



Variation of parameters for local fractional nonhomogenous linear-differential equations

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Abstract

In this paper we study the method of variation of parameters to find a particular solution of a nonhomogenous linear fractional differential equations. A formula similar to that for usual ordinary differential equations is obtained. ©2016 All rights reserved.

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1. Introduction

There are many definitions available in the literature for fractional derivatives. The main ones are the Riemann Liouville definition and the Caputo definition, see [10, 11], and for some applications one can see [5], [8] and [12].

(i) Riemann - Liouville Definition. For $\alpha \in [n - 1, n)$, the α derivative of f is

$$D_a^\alpha(f)(t) = \frac{1}{\Gamma(n - \alpha)} \frac{d^n}{dt^n} \int_a^t \frac{f(x)}{(t - x)^{\alpha - n + 1}} dx.$$

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(ii) Caputo Definition. For $\alpha \in [n - 1, n)$, the α derivative of f is

$$D_a^\alpha(f)(t) = \frac{1}{\Gamma(n - \alpha)} \int_a^t \frac{f^{(n)}(x)}{(t - x)^{\alpha - n + 1}} dx.$$

Such definitions have many setbacks such as:

(i) The Riemann-Liouville derivative does not satisfy $D_a^\alpha(1) = 0$ ($D_a^\alpha(1) = 0$ for the Caputo derivative), if α is not a natural number.

(ii) All fractional derivatives do not satisfy the known formula of the derivative of the product of two functions:

$$D_a^\alpha(fg) = fD_a^\alpha(g) + gD_a^\alpha(f).$$

(iii) All fractional derivatives do not satisfy the known formula of the derivative of the quotient of two functions:

$$D_a^\alpha(f/g) = \frac{gD_a^\alpha(f) - fD_a^\alpha(g)}{g^2}.$$

(iv) All fractional derivatives do not satisfy the chain rule:

$$D_a^\alpha(f \circ g)(t) = f^{(\alpha)}(g(t)) g^{(\alpha)}(t).$$

(v) All fractional derivatives do not satisfy: $D^\alpha D^\beta f = D^{\alpha + \beta} f$, in general.

(vi) All fractional derivatives, specially Caputo definition, assumes that the function f is differentiable.

In [9], the authors gave a new definition of fractional derivative which is a natural extension to the usual first derivative as follows:

Given a function $f : [0, \infty) \rightarrow \mathbb{R}$. Then for all $t > 0, \alpha \in (0, 1)$, let

$$T_\alpha(f)(t) = \lim_{\varepsilon \rightarrow 0} \frac{f(t + \varepsilon t^{1-\alpha}) - f(t)}{\varepsilon},$$

T_α is called the **conformable fractional derivative of f of order α** .

Let $f^{(\alpha)}(t)$ stands for $T_\alpha(f)(t)$.

If f is α -differentiable in some $(0, b)$, $b > 0$ and $\lim_{t \rightarrow 0^+} f^{(\alpha)}(t)$ exists, then define

$$f^{(\alpha)}(0) = \lim_{t \rightarrow 0^+} f^{(\alpha)}(t).$$

According to this definition, we have the following properties, see [9],

- 1 . $T_\alpha(1) = 0$,
- 2 . $T_\alpha(t^p) = pt^{p-\alpha}$ for all $p \in \mathbb{R}$,
- 3 . $T_\alpha(\sin at) = at^{1-\alpha} \cos at$, $a \in \mathbb{R}$,
- 4 . $T_\alpha(\cos at) = -at^{1-\alpha} \sin at$, $a \in \mathbb{R}$,

$$5 \ .T_\alpha(e^{at}) = at^{1-\alpha}e^{at}, \quad a \in \mathbb{R}.$$

Further, many functions behave as in the usual derivative. Here are some formulas

$$\begin{aligned} T_\alpha\left(\frac{1}{\alpha}t^\alpha\right) &= 1, \\ T_\alpha\left(e^{\frac{1}{\alpha}t^\alpha}\right) &= e^{\frac{1}{\alpha}t^\alpha}, \\ T_\alpha\left(\sin\frac{1}{\alpha}t^\alpha\right) &= \cos\left(\frac{1}{\alpha}t^\alpha\right), \\ T_\alpha\left(\cos\frac{1}{\alpha}t^\alpha\right) &= -\sin\left(\frac{1}{\alpha}t^\alpha\right). \end{aligned}$$

For more applications on the conformable fractional derivative, one can see [1, 2, 3, 4, 6, 7].

