

INTERNAL NONLOCAL AND INTEGRAL CONDITION
PROBLEMS OF THE DIFFERENTIAL EQUATION $x' = f(t, x, x')$

A. M. A. EL-SAYED¹, E. M. HAMDALLAH² AND KH. W. ELKADEKY³

ABSTRACT. In this work, we are concerned with the existence of at least one absolutely continuous solution of the Cauchy problem for the differential equation $x' = f(t, x, x')$, $t \in (0, 1)$ with the internal nonlocal condition $\sum_{k=1}^m a_k x(\tau_k) = x_o$, $\tau_k \in (c, d) \subseteq (0, 1)$. The problem of the integral condition $\int_c^d x(s) dg(s) = x_o$ will be considered.

1. INTRODUCTION

Problems with non-local conditions have been extensively studied by several authors in the last two decades. The reader is referred to [1]- [6] and [9] - [15] and references therein.

Here we are consisted with the nonlocal problem

$$\frac{dx(t)}{dt} = f\left(t, x(t), \frac{dx(t)}{dt}\right), \text{ a.e. } t \in (0, 1), \quad (1.1)$$

$$\sum_{k=1}^m a_k x(\tau_k) = x_o, \quad \sum_{k=1}^m a_k \neq 0 \text{ and } \tau_k \in (c, d) \subseteq (0, 1). \quad (1.2)$$

The existence of at least one solution $x \in AC[0, 1]$ will be studied when the function f is measurable in $t \in [0, 1]$, for any $(u_1, u_2) \in R^2$ and continuous in $(u_1, u_2) \in R^2$, for $t \in [0, 1]$. As a consequence of our result, the problem of the

Date: Received: 1 Jan, 2011; Revised: 20 April, 2011.

*Corresponding author

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2000 *Mathematics Subject Classification.* Primary 26A33; Secondary 34A12, 34A40.

Key words and phrases. Nonlocal conditions, integral condition, existence of solution, fixed-point theorem.

differential equation (1.1) with integral condition

$$\int_c^d x(s) dg(s) = x_o, \quad (1.3)$$

where g is a nondecreasing function, will be studied.

It must be noticed that the nonlocal condition (1.2) and the integral condition (1.3) are more general than the following ones

$$x(\tau) = x_o, \quad \tau \in (c, d), \quad (1.4)$$

$$\sum_{k=1}^m a_k x(\tau_k) = 0, \quad \tau_k \in (a, c), \quad (1.5)$$

and

$$\int_a^c x(s) dg(s) = 0. \quad (1.6)$$

The following theorems will be needed.

Theorem (Kolmogorov Compactness Criterion) see[8]

Let $\Omega \subseteq L^P(0, 1)$, $1 \leq P < \infty$. If

- (i) Ω is bounded $L^P(0, 1)$,
- (ii) $x_h \rightarrow x$ as $h \rightarrow 0$ uniformly with respect to $x \in \Omega$, then Ω is relatively compact in $L^P(0, 1)$, where

$$x_h(t) = \frac{1}{h} \int_t^{t+h} x(s) ds.$$

Theorem (Schauder) see[12]

Let U be a convex subset of a Banach space X , and $T : U \rightarrow U$ is compact, continuous map. Then T has at least one fixed point in U .

2. EXISTENCE OF SOLUTION

The following Lemma gives the integral equation representation for the nonlocal problem (1.1)-(1.2).

Lemma 2.1 The solution of the nonlocal problem (1.1)-(1.2) can be expressed by the integral equation

$$x(t) = ax_0 - a \sum_{k=1}^m a_k \int_0^{\tau_k} y(s) ds + \int_0^t y(s) ds \quad (2.1)$$

where y is the solution of the functional integral equation

$$y(t) = f(t, ax_0 - a \sum_{k=1}^m a_k \int_0^{\tau_k} y(s) ds + \int_0^t y(s) ds, y(t)), \quad t \in (0, 1). \quad (2.2)$$

Proof. Let $\frac{dx(t)}{dt} = y(t)$ in equation (1), then

$$y(t) = f(t, x(0) + \int_0^t y(s) ds, y(t)) \quad (2.3)$$

where

$$x(t) = x(0) + \int_0^t y(s) ds. \quad (2.4)$$

Let $t = \tau_k$ in (2.4), we obtain

$$x(\tau_k) = x(0) + \int_0^{\tau_k} y(s) ds$$

and

$$\sum_{k=1}^m a_k x(\tau_k) = \sum_{k=1}^m a_k x(0) + \sum_{k=1}^m a_k \int_0^{\tau_k} y(s) ds. \quad (2.5)$$

Substitute from (2) into (2.5), we get

$$x_0 = \sum_{k=1}^m a_k x(0) + \sum_{k=1}^m a_k \int_0^{\tau_k} y(s) ds$$

and

$$x(0) = a(x_0 - \sum_{k=1}^m a_k \int_0^{\tau_k} y(s) ds) \quad (2.6)$$

where $a = (\sum_{k=1}^m a_k)^{-1}$.

