is similar when $T X$ or $A X$ or $B x$ is a complete subspace of $X$. This completes the proof.
For $A=B$ and $S=T$ in 2.6 , we have the following result.
Corollary 2.7. Let $(X, d)$ be a d-metric space. Let $A$ and $T$ be two self-mappings of $X$ such that

1. $T X \subset A X$
2. The pair $(T, A)$ is weakly compatible and
3. $d(T x, T y) \leq \alpha[d(A x, T y)+d(A y, T x)]+\beta[d(A x, T x)+d(A y, T y)]+\gamma d(A x, A y)$
for all $x, y \in X$ where $\alpha, \beta \geq 0$ and $\gamma>0$ satisfying $\alpha+\beta+\gamma \leq \frac{1}{4}$
4. TX or $A X$ is a complete subspace of $X$.

Then $A$ and $T$ have a unique common fixed point in $X$.
For $A=B=I d_{X}$ in 2.6 , we get the following corollary.
Corollary 2.8. Let $(X, d)$ be a d-metric space. Let $T$ and $S$ be two self-mappings of $X$ such that

1. $d(S x, T y) \leq \alpha[d(x, T y)+d(y, S x)]+\beta[d(x, S x)+d(y, T y)]+\gamma d(x, y)$
for all $x, y \in X$ where $\alpha, \beta \geq 0$ and $\gamma>0$ satisfying $\alpha+\beta+\gamma \leq \frac{1}{4}$
2. $T X$ or $S X$ is a complete subspace of $X$.

Then $T$ and $S$ have a unique common fixed point in $X$.
For $S=T=I d_{X}$ in (2.6), we have the following result.
Corollary 2.9. Let $(X, d)$ be a complete $d$-metric space. Let $A$ and $B$ be two surjective self-mappings of $X$ such that

$$
d(x, y) \leq \alpha[d(A x, y)+d(B y, x)]+\beta[d(A x, x)+d(B y, y)]+\gamma d(A x, B y)
$$

for all $x, y \in X$ where $\alpha, \beta \geq 0$ and $\gamma>0$ satisfying $\alpha+\beta+\gamma \leq \frac{1}{4}$. Then $A$ and $B$ have a unique common fixed point in $X$.

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