In this paper we use the conformable fractional derivative to study methods for finding particular solutions of a certain class of nonhomogenous linear fractional differential equations.

2. Fractional linear differential equations

Definition 2.1. Let $0 < \alpha < 1$ and $n \in \{1, 2, 3, \dots\}$. Then we write

$$T^{n\alpha} f = \underbrace{D^\alpha D^\alpha \dots D^\alpha}_{n \text{ times}} f.$$

For simplicity, we write $f^{(n\alpha)}$ for $T^{n\alpha}$. So $y^{(2\alpha)}(x)$ stands for $\frac{d^\alpha}{dx^\alpha} \left(\frac{d^\alpha y}{dx^\alpha} \right)$.

Definition 2.2. A differential equation of the form

$$T^{n\alpha}y + a_{n-1}T^{(n-1)\alpha}y + \dots + a_1T^\alpha y + a_0y = f(x) \quad (2.1)$$

is called a linear fractional differential equation of order n . The coefficients a_0, a_1, \dots, a_{n-1} could be constants or variables.

Since $0 < \alpha < 1$, if y is n -times differentiable, then there are n -independent solutions y_1, y_2, \dots, y_n for the homogeneous differential equation

$$T^{n\alpha}y + \dots + a_0y = 0. \quad (2.2)$$

To find a particular solution for (2.1), one can use either undetermined coefficients (for special types of f and constant coefficients) or the variation of parameters method. In fact we find a complete formula for y_p when $n = 2$.

Definition 2.3. Let y_1, y_2 be two independent functions. The function

$$W^\alpha[y_1, y_2] = \begin{vmatrix} y_1 & y_2 \\ y_1^{(\alpha)} & y_2^{(\alpha)} \end{vmatrix}$$

will be called the α -Wronskian of y_1 and y_2 .

More generally, If y_1, y_2, \dots, y_n are n linearly independent functions, then

$$W^\alpha[y_1, y_2, \dots, y_n] = \begin{vmatrix} y_1 & y_2 & \dots & y_n \\ y_1^{(\alpha)} & y_2^{(\alpha)} & \dots & y_n^{(\alpha)} \\ \vdots & \vdots & \ddots & \vdots \\ y_1^{((n-1)\alpha)} & y_2^{((n-1)\alpha)} & \dots & y_n^{((n-1)\alpha)} \end{vmatrix}.$$

3. The Main Results

Let y_1 and y_2 be two independent solutions for

$$D^\alpha (D^\alpha y) + a_1 D^\alpha y + a_0 y = 0. \quad (3.1)$$

Our goal is to find y_p for

$$D^\alpha (D^\alpha y) + a_1 D^\alpha y + a_0 y = f(x). \quad (3.2)$$

Procedure:

Step(i). Let

$$y_p = c_1 y_1 + c_2 y_2,$$

where c_1 and c_2 are functions of x . So

$$\begin{aligned} y_p(x) &= c_1(x)y_1(x) + c_2(x)y_2(x), \\ y_p^{(\alpha)} &= c_1^{(\alpha)}y_1 + c_1 y_1^{(\alpha)} + c_2^{(\alpha)}y_2 + c_2 y_2^{(\alpha)}. \end{aligned}$$

Step(ii). Put

$$c_1^{(\alpha)}y_1 + c_2^{(\alpha)}y_2 = 0. \quad (3.3)$$

Hence

$$\begin{aligned} D^\alpha (y_p^{(\alpha)}) &= D^\alpha (c_1 y_1 + c_2 y_2) \\ &= c_1^{(\alpha)}y_1^{(\alpha)} + c_1 y_1^{(2\alpha)} + c_2^{(\alpha)}y_2^{(\alpha)} + c_2 y_2^{(2\alpha)}. \end{aligned}$$

Step(iii). Substitute $D^\alpha (y_p^{(\alpha)})$ in the equation (3.2) to get

$$c_1^{(\alpha)}y_1^{(\alpha)} + c_1 y_1^{(2\alpha)} + c_2^{(\alpha)}y_2^{(\alpha)} + c_2 y_2^{(2\alpha)} + a_1 (c_1 y_1^{(\alpha)} + c_2 y_2^{(\alpha)}) + a_0 (c_1 y_1 + c_2 y_2) = f(x).$$

Hence,

$$c_1 (y_1^{(2\alpha)} + a_1 y_1^{(\alpha)} + a_0 y_1) + c_2 (y_2^{(2\alpha)} + a_1 y_2^{(\alpha)} + a_0 y_2) + c_1^{(\alpha)}y_1^{(\alpha)} + c_2^{(\alpha)}y_2^{(\alpha)} = f(x).$$

