# Strong convergence theorems for a nonexpansive mapping and its applications for solving the split feasibility problem 

Qinwei Fan ${ }^{\text {a,* }}$, Zhangsong Yao ${ }^{\text {b,* }}$<br>${ }^{a}$ School of Science, Xi'an Polytechnic University, Xi'an 710048, P. R. China.<br>${ }^{\text {b }}$ School of Information Engineering, Nanjing Xiaozhuang University, Nanjing 211171, P. R. China.

Communicated by Y. H. Yao


#### Abstract

The aim of this paper is to propose some novel algorithms and their strong convergence theorems for solving the split feasibility problem, and we obtain the corresponding strong convergence results under mild conditions. The split feasibility problem was proposed by [Y. Censor, Y. Elfving, Numer. Algorithms, 8 (1994), 221-239]. So far a lot of algorithms have been given for solving this problem due to its applications in intensity-modulated radiation therapy, signal processing, and image reconstruction. But most of these algorithms are of weak convergence. In this paper, we propose the new algorithms which can provide useful guidelines for solving the relevant problem, such as the split common fixed point problem (SCFP), multi-set split feasibility problem and so on. (c)2017 All rights reserved.


Keywords: Split feasibility problem, strong convergence, nonexpansive mapping, Hilbert space. 2010 MSC: 47J25, 47H45.

## 1. Introduction and preliminaries

The split feasibility problem (SFP) was first introduced by Censor and Elfving [5] in 1994. The SFP is to find a point

$$
\begin{equation*}
x \in C \text { such that } A x \in Q \text {, } \tag{1.1}
\end{equation*}
$$

where $C$ is a nonempty closed convex subset of a Hilbert space $H_{1}, Q$ is a nonempty closed convex subset of a Hilbert space $\mathrm{H}_{2}$, and $A: \mathrm{H}_{1} \rightarrow \mathrm{H}_{2}$ is a bounded linear operator.

As we know, the SFP has received so much attention due to its applications in intensity-modulated radiation therapy, signal processing, and image reconstruction, see Byrne [1, 2], Censor [4-6], Ceng [3], Fan et al. [7], Xu [20, 21], Kraikaew and Saejung [9], Moudafi [10], Qu et al. [12-14], Qin and Yao [11], Yang et al. [16, 22, 27, 28], Yao et al. [23-26], and so on.

To solve the SFP (1.1), many algorithms have been constructed.
In 2002, the so-called CQ algorithm was proposed by Byrne [1, 2] in the following:

$$
x_{n+1}=P_{C}\left(x_{n}-\gamma A^{*}\left(I-P_{Q}\right) A x_{n}\right), \quad n \geqslant 0
$$

[^0]where $0<\gamma<2 / \rho$ with $\rho$ being the spectral radius of the operator $A^{*} A$ and $P_{C}, P_{Q}$ denotes the orthogonal projection onto the sets $\mathrm{C}, \mathrm{Q}$, respectively. However, the stepsize of the CQ algorithm is fixed and related to spectral radius of the operator $A^{*} A$, and the orthogonal projection onto the sets $C$ and $Q$ is not easily calculated usually.

In 2004, Yang [22] constructed a relaxed CQ algorithm for solving a special case of the SFP, in which he replaced them by projections onto halfspaces $C_{k}$ and $Q_{k}$. In 2005, Qu and Xiu [13] modified Yang's relaxed CQ algorithm and the CQ algorithm by adopting the Armijo-like searches to get the stepsize.

In 2008, Qu and Xiu [14] proposed a halfspace relaxation projection method for the SFP, based on a reformulation of the SFP.

Recently, Xu [21] applied Mann's algorithm to the SFP and proposed an averaged CQ algorithm which was proved to be weakly converge to a solution of the SFP. Very recently, Qu et al. [12] studied the computation of the step-size for the CQ-like algorithms for the split feasibility problem.

In this paper, based on such research results, we propose some novel algorithms for the nonexpansive mapping and construct their strong convergence theorems, and we apply these convergence theorems for solving the split feasibility problem.

We use $\rightarrow$ to denote strong convergence and $\rightharpoonup$ for weak convergence, and we use Fix $(T)$ to denote the fixed point set of the operator T. Some concepts and lemmas will be useful in proving our main results as follows:

Let H be a Hilbert space endowed with the inner product $\langle\cdot, \cdot\rangle$ and norm $\|\cdot\|$. Then the following inequality holds

$$
\begin{equation*}
\|x+y\|^{2} \leqslant\|x\|^{2}+2\langle y, x+y\rangle, \quad \forall x, y \in H . \tag{1.2}
\end{equation*}
$$

Definition 1.1. An operator $\mathrm{T}: \mathrm{H} \rightarrow \mathrm{H}$ is said to be
(i) nonexpansive if

$$
\|\mathrm{T} x-\mathrm{T} y\| \leqslant\|x-z\|, \quad \forall x \in \mathrm{H} .
$$

(ii) $v$-inverse strongly monotone ( $v$-ism), with $v>0$, if

$$
\langle x-y, T x-T y\rangle \geqslant v\|T x-T y\|^{2}, \quad \forall x, y \in H .
$$

Definition 1.2. Let C be a nonempty closed convex subset of a Hilbert space H, the metric (nearest point) projection $P_{C}$ from $H$ to $C$ is defined as follows: given $x \in H, P_{C} x$ is the only point in $C$ with the property

$$
\left\|x-P_{C} x\right\|=\inf \{\|x-y\|: y \in C\}
$$

Lemma 1.3 ([19]). Let H be a Hilbert space, C a closed convex subset of H , and $\mathrm{T}: \mathrm{C} \rightarrow \mathrm{C}$ a nonexpansive mapping with $\operatorname{Fix}(\mathrm{T}) \neq \emptyset$. If $\left\{\mathrm{x}_{\mathrm{n}}\right\}$ is a sequence in C weakly converging to x and if $\left\{(\mathrm{I}-\mathrm{T}) \mathrm{x}_{\mathrm{n}}\right\}$ converges strongly to y , then $(\mathrm{I}-\mathrm{T}) \mathrm{x}=\mathrm{y}$.
Lemma 1.4 ([15]). Let C be a nonempty closed convex subset of a Hilbert space $\mathrm{H}, \mathrm{P}_{\mathrm{C}}$ is a nonexpansive mapping from H onto C and is characterized as: given $\mathrm{x} \in \mathrm{H}$, there hold the inequality

$$
\left\langle x-P_{C} x, y-P_{C} x\right\rangle \leqslant 0, \quad \forall y \in C .
$$

