



# Solvability of multi-point boundary value problems on the half-line

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This paper is dedicated to Professor Ljubomir Ćirić

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## Abstract

In this work, using the Leray-Schauder continuation principle, we study the existence of at least one solution to the quasilinear second-order multi-point boundary value problems on the half-line.

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## 1. Introduction

Boundary value problems on the half-line arise quite naturally in the study of radially symmetric solutions of nonlinear elliptic equations and in various applications such as an unsteady flow of gas through a semi-infinite porous media, theory of drain flows and plasma physics. There have been many works concerning the existence of solutions for the boundary value problems on the half-line. We refer the reader to [1, 2, 3, 4, 6, 8, 9, 10, 11, 12, 13, 14, 15, 16, 19, 20, 22, 23] and the references therein.

Recently, Lian and Ge ([11]) studied the second-order three-point boundary value problem

$$\begin{aligned}x''(t) + g(t, x(t), x'(t)) &= 0, \text{ a.e. } t \in \mathbb{R}_+, \\x(0) &= \alpha x(\eta), \quad \lim_{t \rightarrow \infty} x'(t) = 0,\end{aligned}$$

where  $\mathbb{R}_+ = [0, \infty)$ ,  $\alpha \neq 1$  and  $\eta > 0$ . The authors investigated the existence of at least one solution under the assumption that  $g(t, \cdot, \cdot)$  and  $tg(t, \cdot, \cdot)$  are Carathéodory with respect to  $L^1(\mathbb{R}_+)$ .

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More recently, Kosmatov ([10]) studied the second-order nonlinear differential equation

$$(q(t)y'(t))' = k(t, y(t), y'(t)), \text{ a.e. } t \in \mathbb{R}_+,$$

satisfying two sets of boundary conditions:

$$y'(0) = 0, \lim_{t \rightarrow \infty} y(t) = 0$$

and

$$y(0) = 0, \lim_{t \rightarrow \infty} y(t) = 0,$$

where  $k : \mathbb{R}_+ \times \mathbb{R} \times \mathbb{R} \rightarrow \mathbb{R}$  is Carathéodory with respect to  $L^1(\mathbb{R}_+)$ ,  $\mathbb{R} = (-\infty, \infty)$ ,  $q \in C(\mathbb{R}_+) \cap C^1(0, \infty)$ ,  $1/q \in L^1(\mathbb{R}_+)$  and  $q(t) > 0$  for all  $t \in \mathbb{R}_+$ . The author obtained the existence of at least one solution to the above problems using the Leray-Schauder continuation principle. In the end of the paper, the author pointed out that the assumption  $q(0) > 0$  could be omitted, in which case one would have to work in a Banach space equipped with a weighted norm after the boundary conditions are adjusted accordingly.

Motivated by the above works ([10, 11]), we study the quasilinear second-order nonlinear differential equation

$$(w(t)\varphi_p(u'(t)))' + f(t, u(t), u'(t)) = 0, \text{ a.e. } t \in \mathbb{R}_+, \tag{P}$$

satisfying the following four sets of boundary conditions:

$$u(0) = \sum_{i=1}^{m-2} a_i u(\xi_i), \lim_{t \rightarrow \infty} (\varphi_p^{-1}(w)u')(t) = 0, \tag{BC_1}$$

$$u(0) = \sum_{i=1}^{m-2} a_i (\varphi_p^{-1}(w)u')(\xi_i), \lim_{t \rightarrow \infty} (\varphi_p^{-1}(w)u')(t) = 0, \tag{BC_2}$$

$$\lim_{t \rightarrow 0^+} (\varphi_p^{-1}(w)u')(t) = 0, \lim_{t \rightarrow \infty} u(t) = \sum_{i=1}^{m-2} a_i u(\xi_i), \tag{BC_3}$$

$$\lim_{t \rightarrow 0^+} (\varphi_p^{-1}(w)u')(t) = 0, \lim_{t \rightarrow \infty} u(t) = \sum_{i=1}^{m-2} a_i (\varphi_p^{-1}(w)u')(\xi_i), \tag{BC_4}$$

where  $\varphi_p(s) = |s|^{p-2}s$ ,  $p > 1$ ,  $\xi_i \in \mathbb{R}_+$  with  $0 \leq \xi_1 < \xi_2 < \dots < \xi_{m-2}$ ,  $a_i \in \mathbb{R}$  with  $\sum_{i=1}^{m-2} a_i \neq 1$ ,  $w \in C(\mathbb{R}_+, \mathbb{R})$  and  $f : \mathbb{R}_+ \times \mathbb{R} \times \mathbb{R} \rightarrow \mathbb{R}$  is a Carathéodory function such that  $f = f(t, u, v)$  is Lebesgue measurable in  $t$  for all  $(u, v) \in \mathbb{R} \times \mathbb{R}$  and continuous in  $(u, v)$  for almost all  $t \in \mathbb{R}_+$ . We further assume the following conditions hold.

