# Variational principle for a three-point boundary value problem 

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#### Abstract

A variational principle is established for a three-point boundary value problem. The stationary condition includes not only the governing equation but also the natural boundary conditions. The paper reveals that not every boundary condition adopts a variational formulation, and the existence and uniqueness of the solutions of a three-point boundary value problem can be revealed by its variational formulation. © 2016 All rights reserved.


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## 1. Introduction

Two-point boundary value problems are widely studied and applied in various fields, while multiple-point problems are relatively difficult to be solved either numerically or analytically. For example, a differential equation describing a truss bridge requires multiple boundary conditions. An unsuitable boundary condition might make the problem ill-posed, though the solution does exist, and this is the reason that existence of solution was widely studied for three-point boundary problems [1, 10. It becomes an important issue in multiple point problems to incorporate a suitable boundary condition into the governing equations. In this

[^0]paper, we study the following nonlinear three-point boundary value problems for a second-order ordinary differential equation
\[

$$
\begin{equation*}
y^{\prime \prime}+p(x) y^{\prime}+q(x) y+r(x) y^{2}+f(x)=0, \quad x \in\left[x_{1}, x_{3}\right] \tag{1.1}
\end{equation*}
$$

\]

with the following general boundary conditions:

$$
\begin{gather*}
\sum_{i=1}^{3} k_{i} y\left(x_{i}\right)+\sum_{i=1}^{3} h_{i} y^{\prime}\left(x_{i}\right)=\alpha  \tag{1.2}\\
\sum_{i=1}^{3} m_{i} y\left(x_{i}\right)+\sum_{i=1}^{3} n_{i} y^{\prime}\left(x_{i}\right)=\beta, \quad x_{2} \in\left[x_{1}, x_{3}\right] \tag{1.3}
\end{gather*}
$$

where $p(x), q(x), f(x)$ and $r(x)$ are known functions, $k_{i}, h_{i}, m_{i}, n_{i}, \alpha$ and $\beta$ are constants. When $r(x)=0$, Eq. (1.1) is a linear one.

There are some effective approaches to three-point boundary value problems for a second-order ordinary differential equation [2, 9, 11]. In this paper, a variational formulation is to be established via the semi-inverse method [3, 4], and how to suitably incorporate boundary conditions will be discussed.

## 2. Variational formulation

In case $p(x)=0$, without considering the boundary conditions, we have the following variational principle:

$$
\begin{equation*}
J(y)=\int_{a}^{b}\left\{\frac{1}{2} y^{\prime 2}-\frac{1}{2} q(x) y^{2}-f(x) y-\frac{1}{3} r(x) y^{3}\right\} d x \tag{2.1}
\end{equation*}
$$

In order to establish a variational formulation for Eq. (1.1), according to the semi-inverse method [3], we begin with the following trial-functional:

$$
J(y)=\int_{a}^{b}\left\{\frac{1}{2} \sigma(x) y^{\prime 2}+F(x, y)\right\} d x
$$

where $\sigma(x)$ is an unknown function of $x$ to be further determined, and $F$ is an unknown function of $x$ and $y$ and/or derivatives of $y$. There are alternative approaches to construct the trial-functionals, illustrating examples are available in the review article [5]. The semi-inverse method becomes an effective method for establishment of variational formulation directly from governing equations [6] 8].

The Euler-Lagrange equation of Eq. (2.1) reads

$$
\frac{d}{d x}\left[\sigma(x) y^{\prime}\right]-\frac{\partial F}{\partial y}=0,
$$

or

$$
\begin{equation*}
\sigma(x) y^{\prime \prime}+\sigma^{\prime}(x) y^{\prime}-\frac{\partial F}{\partial y}=0 \tag{2.2}
\end{equation*}
$$

Eq. (1.1) can be equivalently written as

$$
\begin{equation*}
\sigma(x) y^{\prime \prime}+\sigma(x) p(x) y^{\prime}+\sigma(x) q(x) y+\sigma(x) r(x) y^{2}+\sigma(x) f(x)=0 \tag{2.3}
\end{equation*}
$$