Lemma 1.5 ( $[17,18])$. Let $\left\{a_{n}\right\}_{n=0}^{\infty}$ be a sequence of nonnegative real numbers satisfying the property

$$
a_{n+1} \leqslant\left(1-\gamma_{n}\right) a_{n}+\gamma_{n} \sigma_{n}, \quad n \geqslant 0,
$$

where $\left\{\gamma_{n}\right\}_{n=0}^{\infty} \subset(0,1)$ and $\left\{\sigma_{n}\right\}_{n=0}^{\infty}$ are such that
(i) $\lim _{n \rightarrow \infty} \gamma_{n}=0$ and $\sum_{n=0}^{\infty} \gamma_{n}=\infty$,
(ii) either $\limsup _{n \rightarrow \infty} \sigma_{n} \leqslant 0$ or $\sum_{n=0}^{\infty}\left|\gamma_{n} \sigma_{n}\right|<\infty$.

Then $\left\{a_{n}\right\}_{n=0}^{\infty}$ converges to zero.

## 2. Main results

Theorem 2.1. Let $C$ be a nonempty closed and convex subset of a real Hilbert space $H_{1}$ and $\theta \in C$, let $T: C \rightarrow C$ be a nonexpansive mapping such that $\operatorname{Fix}(T) \neq \emptyset$. Given $\left\{\alpha_{n}\right\}_{n=1}^{\infty},\left\{\beta_{n}\right\}_{n=1}^{\infty}$, and $\left\{\lambda_{n}\right\}_{n=1}^{\infty}$ in $(0,1)$, the following conditions are satisfied:
(i) $\lim _{n \rightarrow \infty} \alpha_{n}=1, \lim _{n \rightarrow \infty} \beta_{n}=1, \lim _{n \rightarrow \infty} \lambda_{n}=1$;
(ii) $\left|\lambda_{n}-\beta_{n-1} \lambda_{n-1}\right|+\beta_{n} \leqslant 1, \sum_{n=0}^{\infty}\left(1-\beta_{n}\right)\left(1-\lambda_{n}\right)=\infty$;
(iii) $\sum_{n=0}^{\infty}\left|\alpha_{n+1}-\alpha_{n}\right|<\infty, \sum_{n=0}^{\infty}\left|\beta_{n+1}-\beta_{n}\right|<\infty, \sum_{n=0}^{\infty}\left|\lambda_{n+1}-\lambda_{n}\right|<\infty$.

Let $\left\{x_{n}\right\}$ be generated by $x_{1} \in C$ and

$$
\left\{\begin{array}{l}
x_{n+1}=\left(1-\beta_{n}\right)\left(\lambda_{n} x_{n}\right)+\beta_{n} y_{n}  \tag{2.1}\\
y_{n}=\left(1-\alpha_{n}\right) x_{n}+\alpha_{n} T x_{n} .
\end{array}\right.
$$

Then the sequence $\left\{x_{n}\right\}$ converges strongly to a fixed point $\hat{x}$ of $T$, where $\hat{x}$ is the minimum-norm element of $\operatorname{Fix}(T)$.
Proof. First, we show the sequence $\left\{x_{n}\right\}$ is bounded. Indeed, taking a fixed point $x^{*}$ of $T$, we have

$$
\left\|y_{n}-x^{*}\right\| \leqslant\left(1-\alpha_{n}\right)\left\|x_{n}-x^{*}\right\|+\alpha_{n}\left\|T x_{n}-x^{*}\right\| \leqslant\left\|x_{n}-x^{*}\right\|
$$

so

$$
\begin{aligned}
\left\|x_{n+1}-x^{*}\right\| & =\left\|\left(1-\beta_{n}\right)\left(\lambda_{n} x_{n}\right)+\beta_{n} y_{n}-x^{*}\right\| \\
& =\left\|\left(1-\beta_{n}\right)\left(\lambda_{n} x_{n}-x^{*}\right)+\beta_{n}\left(y_{n}-x^{*}\right)\right\| \\
& =\left\|\left(1-\beta_{n}\right) \lambda_{n}\left(x_{n}-x^{*}\right)+\beta_{n}\left(y_{n}-x^{*}\right)-\left(1-\beta_{n}\right)\left(1-\lambda_{n}\right) x^{*}\right\| \\
& \leqslant\left(1-\beta_{n}\right) \lambda_{n}\left\|x_{n}-x^{*}\right\|+\beta_{n}\left\|y_{n}-x^{*}\right\|+\left(1-\beta_{n}\right)\left(1-\lambda_{n}\right)\left\|x^{*}\right\| \\
& \leqslant\left[1-\left(1-\beta_{n}\right)\left(1-\lambda_{n}\right)\right]\left\|x_{n}-x^{*}\right\|+\left(1-\beta_{n}\right)\left(1-\lambda_{n}\right)\left\|x^{*}\right\| \\
& \leqslant \max \left\{\left\|x_{n}-x^{*}\right\|,\left\|x^{*}\right\|\right\} \\
& \vdots \\
& \leqslant \max \left\{\left\|x_{1}-x^{*}\right\|,\left\|x^{*}\right\|\right\} .
\end{aligned}
$$