Substitute from (2.6) into (2.4) and (2.3), we obtain (2.1) and (2.2).

Consider the functional integral equation (2.2) with the following assumptions

- (i) $f : [0, 1] \times R^2 \rightarrow R^+$ is measurable in $t \in [0, 1]$ for any $(u_1, u_2) \in R^2$ and continuous in $(u_1, u_2) \in R^2$ for almost all $t \in [0, 1]$.
- (ii) There exists a function $a \in L_1[0, 1]$ and two constants $b_i > 0$, $i = 1, 2$ such that

$$|f(t, u_1, u_2)| \leq |a(t)| + \sum_{i=1}^2 b_i |u_i|, \quad \forall (t, u_1, u_2) \in [0, 1] \times R^2.$$

(iii)

$$(2b_1 + b_2) < 1.$$

Now we have the following theorem.

Theorem 2.1 Assume that the assumptions (i) - (iii) are satisfied. Then the functional integral equation (2.2) has at least one solution $y \in L_1(0, 1)$.

Proof. Let $y \in B_r \subset L^1$, $B_r = \{y : \|y\|_{L^1} \leq r, r > 0\}$, $r = \frac{\|a\| + ab_1 x_0}{1 - (2b_1 + b_2)}$.

Clearly B_r is nonempty, convex and closed.

Define the operator H by

$$Hy(t) = f(t, ax_0 - a \sum_{k=1}^m a_k \int_0^{\tau_k} y(s) ds + \int_0^t y(s) ds, y(t)), \quad t \in (0, 1). \quad (2.7)$$

From assumptions (i) and (iii), we obtain

$$\begin{aligned}
\|Hy\|_{L_1} &= \int_0^1 |(Hy)(t)| dt \\
&= \int_0^1 |f(t, ax_0 - a \sum_{k=1}^m a_k \int_0^{\tau_k} y(s) ds + \int_0^t y(s) ds, y(t)| dt \\
&\leq \int_0^1 (|a(t)| + b_1 |ax_0 - a \sum_{k=1}^m a_k \int_0^{\tau_k} y(s) ds + \int_0^t y(s) ds| + b_2 |y(t)|) dt \\
&\leq \int_0^1 (|a(t)| dt + \int_0^1 b_1 ax_0 dt + ab_1 \sum_{k=1}^m a_k \int_0^1 \int_0^{\tau_k} |y(s)| ds dt \\
&\quad + b_1 \int_0^1 \int_0^t |y(s)| ds dt + b_2 \int_0^1 |y(t)| dt) \\
&\leq \|a\| + ab_1 x_0 + b_1 \|y\| + b_1 \|y\| + b_2 \|y\| \\
&\leq \|a\| + b_1 ax_0 + (2b_1 + b_2) \|y\| \leq r.
\end{aligned}$$

Then $\|Hy\|_{L_1} \leq r$, which implies that the operator H maps B_r into itself. Assumption (i) implies that H is continuous.

Now, let Ω be a bounded subset of B_r , therefore $H(\Omega)$ is bounded in $L_1(0, 1)$, i.e condition (i) of Kolmogorav compactness criterion is satisfied, it remains to show $(Hy)_h \rightarrow (Hy)$, in $L_1(0, 1)$.

Let $y \in \Omega \subset L_1(0, 1)$, then we have the following

$$\begin{aligned}
\|(Hy)_h - (Hy)\|_{L_1} &= \int_0^1 |(Hy)_h(t) - (Hy)(t)| dt \\
&= \int_0^1 \left| \frac{1}{h} \int_t^{t+h} (Hy)(s) ds - (Hy)(t) \right| dt \\
&\leq \int_0^1 \left(\frac{1}{h} \int_t^{t+h} |(Hy)(s) - (Hy)(t)| ds \right) dt \\
&\leq \int_0^1 \frac{1}{h} \int_t^{t+h} |f(s, ax_0 - a \sum_{k=1}^m a_k \int_0^{s_k} y(\tau) d\tau + \int_0^s y(\tau) d\tau, y(s)) \\
&\quad - f(t, ax_0 - a \sum_{k=1}^m a_k \int_0^{\tau_k} y(s) ds + \int_0^t y(s) ds, y(t))| ds dt.
\end{aligned}$$

Since $y \in \Omega \subset L_1$, and (assumption (ii) implies that) $f \in L_1[0, 1]$, it follows that

$$\frac{1}{h} \int_t^{t+h} |f(s, ax_0 - a \sum_{k=1}^m a_k \int_0^{s_k} y(\tau) d\tau + \int_0^s y(\tau) d\tau, y(s))$$

$$-f(t, ax_0 - a \sum_{k=1}^m a_k \int_0^{\tau_k} y(s) ds + \int_0^t y(s) ds, y(t))| ds \rightarrow 0 \text{ as } h \rightarrow 0, t \in (0, 1).$$

Hence $(Hy)_h \rightarrow (Hy)$, uniformly as $h \rightarrow 0$.