Comparison of Eq. (2.2) with Eq. (2.3) results in

$$
\begin{gathered}
\sigma^{\prime}(x)=\sigma(x) p(x) \\
\frac{\partial F}{\partial y}=-\sigma(x) q(x) y-\sigma(x) r(x) y^{2}-\sigma(x) f(x)
\end{gathered}
$$

We can identify $\sigma(x)$ and $F(y)$ as follows

$$
\begin{gather*}
\sigma(x)=\exp \left\{\int p(x) d x\right\}  \tag{2.4}\\
F(x, y)=-\frac{1}{2} \sigma(x) q(x) y^{2}-\frac{1}{3} \sigma(x) r(x) y^{3}-\sigma(x) f(x) y
\end{gather*}
$$

We, therefore, obtain the following variational formulation for Eq. (1.1):

$$
\begin{equation*}
J(y)=\int_{a}^{b}\left\{\frac{1}{2} \sigma(x) y^{\prime 2}-\frac{1}{2} \sigma(x) q(x) y^{2}-\frac{1}{3} \sigma(x) r(x) y^{3}-\sigma(x) f(x) y\right\} d x \tag{2.5}
\end{equation*}
$$

where $\sigma(x)$ is called integral factor, and it is defined in Eq. (2.4).

## 3. Boundary conditions

In order to incorporate the boundary conditions into the variational formulation, we consider the case $r(x)=0$.

We write Eq. 2.5) in the form

$$
\begin{align*}
J(y)= & \int_{x_{1}}^{x_{2}}\left\{\frac{1}{2} \sigma(x) y^{\prime 2}-\frac{1}{2} \sigma(x) q(x) y^{2}-\sigma(x) f(x) y\right\} d x \\
& +\int_{x_{2}}^{x_{3}}\left\{\frac{1}{2} \sigma(x) y^{\prime 2}-\frac{1}{2} \sigma(x) q(x) y^{2}-\sigma(x) f(x) y\right\} d x  \tag{3.1}\\
& +\sum_{i=1}^{3} F_{i}\left(y\left(x_{1}\right), y\left(x_{2}\right), y\left(x_{3}\right), y^{\prime}\left(x_{1}\right), y^{\prime}\left(x_{2}\right), y^{\prime}\left(x_{3}\right)\right)
\end{align*}
$$

where $F_{i}(i=1,2,3)$ are introduced to match the boundary conditions of Eq. (1.2) and Eq. (1.3). The variation of Eq. (3.1) reads

$$
\begin{aligned}
\delta J(y)= & \int_{x_{1}}^{x_{2}}\left\{\sigma(x) y^{\prime} \delta y^{\prime}-\sigma(x) q(x) y \delta y-\sigma(x) f(x) \delta y\right\} d x \\
& +\int_{x_{2}}^{x_{3}}\left\{\sigma(x) y^{\prime} \delta y^{\prime}-\sigma(x) q(x) y \delta y-\sigma(x) f(x) \delta y\right\} d x \\
& +\sum_{i=1}^{3} \delta F_{i}\left(y\left(x_{1}\right), y\left(x_{2}\right), y\left(x_{3}\right), y^{\prime}\left(x_{1}\right), y^{\prime}\left(x_{2}\right), y^{\prime}\left(x_{3}\right)\right)
\end{aligned}
$$

or

$$
\begin{aligned}
\delta J(y)= & \int_{x_{1}}^{x_{2}}\left\{\sigma(x) y^{\prime} \frac{d}{d x}(\delta y)-\sigma(x) q(x) y \delta y-\sigma(x) f(x) \delta y\right\} d x \\
& +\int_{x_{2}}^{x_{3}}\left\{\sigma(x) y^{\prime} \frac{d}{d x}(\delta y)-\sigma(x) q(x) y \delta y-\sigma(x) f(x) \delta y\right\} d x \\
& +\sum_{i=1}^{3} \delta F_{i}\left(y\left(x_{1}\right), y\left(x_{2}\right), y\left(x_{3}\right), y^{\prime}\left(x_{1}\right), y^{\prime}\left(x_{2}\right), y^{\prime}\left(x_{3}\right)\right)
\end{aligned}
$$