Therefore, $\left\{x_{n}\right\}$ is bounded, so are $\left\{y_{n}\right\}$ and $\left\{T x_{n}\right\}$.
Second, we show $\left\|x_{n}-T x_{n}\right\| \rightarrow 0$, as $n \rightarrow \infty$.
By condition (i) and the boundedness of $\left\{x_{n}\right\}$ and $\left\{y_{n}\right\}$, we have

$$
\begin{equation*}
\left\|x_{n+1}-y_{n}\right\|=\left(1-\beta_{n}\right)\left\|\lambda_{n} x_{n}-y_{n}\right\| \rightarrow 0 \tag{2.2}
\end{equation*}
$$

and

$$
\begin{equation*}
\left\|y_{n}-T x_{n}\right\|=\left(1-\alpha_{n}\right)\left\|x_{n}-T x_{n}\right\| \rightarrow 0 \tag{2.3}
\end{equation*}
$$

So, it suffices to show that

$$
\left\|x_{n+1}-x_{n}\right\| \rightarrow 0
$$

Calculating $y_{n}-y_{n-1}$, after some manipulations we obtain

$$
\begin{aligned}
y_{n}-y_{n-1} & =\left(1-\alpha_{n}\right) x_{n}+\alpha_{n} T x_{n}-\left(1-\alpha_{n-1}\right) x_{n-1}-\alpha_{n-1} T x_{n-1} \\
& =x_{n}-x_{n-1}-\alpha_{n} x_{n}+\alpha_{n-1} x_{n-1}+\alpha_{n} T x_{n}-\alpha_{n-1} T x_{n-1} \\
& =x_{n}-x_{n-1}-\alpha_{n} x_{n}+\alpha_{n} x_{n-1}-\alpha_{n} x_{n-1}+\alpha_{n-1} x_{n-1}+\alpha_{n} T x_{n}-\alpha_{n-1} T x_{n-1} \\
& =x_{n}-x_{n-1}-\alpha_{n}\left(x_{n}-x_{n-1}\right)-\left(\alpha_{n}-\alpha_{n-1}\right) x_{n-1}+\alpha_{n} T x_{n}-\alpha_{n-1} T x_{n-1} \\
& =\left(1-\alpha_{n}\right)\left(x_{n}-x_{n-1}\right)-\left(\alpha_{n}-\alpha_{n-1}\right) x_{n-1}+\alpha_{n} T x_{n}-\alpha_{n} T x_{n-1}+\alpha_{n} T x_{n-1}-\alpha_{n-1} T x_{n-1} \\
& =\left(1-\alpha_{n}\right)\left(x_{n}-x_{n-1}\right)-\left(\alpha_{n}-\alpha_{n-1}\right) x_{n-1}+\alpha_{n}\left(T x_{n}-T x_{n-1}\right)+\left(\alpha_{n}-\alpha_{n-1}\right) T x_{n-1} \\
& =\left(1-\alpha_{n}\right)\left(x_{n}-x_{n-1}\right)-\left(\alpha_{n}-\alpha_{n-1}\right)\left(x_{n-1}-T x_{n-1}\right)+\alpha_{n}\left(T x_{n}-T x_{n-1}\right) .
\end{aligned}
$$

It follows that

$$
\begin{align*}
\left\|y_{n}-y_{n-1}\right\| & \leqslant\left(1-\alpha_{n}\right)\left\|x_{n}-x_{n-1}\right\|+\left|\alpha_{n}-\alpha_{n-1}\right|\left\|x_{n-1}-T x_{n-1}\right\|+\alpha_{n}\left\|T x_{n}-T x_{n-1}\right\| \\
& \leqslant\left\|x_{n}-x_{n-1}\right\|+\left|\alpha_{n}-\alpha_{n-1}\right|\left\|x_{n-1}-T x_{n-1}\right\| . \tag{2.4}
\end{align*}
$$

Calculating $x_{n+1}-x_{n}$, after some manipulations we obtain

$$
\begin{align*}
x_{n+1}-x_{n}= & \left(1-\beta_{n}\right)\left(\lambda_{n} x_{n}\right)+\beta_{n} y_{n}-\left(1-\beta_{n-1}\right)\left(\lambda_{n-1} x_{n-1}\right)-\beta_{n-1} y_{n-1} \\
= & \lambda_{n} x_{n}-\beta_{n} \lambda_{n} x_{n}+\beta_{n} y_{n}-\lambda_{n-1} x_{n-1}+\beta_{n-1} \lambda_{n-1} x_{n-1}-\beta_{n-1} y_{n-1} \\
= & \lambda_{n} x_{n}-\lambda_{n} x_{n-1}+\lambda_{n} x_{n-1}-\lambda_{n-1} x_{n-1}-\beta_{n} \lambda_{n} x_{n} \\
& +\beta_{n-1} \lambda_{n-1} x_{n}-\beta_{n-1} \lambda_{n-1} x_{n}+\beta_{n-1} \lambda_{n-1} x_{n-1} \\
& +\beta_{n} y_{n}-\beta_{n} y_{n-1}+\beta_{n} y_{n-1}-\beta_{n-1} y_{n-1}  \tag{2.5}\\
= & \lambda_{n}\left(x_{n}-x_{n-1}\right)+\left(\lambda_{n}-\lambda_{n-1}\right) x_{n-1}-\left(\beta_{n} \lambda_{n}-\beta_{n-1} \lambda_{n-1}\right) x_{n} \\
& -\beta_{n-1} \lambda_{n-1}\left(x_{n}-x_{n-1}\right)+\beta_{n}\left(y_{n}-y_{n-1}\right)+\left(\beta_{n}-\beta_{n-1}\right) y_{n-1} \\
= & \left(\lambda_{n}-\beta_{n-1} \lambda_{n-1}\right)\left(x_{n}-x_{n-1}\right)+\left(\lambda_{n}-\lambda_{n-1}\right) x_{n-1} \\
& -\left(\beta_{n} \lambda_{n}-\beta_{n-1} \lambda_{n-1}\right) x_{n}+\beta_{n}\left(y_{n}-y_{n-1}\right)+\left(\beta_{n}-\beta_{n-1}\right) y_{n-1},
\end{align*}
$$