(F) There exist measurable functions  $\alpha, \beta$  and  $\gamma$  such that

$$\alpha, \beta/w, \gamma \in L^1(\mathbb{R}_+)$$

and

$$|f(t, u, v)| \leq \alpha(t)|u|^{p-1} + \beta(t)|v|^{p-1} + \gamma(t), \text{ a.e. } t \in \mathbb{R}_+.$$

(W)  $\varphi_p^{-1}(1/w) \in L^1(\mathbb{R}_+)$  and  $Z_w = \{t \in \mathbb{R}_+ \mid w(t) = 0\}$  is a finite set.

By a solution to problem (P), (BC<sub>*i*</sub>), we understand a function  $u \in C(\mathbb{R}_+) \cap C^1(\mathbb{R}_+ \setminus Z_w)$  with  $w\varphi_p(u') \in AC(\mathbb{R}_+)$  satisfying (P), (BC<sub>*i*</sub>) ( $i = 1, 2, 3, 4$ ).

To the author’s knowledge, the multi-point boundary value problems with sign-changing weight  $w$  have not been investigated until now. The purpose of this paper is to establish the existence of at least one solution to  $p$ -Laplacian boundary value problems (P), (BC<sub>*i*</sub>) ( $i = 1, 2, 3, 4$ ) with sign-changing weight  $w$ .

Since  $\mathbb{R}_+$  is not compact, the related compactness principle on a bounded interval  $[0, 1]$  does not hold. In addition, solutions  $u$  of  $(P)$ ,  $(BC_i)$  ( $i = 1, 2, 3, 4$ ) may not be in  $C^1(\mathbb{R}_+)$  since  $w$  may have zeros in  $\mathbb{R}_+$ . In order to overcome these difficulties, a new Banach space equipped with a weighted norm is introduced, and then we can proceed with the Leray-Schauder continuation principle which was used in many works (see, e.g., [5, 7, 9, 10, 11, 17]) in order to prove the existence of a solution for the problems  $(P)$ ,  $(BC_i)$  ( $i = 1, 2, 3, 4$ ).

The rest of this paper is organized as follows. In Section 2, a weighted Banach space and corresponding operators to problems  $(P)$ ,  $(BC_i)$  ( $i = 1, 2, 3, 4$ ) are introduced, and lemmas are presented. In Section 3, our main results are given, and also an example to illustrate our results is presented.

## 2. Preliminaries

Let  $X$  be the Banach space

$$X = \{u \in C^1(\mathbb{R}_+ \setminus Z_w) \mid u \text{ and } \varphi_p^{-1}(w)u' \text{ are continuous and bounded functions on } \mathbb{R}_+\}$$

equipped with norm

$$\|u\| = \|u\|_\infty + \|\varphi_p^{-1}(w)u'\|_\infty,$$

where  $\|v\|_\infty = \sup_{t \in \mathbb{R}_+} |v(t)|$  and let  $Y$  be the Banach space  $L^1(\mathbb{R}_+)$  equipped with norm

$$\|h\|_1 = \int_0^\infty |h(s)| ds.$$

For convenience, we will use the following constants

$$A = 1 - \sum_{i=1}^{m-2} a_i,$$

$$B = |A|^{-1} \sum_{i=1}^{m-2} |a_i| \int_0^{\xi_i} \varphi_p^{-1} \left( \frac{1}{|w(s)|} \right) ds + \int_0^\infty \varphi_p^{-1} \left( \frac{1}{|w(s)|} \right) ds,$$

$$C = \sum_{i=1}^{m-2} |a_i| + \int_0^\infty \varphi_p^{-1} \left( \frac{1}{|w(s)|} \right) ds,$$

$$D = |A|^{-1} \sum_{i=1}^{m-2} |a_i| \int_{\xi_i}^\infty \varphi_p^{-1} \left( \frac{1}{|w(s)|} \right) ds + \int_0^\infty \varphi_p^{-1} \left( \frac{1}{|w(s)|} \right) ds.$$