Then by Kolmogorov compactness criterion, $H(\Omega)$ is relatively compact.

That is H has a fixed point in B_r , then there exist at least one solution $y \in L_1(0, 1)$ of the functional equation (2.3).

Now, consider the nonlocal problem (1.1)-(1.2).

Theorem 2.2 Let the assumptions of Theorem 2.1 are satisfied. Then the nonlocal problem (1.1)-(1.2) has at least one solution $x \in AC[0, 1]$.

Proof. From Theorem 2.1 and equations (2.1) and (2.6) we deduce that there exist at least one solution $x \in AC[0, 1]$ of equation (2.1) where

$$x(0) = \lim_{t \rightarrow 0} x(t) = ax_0 - a \sum_{k=1}^m a_k \int_0^{\tau_k} y(s) ds \quad (2.8)$$

and

$$x(1) = \lim_{t \rightarrow 1} x(t) = ax_0 - a \sum_{k=1}^m a_k \int_0^{\tau_k} y(s) ds + \int_0^1 y(s) ds \quad (2.9)$$

To complete the proof, we prove that equation (2.1) satisfies nonlocal problem (1.1)-(1.2).

Differentiating (2.1), we get

$$\frac{dx}{dt} = y(t) = f(t, x(t), \frac{dx}{dt})$$

Let $t = \tau_k$ in (2.1), we get

$$\begin{aligned} x(\tau_k) &= ax_0 - a \sum_{k=1}^m a_k \int_0^{\tau_k} y(s) ds + \int_0^{\tau_k} y(s) ds \\ &= ax_0 + (1 - a \sum_{k=1}^m a_k) \int_0^{\tau_k} y(s) ds. \end{aligned}$$

Then

$$\sum_{k=1}^m a_k x(\tau_k) = \sum_{k=1}^m a_k ax_0 + \sum_{k=1}^m a_k (1 - a \sum_{k=1}^m a_k) \int_0^{\tau_k} y(s) ds = x_0.$$

This complete the proof of the equivalent between the nonlocal problem (1.1)-(1.2) and the integral equation (2.1).

This implies that there exist at least one solution $x \in AC[0, 1]$ of the nonlocal problem (1.1)-(1.2).

3. NONLOCAL INTEGRAL CONDITION

Let $x \in AC[0, 1]$ be the solution of the nonlocal problem (1.1)-(1.2). Let $a_k = g(t_k) - g(t_{k-1})$, g is a nondecreasing function, $\tau_k \in (t_{k-1}, t_k)$, $c = t_0 < t_1 < t_2, \dots < t_n = d$, then the nonlocal condition (1.2) will be

$$\sum_{k=1}^m (g(t_k) - g(t_{k-1})) x(\tau_k) = x_o.$$

From the continuity of the solution x of the nonlocal problem (1.1)-(1.2) we can obtain

$$\lim_{m \rightarrow \infty} \sum_{k=1}^m (g(t_k) - g(t_{k-1})) x(\tau_k) = \int_c^d x(s) dg(s).$$

and the nonlocal condition (2) transformed to the integral one

$$\int_c^d x(s) dg(s) = x_o.$$

Now, we have the following Theorem

Theorem 3.1 Let the assumptions of Theorem 2.1 are satisfied. Then there exists at least one solution $x \in AC[0, 1]$ of the nonlocal problem with integral condition,

$$\frac{dx(t)}{dt} = f(t, x(t), \frac{dx(t)}{dt}), \text{ a.e. } t \in (0, 1],$$

$$\int_c^d x(s) dg(s) = x_o.$$

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¹DEPARTMENT OF MATHEMATICS, ALEXANDRIA UNIVERSITY, ALEXANDRIA, EGYPT
E-mail address: amasayed@hotmail.com

²DEPARTMENT OF MATHEMATICS, ALEXANDRIA UNIVERSITY, ALEXANDRIA, EGYPT
E-mail address: emanhmdalla@hotmail.com

³ DEPARTMENT OF MATHEMATICS, FACULTY OF SCIENCE, GARYOUNIS UNIVERSITY, BENGHAZI, LIBYA
E-mail address: k-welkadeky@yahoo.com