Then it follows from (2.5) and (2.4) that

$$
\begin{align*}
\left\|x_{n+1}-x_{n}\right\| \leqslant & \left|\lambda_{n}-\beta_{n-1} \lambda_{n-1}\right|\left|\left|x_{n}-x_{n-1}\left\|+\left|\lambda_{n}-\lambda_{n-1}\right|\right\| x_{n-1} \|\right.\right. \\
& +\left|\beta_{n} \lambda_{n}-\beta_{n-1} \lambda_{n-1}\right|\left\|x_{n}\right\|+\beta_{n}\left\|y_{n}-y_{n-1}\right\|+\left|\beta_{n}-\beta_{n-1}\right|\left\|y_{n-1}\right\| \\
\leqslant & \left|\lambda_{n}-\beta_{n-1} \lambda_{n-1}\right|\left|\left|x_{n}-x_{n-1}\left\|+\left|\lambda_{n}-\lambda_{n-1}\right|| | x_{n-1}\right\|+\left|\beta_{n} \lambda_{n}-\beta_{n-1} \lambda_{n-1}\right|\left\|x_{n}\right\|\right.\right. \\
& +\beta_{n}\left(\left\|x_{n}-x_{n-1}\right\|+\left|\alpha_{n}-\alpha_{n-1}\right|\left\|x_{n-1}-T x_{n-1}\right\|\right)+\left|\beta_{n}-\beta_{n-1}\right|\left\|y_{n-1}\right\| \\
\leqslant & \left(\beta_{n}+\left|\lambda_{n}-\beta_{n-1} \lambda_{n-1}\right|\right)\left\|x_{n}-x_{n-1}\right\| \\
& +M\left(\left|\lambda_{n}-\lambda_{n-1}\right|+\left|\beta_{n} \lambda_{n}-\beta_{n-1} \lambda_{n-1}\right|+\left|\alpha_{n}-\alpha_{n-1}\right|+\left|\beta_{n}-\beta_{n-1}\right|\right)  \tag{2.6}\\
\leqslant & {\left[1-\left(1-\beta_{n}-\left|\lambda_{n}-\beta_{n-1} \lambda_{n-1}\right|\right)\right]\left\|x_{n}-x_{n-1}\right\| } \\
& +M\left(\left|\lambda_{n}-\lambda_{n-1}\right|+\left|\beta_{n} \lambda_{n}-\beta_{n-1} \lambda_{n-1}\right|+\left|\alpha_{n}-\alpha_{n-1}\right|+\left|\beta_{n}-\beta_{n-1}\right|\right) \\
\leqslant & \left(1-\sigma_{n}\right)\left\|x_{n}-x_{n-1}\right\|+M\left(\left|\lambda_{n}-\lambda_{n-1}\right|+\left|\beta_{n} \lambda_{n}-\beta_{n-1} \lambda_{n-1}\right|\right. \\
& \left.+\left|\alpha_{n}-\alpha_{n-1}\right|+\left|\beta_{n}-\beta_{n-1}\right|\right) \\
\leqslant & \left(1-\sigma_{n}\right)\left\|x_{n}-x_{n-1}\right\|+M\left(2\left|\lambda_{n}-\lambda_{n-1}\right|+\left|\alpha_{n}-\alpha_{n-1}\right|+2\left|\beta_{n}-\beta_{n-1}\right|\right),
\end{align*}
$$

where $\sigma_{n}=1-\beta_{n}-\left|\lambda_{n}-\beta_{n-1} \lambda_{n-1}\right|$ and $M>0$ is a constant such that $M \geqslant \max \left\{\left\|x_{n-1}\right\|, \| x_{n-1}-\right.$ $\left.T x_{n-1}\|,\| y_{n-1} \|\right\}$ for all $n$. By the assumption (i)-(iii), we have $\lim _{n \rightarrow \infty} \sigma_{n}=0, \sum_{n=1}^{\infty} \sigma_{n}=\infty$, and $\sum_{n=1}^{\infty} 2\left|\lambda_{n}-\lambda_{n-1}\right|+\left|\alpha_{n}-\alpha_{n-1}\right|+2\left|\beta_{n}-\beta_{n-1}\right|<\infty$. Hence, applying Lemma 1.5 to (2.6), we obtain

$$
\begin{equation*}
\left\|x_{n+1}-x_{n}\right\| \rightarrow 0 . \tag{2.7}
\end{equation*}
$$

By (2.2), (2.3), and (2.7), we get

$$
\begin{equation*}
\left\|x_{n}-T x_{n}\right\| \leqslant\left\|x_{n}-x_{n+1}\right\|+\left\|x_{n+1}-y_{n}\right\|+\left\|y_{n}-T x_{n}\right\| \rightarrow 0, \tag{2.8}
\end{equation*}
$$

as $n \rightarrow \infty$.
Since $\left\{x_{n}\right\}$ is bounded, there exists a subsequence $x_{n_{j}}$ of $\left\{x_{n}\right\}$ such that $x_{n_{j}} \rightharpoonup \hat{x} \in H_{1}$. By (2.8) and the demiclosedness principle of $T-I$ at zero in Lemma 1.3, we have that $z \in F(T)$.