For each  $h \in Y$ , we define, for  $t \in \mathbb{R}_+$ ,

$$\begin{aligned} (T_1 h)(t) &= A^{-1} \sum_{i=1}^{m-2} a_i \int_0^{\xi_i} \varphi_p^{-1} \left( \frac{1}{w(s)} \int_s^\infty h(\tau) d\tau \right) ds \\ &\quad + \int_0^t \varphi_p^{-1} \left( \frac{1}{w(s)} \int_s^\infty h(\tau) d\tau \right) ds, \end{aligned}$$

$$\begin{aligned} (T_2 h)(t) &= \sum_{i=1}^{m-2} a_i \varphi_p^{-1} \left( \int_{\xi_i}^\infty h(s) ds \right) \\ &\quad + \int_0^t \varphi_p^{-1} \left( \frac{1}{w(s)} \int_s^\infty h(\tau) d\tau \right) ds, \end{aligned}$$

$$\begin{aligned} (T_3 h)(t) &= A^{-1} \sum_{i=1}^{m-2} a_i \int_{\xi_i}^\infty \varphi_p^{-1} \left( \frac{1}{w(s)} \int_0^s h(\tau) d\tau \right) ds \\ &\quad + \int_t^\infty \varphi_p^{-1} \left( \frac{1}{w(s)} \int_0^s h(\tau) d\tau \right) ds \end{aligned}$$

and

$$(T_4h)(t) = -\sum_{i=1}^{m-2} a_i \varphi_p^{-1} \left( \int_0^{\xi_i} h(s) ds \right) + \int_t^\infty \varphi_p^{-1} \left( \frac{1}{w(s)} \int_0^s h(\tau) d\tau \right) ds.$$

Then  $T_i : Y \rightarrow X$  is well defined and for each  $h \in Y$ ,  $T_i h$  is the unique solution of the differential equation

$$(w(t)\varphi_p(u'(t)))' + h(t) = 0, \text{ a.e. } t \in \mathbb{R}_+,$$

subject to the boundary conditions  $(BC_i)$  ( $i = 1, 2, 3, 4$ ).

**Lemma 2.1.** *Let  $h \in Y$ . Then  $T_1h$  satisfies*

$$\|T_1h\|_\infty \leq B\|h\|_1^{1/(p-1)} \tag{2.1}$$

and

$$\|\varphi_p^{-1}(w)(T_1h)'\|_\infty \leq \|h\|_1^{1/(p-1)}. \tag{2.2}$$

**Proof.** Let  $h \in Y$ . Then, for all  $t \in \mathbb{R}_+$ , one has

$$\begin{aligned} |T_1h(t)| &\leq \left( |A|^{-1} \sum_{i=1}^{m-2} |a_i| \int_0^{\xi_i} \varphi_p^{-1} \left( \frac{1}{|w(s)|} \right) ds \right) \left( \int_0^\infty |h(s)| ds \right)^{1/(p-1)} \\ &\quad + \left( \int_0^t \varphi_p^{-1} \left( \frac{1}{|w(s)|} \right) ds \right) \left( \int_0^\infty |h(s)| ds \right)^{1/(p-1)} \\ &\leq B\|h\|_1^{1/(p-1)}. \end{aligned}$$

Similarly, for all  $t \in \mathbb{R}_+$ , one has

$$\begin{aligned} |(\varphi_p^{-1}(w)(T_1h)')(t)| &= \left| \varphi_p^{-1} \left( \int_t^\infty h(s) ds \right) \right| \\ &\leq \|h\|_1^{1/(p-1)}. \end{aligned}$$

Thus the proof is complete. □

The following lemmas can be proved by the similar manner and so we omit the proofs.

**Lemma 2.2.** *Let  $h \in Y$ . Then, for each  $i = 2, 4$ ,  $T_ih$  satisfies*

$$\|T_ih\|_\infty \leq C\|h\|_1^{1/(p-1)}$$

and

$$\|\varphi_p^{-1}(w)(T_ih)'\|_\infty \leq \|h\|_1^{1/(p-1)}.$$

**Lemma 2.3.** *Let  $h \in Y$ . Then  $T_3h$  satisfies*

$$\|T_ih\|_\infty \leq D\|h\|_1^{1/(p-1)}$$

and

$$\|\varphi_p^{-1}(w)(T_ih)'\|_\infty \leq \|h\|_1^{1/(p-1)}.$$

We define the Nemiskii operator  $N : X \rightarrow Y$  by

$$(Nu)(t) = f(t, u(t), u'(t)), \quad t \in \mathbb{R}_+.$$

It follows from (F) that  $N$  maps bounded sets of  $X$  into bounded sets of  $Y$  and is continuous. For each  $i \in \{1, 2, 3, 4\}$ , define  $L_i \triangleq T_i N : X \rightarrow X$ . Then  $L_i$  is well defined and problem (P),  $(BC_i)$  has a solution  $u$  if and only if  $L_i$  has a fixed point  $u$  in  $X$ .