Step(iv). Since y_1 and y_2 are solutions for (3.2), we get

$$c_1^{(\alpha)}y_1^{(\alpha)} + c_2^{(\alpha)}y_2^{(\alpha)} = f(x). \quad (3.4)$$

Now we have to solve (3.3) and (3.4) to get

$$c_1^{(\alpha)} = -\frac{f(x)y_2(x)}{W^\alpha[y_1, y_2]}$$

and

$$c_2^{(\alpha)} = \frac{f(x)y_1(x)}{W^\alpha[y_1, y_2]}.$$

Thus

$$y_p(x) = \int_a^x \frac{\begin{vmatrix} y_1(t) & y_2(t) \\ y_1(x) & y_2(x) \end{vmatrix}}{W^\alpha[y_1, y_2](t)} \frac{f(t)}{t^{1-\alpha}} dt,$$

that is to say,

$$\begin{aligned} y_p(x) &= I_\alpha^a \left[\frac{\begin{vmatrix} y_1(t) & y_2(t) \\ y_1(x) & y_2(x) \end{vmatrix}}{W^\alpha[y_1, y_2](t)} f(t) \right] \\ &= I_\alpha^a (K(x, t)f(t)), \end{aligned}$$

where

$$K(x, t) = \frac{\begin{vmatrix} y_1(t) & y_2(t) \\ y_1(x) & y_2(x) \end{vmatrix}}{W^\alpha[y_1, y_2](t)}.$$

Similarly we can consider the case of higher order linear fractional differential equations. Let y_1, y_2, \dots, y_n be linearly independent solutions of the homogeneous equation (2.2). As we have shown above, one can find a particular solution of the nonhomogeneous equation (2.1) of the form

$$y_p(x) = c_1(x)y_1(x) + c_2(x)y_2(x) + \dots + c_n(x)y_n(x). \quad (3.5)$$

One can apply the same steps in the previous process and obtain the following nonhomogeneous algebraic linear system of n equations for $c_1^{(\alpha)}, c_2^{(\alpha)}, \dots, c_n^{(\alpha)}$

$$\begin{aligned} y_1 c_1^{(\alpha)} + y_2 c_2^{(\alpha)} + \dots + y_n c_n^{(\alpha)} &= 0 \\ y_1^{(\alpha)} c_1^{(\alpha)} + y_2^{(\alpha)} c_2^{(\alpha)} + \dots + y_n^{(\alpha)} c_n^{(\alpha)} &= 0 \\ y_1^{(2\alpha)} c_1^{(\alpha)} + y_2^{(2\alpha)} c_2^{(\alpha)} + \dots + y_n^{(2\alpha)} c_n^{(\alpha)} &= 0 \\ \vdots & \\ y_1^{((n-1)\alpha)} c_1^{(\alpha)} + y_2^{((n-1)\alpha)} c_2^{(\alpha)} + \dots + y_n^{((n-1)\alpha)} c_n^{(\alpha)} &= f. \end{aligned}$$

Using Cramer's rule we find

$$c_m^{(\alpha)}(x) = \frac{f(x)W_m^\alpha(x)}{W^\alpha(x)}, \quad (3.6)$$

where $W^\alpha(x) = W^\alpha(y_1, y_2, \dots, y_n)(x)$ and W_m^α is the determinant obtained from W^α by replacing the m th column by the column $(0, 0, \dots, 0, 1)$. Thus

$$y_p(x) = \sum_{m=1}^n y_m \int_a^x \frac{f(t)W_m^\alpha(t)}{W^\alpha(t)t^{1-\alpha}} dt, \quad (3.7)$$

where a is an arbitrary positive constant.

4. Examples

Example 4.1. We first solve the following fractional differential equation

$$D^{1/2} (D^{1/2}y) = \ln x, \quad x > 0. \quad (4.1)$$

One can easily show that $y_1 = 1$ and $y_2 = \sqrt{x}$ are two linearly independent solutions of the corresponding homogeneous equation

$$D^{1/2} (D^{1/2}y) = 0. \quad (4.2)$$

Let us find the particular solution $y_p(x)$ of equation (4.1) using the method of variation of parameters, precisely, we want to apply the formula

$$\begin{aligned} y_p(x) &= -y_1 \int \frac{y_2 f(x)}{W^\alpha[y_1, y_2]x^{1-\alpha}} dx + y_2 \int \frac{y_1 f(x)}{W^\alpha[y_1, y_2]x^{1-\alpha}} dx \\ &= -y_1 \int \frac{y_2 f(x)}{W[y_1, y_2]x^{2-2\alpha}} dx + y_2 \int \frac{y_1 f(x)}{W[y_1, y_2]x^{2-2\alpha}} dx. \end{aligned}$$