At last, we prove $\left\{x_{n}\right\}$ converges strongly to $\hat{x}$. Setting $w_{n}=\left(1-\beta_{n}\right) x_{n}+\beta_{n} y_{n}, n \geqslant 1$, then from (2.1) we have

$$
x_{n+1}=w_{n}-\left(1-\beta_{n}\right)\left(1-\lambda_{n}\right) x_{n} .
$$

By the boundedness of $\left\{x_{n}\right\}$, we have,

$$
\begin{equation*}
\left\|x_{n+1}-w_{n}\right\|=\left(1-\beta_{n}\right)\left(1-\lambda_{n}\right)\left\|x_{n}\right\| \rightarrow 0 . \tag{2.9}
\end{equation*}
$$

Using the fact $x_{n_{j}} \rightharpoonup z$ and (2.9), we conclude that $w_{n_{j}} \rightharpoonup z$. It follows that

$$
\begin{align*}
x_{n+1} & =\left[1-\left(1-\beta_{n}\right)\left(1-\lambda_{n}\right)\right] w_{n}-\left(1-\beta_{n}\right)\left(1-\lambda_{n}\right)\left(x_{n}-w_{n}\right) \\
& =\left[1-\left(1-\beta_{n}\right)\left(1-\lambda_{n}\right)\right] w_{n}-\left(1-\beta_{n}\right)\left(1-\lambda_{n}\right) \beta_{n}\left(x_{n}-y_{n}\right) \tag{2.10}
\end{align*}
$$

Also we have

$$
\begin{equation*}
\left\|w_{n}-\hat{x}\right\|^{2}=\left\|x_{n}-\hat{x}-\beta_{n}\left(x_{n}-y_{n}\right)\right\|^{2} \leqslant\left\|x_{n}-\hat{x}\right\|^{2}-2 \beta_{n}\left\langle x_{n}-y_{n}, w_{n}-\hat{x}\right\rangle \tag{2.11}
\end{equation*}
$$

By (2.10), (2.11), and (1.2), we obtain

$$
\begin{align*}
\left\|x_{n+1}-\hat{x}\right\|^{2}= & \|\left[1-\left(1-\beta_{n}\right)\left(1-\lambda_{n}\right)\right]\left(w_{n}-\hat{x}\right) \\
& -\left(1-\beta_{n}\right)\left(1-\lambda_{n}\right) \beta_{n}\left(x_{n}-y_{n}\right)-\left(1-\beta_{n}\right)\left(1-\lambda_{n}\right) \hat{x} \|^{2} \\
\leqslant & {\left[1-\left(1-\beta_{n}\right)\left(1-\lambda_{n}\right)\right]^{2}\left\|w_{n}-\hat{x}\right\|^{2}-2\left(1-\beta_{n}\right)\left(1-\lambda_{n}\right)\left\langle\beta_{n}\left(x_{n}-y_{n}\right)+\hat{x}, x_{n+1}-\hat{x}\right\rangle } \\
= & {\left[1-\left(1-\beta_{n}\right)\left(1-\lambda_{n}\right)\right]^{2}\left\|w_{n}-\hat{x}\right\|^{2}-2\left(1-\beta_{n}\right)\left(1-\lambda_{n}\right) \beta_{n}\left\langle\left(x_{n}-y_{n}\right), x_{n+1}-\hat{x}\right\rangle } \\
& -2\left(1-\beta_{n}\right)\left(1-\lambda_{n}\right)\left\langle\hat{x}, x_{n+1}-\hat{x}\right\rangle \\
\leqslant & {\left[1-\left(1-\beta_{n}\right)\left(1-\lambda_{n}\right)\right]\left(\left\|x_{n}-\hat{x}\right\|^{2}-2 \beta_{n}\left\langle x_{n}-y_{n}, w_{n}-\hat{x}\right\rangle\right) }  \tag{2.12}\\
& -2\left(1-\beta_{n}\right)\left(1-\lambda_{n}\right) \beta_{n}\left\langle\left(x_{n}-y_{n}\right), x_{n+1}-\hat{x}\right\rangle-2\left(1-\beta_{n}\right)\left(1-\lambda_{n}\right)\left\langle\hat{x}, x_{n+1}-\hat{x}\right\rangle \\
= & {\left[1-\left(1-\beta_{n}\right)\left(1-\lambda_{n}\right)\right]\left\|x_{n}-\hat{x}\right\|^{2}-2\left(1-\beta_{n}\right)\left(1-\lambda_{n}\right) \beta_{n}\left\langle x_{n}-y_{n}, w_{n}-\hat{x}\right\rangle } \\
& -2\left(1-\beta_{n}\right)\left(1-\lambda_{n}\right) \beta_{n}\left\langle\left(x_{n}-y_{n}\right), x_{n+1}-\hat{x}\right\rangle-2\left(1-\beta_{n}\right)\left(1-\lambda_{n}\right)\left\langle\hat{x}, x_{n+1}-\hat{x}\right\rangle \\
= & \left(1-\gamma_{n}\right)\left\|x_{n}-\hat{x}\right\|^{2}+\gamma_{n}\left(-2 \beta_{n}\left\langle x_{n}-y_{n}, w_{n}-\hat{x}\right\rangle\right. \\
& \left.-2 \beta_{n}\left\langle\left(x_{n}-y_{n}\right), x_{n+1}-\hat{x}\right\rangle-2\left\langle\hat{x}, x_{n+1}-\hat{x}\right\rangle\right),
\end{align*}
$$

where $\gamma_{n}=\left(1-\beta_{n}\right)\left(1-\lambda_{n}\right)$.
By conditions (i) and (ii), we have that $\lim _{n \rightarrow \infty} \gamma_{n}=0, \sum_{n=1}^{\infty} \gamma_{n}=\infty$. Clearly,

$$
\begin{aligned}
& \limsup _{n \rightarrow \infty}-2 \beta_{n}\left\langle x_{n}-y_{n}, w_{n}-\hat{x}\right\rangle=0 \\
& \limsup _{n \rightarrow \infty}-2 \beta_{n}\left\langle\left(x_{n}-y_{n}\right), x_{n+1}-\hat{x}\right\rangle=0
\end{aligned}
$$

and

$$
\limsup _{n \rightarrow \infty}-2\left\langle\hat{x}, x_{n+1}-\hat{x}\right\rangle=\lim _{j \rightarrow \infty}-2\left\langle\hat{x}, x_{n_{j}}-\hat{x}\right\rangle=-2\langle\hat{x}, z-\hat{x}\rangle \leqslant 0
$$

Hence, applying Lemma 1.5 to (2.12), we obtain that $\left\|x_{n}-\hat{x}\right\| \rightarrow 0$.
The proof is completed.