To show the compactness of the operators  $L_i$  ( $i = 1, 2, 3, 4$ ), we use the following compactness criterion.

**Theorem 2.4.** ([2]) *Let  $Z$  be the space of all bounded continuous vector-valued functions on  $\mathbb{R}_+$  and  $S \subset Z$ . Then  $S$  is relatively compact in  $Z$  if the following conditions hold.*

- (i)  $S$  is bounded in  $Z$ .
- (ii) the functions from  $S$  are equicontinuous on any compact interval of  $\mathbb{R}_+$ .
- (iii) the functions from  $S$  are equiconvergent, that is, given  $\epsilon > 0$ , there exists a  $T = T(\epsilon) > 0$  such that  $\|\phi(t) - \phi(\infty)\|_{\mathbb{R}^n} < \epsilon$ , for all  $t > T$  and all  $\phi \in S$ .

**Lemma 2.5.** *For each  $i \in \{1, 2, 3, 4\}$ , the mapping  $L_i : X \rightarrow X$  is completely continuous.*

**Proof.** We only prove that  $L_1 : X \rightarrow X$  is completely continuous since other cases can be proved by the similar manner.

First, we show that  $L_1$  is compact. Let  $\Sigma$  be bounded in  $X$ , i.e., there exists  $M > 0$  such that  $\|u\| \leq M$  for all  $u \in \Sigma$ . Then there exists  $h_M \in Y$  such that  $|(Nu)(t)| \leq h_M(t)$  for all  $t \in \mathbb{R}_+$  and all  $u \in \Sigma$ . By Lemma 2.1,  $L_1(\Sigma)$  is bounded in  $X$ .

For  $t_1, t_2 \in \mathbb{R}_+$  with  $t_1 < t_2$ , one has

$$\begin{aligned} |(L_1u)(t_1) - (L_1u)(t_2)| &= \left| \int_{t_1}^{t_2} \varphi_p^{-1} \left( \frac{1}{w(s)} \int_s^\infty (Nu)(\tau) d\tau \right) ds \right| \\ &\leq \|h_M\|_1^{1/(p-1)} \int_{t_1}^{t_2} \varphi_p^{-1} \left( \frac{1}{|w(s)|} \right) ds \end{aligned}$$

and

$$\begin{aligned} &|(\varphi_p^{-1}(w)(L_1u)')(t_1) - (\varphi_p^{-1}(w)(L_1u)')(t_2)| \\ &= \left| \varphi_p^{-1} \left( \int_{t_1}^\infty (Nu)(s) ds \right) - \varphi_p^{-1} \left( \int_{t_2}^\infty (Nu)(s) ds \right) \right|, \end{aligned}$$

which yield that  $L_1(\Sigma)$  and  $\{\varphi_p^{-1}(w)(L_1u)' \mid u \in \Sigma\}$  are equicontinuous on  $\mathbb{R}_+$  by the facts that  $\varphi_p^{-1}$  is uniformly continuous on  $[-1, 1]$  and  $|(Nu)(t)| \leq h_M(t)$  for all  $t \in \mathbb{R}_+$ .

For  $u \in \Sigma$ , one has

$$\lim_{t \rightarrow \infty} (\varphi_p^{-1}(w)(L_1u)')(t) = \lim_{t \rightarrow \infty} \varphi_p^{-1} \left( \int_t^\infty (Nu)(s) ds \right) = 0.$$

Then

$$\begin{aligned} |L_1u(t) - \lim_{t \rightarrow \infty} L_1u(t)| &= \left| \int_t^\infty \varphi_p^{-1} \left( \frac{1}{w(s)} \int_s^\infty (Nu)(\tau) d\tau \right) ds \right| \\ &\leq \|h_M\|_1^{1/(p-1)} \int_t^\infty \varphi_p^{-1} \left( \frac{1}{|w(s)|} \right) ds \end{aligned}$$

and

$$\begin{aligned} |(\varphi_p^{-1}(w)(L_1u)')(t) - \lim_{t \rightarrow \infty} (\varphi_p^{-1}(w)(L_1u)')(t)| &= \left| \varphi_p^{-1} \left( \int_t^\infty (Nu)(s) ds \right) \right| \\ &\leq \left( \int_t^\infty |h_M(s)| ds \right)^{1/(p-1)}, \end{aligned}$$

which yield that  $L_1(\Sigma)$  and  $\{\varphi_p^{-1}(w)(L_1u)' \mid u \in \Sigma\}$  are equiconvergent. By Theorem 2.4, we can conclude that  $T_1$  is compact.