Since $y_1 = 1$, $y_2 = \sqrt{x}$, $f(x) = \ln x$ and $W[y_1, y_2] = \frac{1}{2\sqrt{x}}$, we obtain

$$\begin{aligned} y_p(x) &= - \int \frac{\sqrt{x} \ln x}{\frac{1}{2\sqrt{x}} x} dx + \sqrt{x} \int \frac{\ln x}{\frac{1}{2\sqrt{x}} x} dx \\ &= -2 \int \ln x dx + 2\sqrt{x} \int \frac{\ln x}{\sqrt{x}} dx \\ &= 2x \ln x - 6x. \end{aligned}$$

Thus, the general solution $y(x)$ can be written as

$$y(x) = c_1 + c_2\sqrt{x} + 2x \ln x - 6x.$$

Example 4.2. Consider the following fractional differential equation

$$xD^{1/2} (D^{1/2}y) - \frac{1}{2}y = x^{3/2} + x, \quad x > 0. \quad (4.3)$$

One can easily show that $y_1 = x$ and $y_2 = x^{-1/2}$ are two linearly independent solutions of the corresponding homogeneous equation

$$xD^{1/2} (D^{1/2}y) - \frac{1}{2}y = 0. \quad (4.4)$$

Let us find the particular solution $y_p(x)$ of equation (4.3) using the formula

$$y_p(x) = -y_1 \int \frac{y_2 f(x)}{W[y_1, y_2]x^{2-2\alpha}} dx + y_2 \int \frac{y_1 f(x)}{W[y_1, y_2]x^{2-2\alpha}} dx.$$

Substitute $y_1 = x$, $y_2 = x^{-1/2}$, $f(x) = x^{1/2} + 1$ and $W[y_1, y_2] = -\frac{3}{2}x^{-1/2}$ in the above equation, we get

$$\begin{aligned} y_p(x) &= -x \int \frac{x^{-1/2}(x^{1/2} + 1)}{-\frac{3}{2}x^{-1/2} x} dx + x^{-1/2} \int \frac{x(x^{1/2} + 1)}{-\frac{3}{2}x^{-1/2} x} dx \\ &= x^{3/2} + \frac{2}{3} x \ln x - \frac{4}{9} x. \end{aligned}$$

Thus the general solution of equation (4.3) can be written as

$$y(x) = c_1x + c_2x^{-1/2} + x^{3/2} + \frac{2}{3} x \ln x - \frac{4}{9} x.$$

Example 4.3. Let us solve the following fractional differential equation

$$D^{1/2} (D^{1/2} (D^{1/2}y)) = x^{5/2}. \quad (4.5)$$

One can verify that $y_1 = 1$, $y_2 = x$ and $y_3 = x^{1/2}$ are linearly independent solutions of the homogeneous equation

$$D^{1/2} (D^{1/2} (D^{1/2}y)) = 0.$$

By simple calculations, we can obtain

$$W^{1/2} = -\frac{1}{4}, \quad W_1^{1/2} = -\frac{1}{2}x, \quad W_2^{1/2} = -\frac{1}{2} \quad \text{and} \quad W_3^{1/2} = x^{1/2}.$$

Now, see (3.7),

$$\begin{aligned} y_p(x) &= y_1 \int \frac{W_1^{1/2} f(x)}{W^{1/2} x^{1/2}} dx + y_2 \int \frac{W_2^{1/2} f(x)}{W^{1/2} x^{1/2}} dx + y_3 \int \frac{W_3^{1/2} f(x)}{W^{1/2} x^{1/2}} dx \\ &= \int \frac{-\frac{1}{2}x^{5/2}}{-\frac{1}{4}x^{1/2}} dx + x \int \frac{-\frac{1}{2}x^{5/2}}{-\frac{1}{4}x^{1/2}} dx + x^{1/2} \int \frac{x^{1/2}x^{5/2}}{-\frac{1}{4}x^{1/2}} dx \\ &= 2 \int x^3 dx + 2x \int x^2 dx - 4x^{1/2} \int x^{5/2} dx \\ &= \frac{1}{42}x^4. \end{aligned}$$

Thus the general solution of equation (4.5) is given by

$$y(x) = c_1 + c_2x + c_3x^{1/2} + \frac{1}{42}x^4.$$

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