## 3. Applications

Lemma 3.1 ([21]). Given $x^{*} \in \mathrm{H}$, then $x^{*}$ solves the SFP (1.1) if and only if $x^{*}$ is the solution of the fixed point equation $x=P_{C}\left(I-\gamma A^{*}\left(I-P_{Q}\right) A\right) x$.

Proposition 3.2. Let C be a nonempty closed convex subset of a Hilbert space $\mathrm{H}_{1}, \mathrm{Q}$ be a nonempty closed convex subset of a Hilbert space $\mathrm{H}_{2}$, and $\mathrm{A}: \mathrm{H}_{1} \rightarrow \mathrm{H}_{2}$ is a bounded linear operator. Let $\mathrm{P}_{\mathrm{C}}, \mathrm{P}_{\mathrm{Q}}$ denote the orthogonal projections onto the sets $C, Q$, respectively. Let $0<\gamma<\frac{2}{\rho}$, $\rho$ is the spectral radius of $A^{*} A$, and $A^{*}$ is the adjoint of $A$. Then the operator $T \triangleq \mathrm{P}_{\mathrm{C}}\left(\mathrm{I}-\gamma \mathrm{A}^{*}\left(\mathrm{I}-\mathrm{P}_{\mathrm{Q}}\right) \mathrm{A}\right)$ is nonexpansive on C .

Proof. This proof is divided into 4 steps in the following.

Step 1. We show that $\mathrm{P}_{\mathrm{Q}}$ is 1-ism.

$$
\left\langle x-y, P_{Q^{x}}-P_{Q} y\right\rangle-\left\|P_{Q^{x}}-P_{Q} y\right\|^{2}=\left\langle x-P_{Q^{x}}, P_{Q^{x}}-P_{Q} y\right\rangle+\left\langle y-P_{Q} y, P_{Q} y-P_{Q^{x}}\right\rangle \geqslant 0 .
$$

Step 2. We show that $\mathrm{I}-\mathrm{P}_{\mathrm{Q}}$ is 1 -ism.

$$
\begin{aligned}
& \left\langle x-y,\left(I-P_{Q}\right) x-\left(I-P_{Q}\right) y\right\rangle-\left\|\left(I-P_{Q}\right) x-\left(I-P_{Q}\right) y\right\|^{2} \\
& \quad=\|x-y\|^{2}-\left\langle x-y, P_{Q} x-P_{Q} y\right\rangle-\|x-y\|^{2}-\left\|\mathrm{P}_{\mathrm{Q}} x-\mathrm{P}_{\mathrm{Q}} y\right\|^{2}+2\left\langle x-Y, \mathrm{P}_{\mathrm{Q}} x-\mathrm{P}_{\mathrm{Q}} y\right\rangle \\
& \quad=\left\langle x-Y, \mathrm{P}_{\mathrm{Q}} x-\mathrm{P}_{\mathrm{Q}} y\right\rangle-\left\|\mathrm{P}_{\mathrm{Q}} x-\mathrm{P}_{\mathrm{Q}} y\right\|^{2} \geqslant 0 .
\end{aligned}
$$

Step 3. We show $U \triangleq A^{*}\left(I-P_{Q}\right) A$ is $\frac{1}{\rho}$-ism.
Since $\mathrm{I}-\mathrm{P}_{\mathrm{Q}}$ is 1-ism and from the property of adjoint operator, we get

$$
\begin{aligned}
\langle x-y, \mathrm{U} x-\mathrm{U} y\rangle & =\left\langle x-y, A^{*}\left(\mathrm{I}-\mathrm{P}_{\mathrm{Q}}\right) A x-A^{*}\left(\mathrm{I}-\mathrm{P}_{\mathrm{Q}}\right) A y\right\rangle \\
& =\left\langle A x-A y,\left(\mathrm{I}-\mathrm{P}_{\mathrm{Q}}\right) A x-\left(\mathrm{I}-\mathrm{P}_{\mathrm{Q}}\right) A y\right\rangle \\
& \geqslant\left\|\left(\mathrm{I}-\mathrm{P}_{\mathrm{Q}}\right) A x-\left(\mathrm{I}-\mathrm{P}_{\mathrm{Q}}\right) A y\right\|^{2} \\
& =\frac{\left\|A^{*}\right\|^{2}}{\|A\|^{2}}\left\|\left(\mathrm{I}-\mathrm{P}_{\mathrm{Q}}\right) A x-\left(\mathrm{I}-\mathrm{P}_{\mathrm{Q}}\right) A y\right\|^{2} \\
& \geqslant \frac{1}{\rho}\left\|A^{*}\left(\mathrm{I}-\mathrm{P}_{\mathrm{Q}}\right) A x-A^{*}\left(\mathrm{I}-\mathrm{P}_{\mathrm{Q}}\right) A y\right\|^{2}=\frac{1}{\rho}\|\mathrm{U} x-\mathrm{U} y\|^{2} .
\end{aligned}
$$

It follows from the above inequality that $\gamma \mathrm{U}$ is $\frac{1}{\gamma \rho}$-ism.
Step 4. We show $\mathrm{V} \triangleq \mathrm{I}-\gamma \mathrm{U}$ is nonexpansive. By $0<\gamma<\frac{2}{\rho}$, we obtain

$$
\begin{aligned}
\|\mathrm{V} x-\mathrm{V} y\|^{2} & =\langle(\mathrm{I}-\gamma \mathrm{U}) \mathrm{x}-(\mathrm{I}-\gamma \mathrm{U}) \mathrm{y},(\mathrm{I}-\gamma \mathrm{U}) \mathrm{x}-(\mathrm{I}-\gamma \mathrm{U}) \mathrm{y}\rangle \\
& =\|x-y\|^{2}+\gamma\left[\gamma\|\mathrm{U} x-\mathrm{U} y\|^{2}-2\langle x-\mathrm{y}, \mathrm{U} x-\mathrm{U} y\rangle\right] \\
& \leqslant\|x-y\|^{2} .
\end{aligned}
$$