It follows from the Lebesgue dominated convergence theorem that  $L_1 : X \rightarrow X$  is continuous, and thus the proof is complete.  $\square$

### 3. Main results

In this section, we give our main results.

**Theorem 3.1.** *Assume  $B^{p-1}\|\alpha\|_1 + \|\beta/w\|_1 < 1$ . Then problem (P),  $(BC_1)$  has at least one solution for every  $\gamma \in Y$ .*

**Proof.** Consider the differential equation, for  $\lambda \in [0, 1]$ ,

$$(w(t)\varphi_p(u'(t)))' + \lambda f(t, u(t), u'(t)) = 0, \quad a.e. \ t \in \mathbb{R}_+, \quad (3.1)$$

subject to the boundary condition  $(BC_1)$ .

Let  $u$  be any solution of (3.1),  $(BC_1)$ . Then, by (F) and Lemma 2.1, one has

$$\begin{aligned} \|(w\varphi_p(u'))'\|_1 &= \lambda \|Nu\|_1 \\ &\leq \|\alpha\|_1 \|u\|_\infty^{p-1} + \|\beta/w\|_1 \|\varphi_p^{-1}(w)u'\|_\infty^{p-1} + \|\gamma\|_1 \\ &\leq B^{p-1}\|\alpha\|_1 \|(w\varphi_p(u'))'\|_1 + \|\beta/w\|_1 \|(w\varphi_p(u'))'\|_1 + \|\gamma\|_1, \end{aligned}$$

which yields

$$\|(w\varphi_p(u'))'\|_1 \leq \frac{\|\gamma\|_1}{1 - (B^{p-1}\|\alpha\|_1 + \|\beta/w\|_1)}.$$

It follows from Lemma 2.1 that the set of all possible solutions to problem (3.1),  $(BC_1)$  is a priori bounded by a constant independent of  $\lambda \in [0, 1]$ . Thus the proof is complete in view of the Leray-Schauder continuation principle (see, e.g., [18, 21]).  $\square$

Similarly, the following results are obtained.

**Theorem 3.2.** *Assume  $C^{p-1}\|\alpha\|_1 + \|\beta/w\|_1 < 1$ . Then problems (P),  $(BC_i)$  ( $i = 2, 4$ ) have at least one solution for every  $\gamma \in Y$ .*

**Theorem 3.3.** *Assume  $D^{p-1}\|\alpha\|_1 + \|\beta/w\|_1 < 1$ . Then problem (P),  $(BC_3)$  has at least one solution for every  $\gamma \in Y$ .*

Finally, we give an example to illustrate our results.

**Example 3.4.** In problems (P),  $(BC_i)$  ( $i = 1, 2, 3, 4$ ), let  $p = 3$ ,  $m = 3$ ,  $a_1 = 1/2$ ,  $\xi_1 = 1$ , and

$$w(t) = \begin{cases} \varphi_3(-(1-t)^{1/2}), & 0 \leq t < 1, \\ \varphi_3((t-1)^{1/2}), & 1 \leq t < 2, \\ \varphi_3(\exp(t-2)), & t \geq 2. \end{cases}$$

Then  $A = 1/2$ ,  $B = 7$ ,  $C = 11/2$  and  $D = 8$ . For any  $\gamma \in Y$ , we set

$$f(t, u, v) = \frac{\sin t}{(t+70)^2} \varphi_3(u) + \frac{w(t)}{(t+70)^2} \varphi_3(v) + \gamma(t).$$

Then  $\alpha(t) = \beta/w = 1/(t+70)^2$ , and  $\|\alpha\|_1 = \|\beta/w\|_1 = 1/70$ . Thus by Theorems 3.1, 3.2 and 3.3, problems (P),  $(BC_i)$  ( $i = 1, 2, 3, 4$ ) has at least one solution for every  $\gamma \in Y$ .

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