Hence, $\|V x-V y\| \leqslant\|x-y\|$. Then $T \triangleq P_{C}\left(I-\gamma A^{*}\left(I-P_{Q}\right) A\right)$ is nonexpansive on $C$.
Theorem 3.3. Let $\mathrm{H}_{1}$ and $\mathrm{H}_{2}$ be two real Hilbert spaces, $\mathrm{A}: \mathrm{H}_{1} \rightarrow \mathrm{H}_{2}$ be a bounded linear operator, and $\mathrm{A}^{*}$ : $\mathrm{H}_{2} \rightarrow \mathrm{H}_{1}$ be a adjoint operator of A. Assume the SFP (1.1) is consistent, $0<\gamma<\frac{2}{\rho}, \rho$ is the spectral radius of $A^{*} A, S \neq \emptyset$, and $\left\{\alpha_{n}\right\}_{n=1}^{\infty},\left\{\beta_{n}\right\}_{n=1}^{\infty}$, and $\left\{\lambda_{n}\right\}_{n=1}^{\infty}$ in $(0,1)$, the following conditions are satisfied:
(i) $\lim _{n \rightarrow \infty} \alpha_{n}=1, \lim _{n \rightarrow \infty} \beta_{n}=1, \lim _{n \rightarrow \infty} \lambda_{n}=1$;
(ii) $\left|\lambda_{n}-\beta_{n-1} \lambda_{n-1}\right|+\beta_{n} \leqslant 1, \sum_{n=0}^{\infty}\left(1-\beta_{n}\right)\left(1-\lambda_{n}\right)=\infty$;
(iii) $\sum_{n=0}^{\infty}\left|\alpha_{n+1}-\alpha_{n}\right|<\infty, \sum_{n=0}^{\infty}\left|\beta_{n+1}-\beta_{n}\right|<\infty, \sum_{n=0}^{\infty}\left|\lambda_{n+1}-\lambda_{n}\right|<\infty$.

Let $\left\{x_{n}\right\}$ be generated by $x_{1} \in \mathrm{H}_{1}$ and

$$
\left\{\begin{array}{l}
x_{n+1}=\left(1-\beta_{n}\right)\left(\lambda_{n} x_{n}\right)+\beta_{n} y_{n}, \\
y_{n}=\left(1-\alpha_{n}\right) x_{n}+\alpha_{n} P_{C}\left(x_{n}-\gamma A^{*}\left(I-P_{Q}\right) A x_{n}\right) .
\end{array}\right.
$$

Then the sequence $\left\{x_{n}\right\}$ converges strongly to a point $\hat{x} \in S$, where $\hat{x}$ is the minimum-norm solution of (1.1).
Proof. From Lemma 3.1, we know $x \in S$ if and only if $x=P_{C}\left(I-\gamma A^{*}\left(I-P_{Q}\right) A\right) x$.
From Proposition 3.2, we know the operator $T \triangleq \mathrm{P}_{\mathrm{C}}\left(\mathrm{I}-\gamma \mathrm{U} A^{*}\left(\mathrm{I}-\mathrm{P}_{\mathrm{Q}}\right) \mathcal{A}\right)$ is nonexpansive.
Based on Theorem 2.1, we can obtain the sequence $\left\{x_{n}\right\}$ converges strongly to a point $\hat{x} \in S$, where $\hat{x}$ is the minimum-norm solution of (1.1).

Theorem 3.4. Let $H_{1}$ and $H_{2}$ be two real Hilbert spaces, $A: H_{1} \rightarrow H_{2}$ be a bounded linear operator, and $A^{*}$ : $\mathrm{H}_{2} \rightarrow \mathrm{H}_{1}$ be a adjoint operator of $A$. Assume the SFP (1.1) is consistent, $0<\gamma<\frac{2}{\rho}$, $\rho$ is the spectral radius of $A^{*} A, S \neq \emptyset$, and $\left\{\alpha_{n}\right\}_{n=1}^{\infty}$ and $\left\{\beta_{n}\right\}_{n=1}^{\infty}$ in $(0,1)$, the following conditions are satisfied:
(i) $\lim _{n \rightarrow \infty} \alpha_{n}=1, \lim _{n \rightarrow \infty} \beta_{n}=1$;
(ii) $\sum_{n=0}^{\infty}\left(1-\alpha_{n}\right)=\infty, \sum_{n=0}^{\infty}\left(1-\beta_{n}\right)=\infty$;
(iii) $\sum_{n=0}^{\infty}\left|\alpha_{n+1}-\alpha_{n}\right|<\infty, \sum_{n=0}^{\infty}\left|\beta_{n+1}-\beta_{n}\right|<\infty$;

Let $\left\{x_{n}\right\}$ be generated by $x_{1} \in H_{1}$ and

$$
\left\{\begin{array}{l}
x_{n+1}=\left(1-\beta_{n}\right) u+\beta_{n} y_{n}, \\
y_{n}=\left(1-\alpha_{n}\right) x_{n}+\alpha_{n} P_{C}\left(x_{n}-\gamma A^{*}\left(I-P_{Q}\right) A x_{n}\right)
\end{array}\right.
$$

Then the sequence $\left\{x_{n}\right\}$ converges strongly to a point $\hat{x} \in S$, and the solution $\hat{x}$ is the nearest point to $u$.
Proof. From Lemma 3.1, we know $x \in S$ if and only if $x=P_{C}\left(I-\gamma A^{*}\left(I-P_{Q}\right) A\right) x$.
From Proposition 3.2, we know the operator $T \triangleq P_{C}\left(I-\gamma U A^{*}\left(I-P_{Q}\right) A\right)$ is nonexpansive.
Based on Theorem 1 of [8], we can obtain the sequence $\left\{x_{n}\right\}$ converges strongly to a point $\hat{x} \in S$, and the solution $\hat{x}$ is the nearest point to $u$.

## 4. Conclusions

In this paper, we propose two strong convergence algorithms for solving the split feasibility problem and obtain corresponding strong convergence theorems. This method can be applied in solving the relevant problem, such as the split common fixed point problem (SCFP), multi-set split feasibility problem, and so on.

## Acknowledgment

This work was supported by Natural Science Basic Research Plan in Shaanxi Province of China (No. 2016JQ1022) and Special Science Research Plan of the Education Bureau of Shaanxi Province of China (No. 16JK1341) and Doctoral Scientific Research Foundation of Xi'an Polytechnic University (No. BS1432), National Science Foundation of China (No. 11501431) and Natural Science Foundation of Jiangsu (No. 16KJB110016).

## References

[1] C. Byrne, Iterative oblique projection onto convex sets and the split feasibility problem, Inverse Problems, 18 (2002), 441-453. 1
[2] C. Byrne, A unified treatment of some iterative algorithms in signal processing and image reconstruction, Inverse Problems, 20 (2004), 103-120. 1
[3] L.-C. Ceng, Q. H. Ansari, J.-C. Yao, Relaxed extragradient methods for finding minimum-norm solutions of the split feasibility problem, Nonlinear Anal., 75 (2012), 2116-2125. 1
[4] Y. Censor, T. Borfeid, B. Martin, A. Troimov, A unified approach for inversion problems in intensity-modulated radiation therapy, Phys. Med. Biol., 51 (2005), 2353-2365. 1
[5] Y. Censor, Y. Elfving, A multiprojection algorithm using Bregman projection in a product space, Numer. Algorithms, 8 (1994), 221-239. 1
[6] Y. Censor, Y. Elfving, N. Kopf, T. Bottfeld, The multiple-sets split feasibility problem and its applications for inverse problems, Inverse Problems, 21 (2005), 2071-2084. 1
[7] Q.-W. Fan, W. Wu, J. M. Zurada, Convergence of batch gradient learning with smoothing regularization and adaptive momentum for neural, SpringerPlus, 5 (2016), 17 pages. 1
[8] T.-H. Kim, H.-K. Xu, Strong convergence of modified Mann iterations, Nonlinear Anal., 61 (2005), 51-60. 3
[9] R. Kraikaew, S. Saejung, On split common fixed point problems, J. Math. Anal. Appl., 415 (2014), 513-524. 1
[10] A. Moudafi, A relaxed alternating CQ-algorithm for convex feasibility problems, Nonlinear Anal., 79 (2013), 117-121. 1
[11] X.-L. Qin, J.-C. Yao, Weak convergence of a Mann-like algorithm for nonexpansive and accretive operators, J. Inequal. Appl., 2016 (2016), 9 pages. 1
[12] B. Qu, B.-H. Liu, N. Zheng, On the computation of the step-size for the CQ-like algorithms for the split feasibility problem, Appl. Math. Comput., 262 (2015), 218-223. 1, 1
[13] B. Qu, N.-H. Xiu, A note on the CQ algorithm for the split feasibility problem, Inverse Problems, 21 (2005), 1655-1665. 1
[14] B. Qu, N.-H. Xiu, A new halfspace-relaxation projection method for the split feasibility problem, Linear Algebra Appl., 428 (2008), 1218-1229. 1, 1
[15] W. Takahashi, Nonlinear functional analysis, Fixed point theory and its applications, Yokohama Publishers, Yokohama, (2000). 1.4
[16] Z.-W. Wang, Q.-Z. Yang, Y.-N. Yang, The relaxed inexact projection methods for the split feasibility problem, Appl. Math. Comput., 217 (2011), 5347-5359. 1
[17] H.-K. Xu, Iterative algorithms for nonlinear operators, J. London Math. Soc., 66 (2002), 240-256. 1.5
[18] H.-K. Xu, An iterative approach to quadratic optimization, J. Optim. Theory Appl., 116 (2003), 659-678. 1.5
[19] H.-K. Xu, Viscosity approximation methods for nonexpansive mappings, J. Math. Anal. Appl., 298 (2004), 279-291. 1.3
[20] H.-K. Xu, A variable Krasonsel'skil-Mann algorithm and the multiple-set split feasibility problem, Inverse Problems, 22 (2006), 2021-2034. 1
[21] H.-K. Xu, Iterative methods for the split feasibility problem in infinite-dimensional Hilbert spaces, Inverse Problems, 26 (2010), 17 pages. 1, 1, 3.1
[22] Q.-Z. Yang, The relaxed CQ algorithm solving the split feasibility problem, Inverse Problems, 20 (2004), 1261-1266. 1, 1
[23] Y.-H. Yao, R. P. Agarwal, M. Postolache, Y.-C. Liou, Algorithms with strong convergence for the split common solution of the feasibility problem and fixed point problem, Fixed Point Theory Appl., 2014 (2014), 14 pages. 1
[24] Y.-H. Yao, Y.-C. Liou, J.-C. Yao, Split common fixed point problem for two quasi-pseudo-contractive operators and its algorithm construction, Fixed Point Theory Appl., 2015 (2015), 19 pages.
[25] Y.-H. Yao, G. Marino, H.-K. Xu, Y.-C. Liou, Construction of minimum-norm fixed points of pseudocontractions in Hilbert spaces, J. Inequal. Appl., 2014 (2014), 14 pages.
[26] Y.-H. Yao, M. Postolache, Y.-C. Liou, Strong convergence of a self-adaptive method for the split feasibility problem, Fixed Point Theory Appl., 2013 (2013), 12 pages. 1
[27] J.-L. Zhao, Q.-Z. Yang, Several solution methods for the split feasibility problem, Inverse Problems, 21 (2005), 1791-1799. 1
[28] J.-L. Zhao, Y.-J. Zhang, Q.-Z. Yang, Modified projection methods for the split feasibility problem and the multiple-sets split feasibility problem, Appl. Math. Comput., 219 (2012), 1644-1653. 1


[^0]:    *Corresponding author
    Email addresses: qinweifan@126.com (Qinwei Fan), yaozhsong@163.com (Zhangsong Yao)