Integration by parts results in

$$
\begin{aligned}
\delta J(y)= & \int_{x_{1}}^{x_{2}}\left\{-\delta y \frac{d}{d x}\left(\sigma(x) y^{\prime}\right)-\sigma(x) q(x) y \delta y-\sigma(x) f(x) \delta y\right\} d x \\
& +\int_{x_{2}}^{x_{3}}\left\{-\delta y \frac{d}{d x}\left(\sigma(x) y^{\prime}\right)-\sigma(x) q(x) y \delta y-\sigma(x) f(x) \delta y\right\} d x
\end{aligned}
$$

$$
\begin{aligned}
& +\left.\left\{\sigma(x) y^{\prime} \delta y\right\}\right|_{x=x_{1}} ^{x=x_{2}}+\left.\left\{\sigma(x) y^{\prime} \delta y\right\}\right|_{x=x_{2}} ^{x=x_{3}} \\
& +\sum_{i=1}^{3} \delta F_{i}\left(y\left(x_{1}\right), y\left(x_{2}\right), y\left(x_{3}\right), y^{\prime}\left(x_{1}\right), y^{\prime}\left(x_{2}\right), y^{\prime}\left(x_{3}\right)\right) .
\end{aligned}
$$

By setting $\delta J(y)=0$, we can obtain the following natural boundary conditions:
On $x=x_{1}$ :

$$
\begin{gathered}
\delta y\left(x_{1}\right):-\sigma\left(x_{1}\right) y^{\prime}\left(x_{1}\right)+\frac{\partial F_{1}}{\partial y\left(x_{1}\right)}+\frac{\partial F_{2}}{\partial y\left(x_{1}\right)}+\frac{\partial F_{3}}{\partial y\left(x_{1}\right)}=0, \\
\delta y^{\prime}\left(x_{1}\right): \frac{\partial F_{1}}{\partial y^{\prime}\left(x_{1}\right)}+\frac{\partial F_{2}}{\partial y^{\prime}\left(x_{1}\right)}+\frac{\partial F_{3}}{\partial y^{\prime}\left(x_{1}\right)}=0 .
\end{gathered}
$$

On $x=x_{2}$ :

$$
\begin{gather*}
\delta y\left(x_{2}\right): \frac{\partial F_{1}}{\partial y\left(x_{2}\right)}+\frac{\partial F_{2}}{\partial y\left(x_{2}\right)}+\frac{\partial F_{3}}{\partial y\left(x_{2}\right)}=0,  \tag{3.2}\\
\delta y^{\prime}\left(x_{2}\right): \frac{\partial F_{1}}{\partial y^{\prime}\left(x_{2}\right)}+\frac{\partial F_{2}}{\partial y^{\prime}\left(x_{2}\right)}+\frac{\partial F_{3}}{\partial y^{\prime}\left(x_{2}\right)}=0 . \tag{3.3}
\end{gather*}
$$

On $x=x_{3}$ :

$$
\begin{gather*}
\delta y\left(x_{3}\right): \sigma\left(x_{3}\right) y^{\prime}\left(x_{3}\right)+\frac{\partial F_{1}}{\partial y\left(x_{3}\right)}+\frac{\partial F_{2}}{\partial y\left(x_{3}\right)}+\frac{\partial F_{3}}{\partial y\left(x_{3}\right)}=0, \\
\delta y^{\prime}\left(x_{3}\right): \frac{\partial F_{1}}{\partial y^{\prime}\left(x_{3}\right)}+\frac{\partial F_{2}}{\partial y^{\prime}\left(x_{3}\right)}+\frac{\partial F_{3}}{\partial y^{\prime}\left(x_{3}\right)}=0 . \tag{3.4}
\end{gather*}
$$

Incorporating the boundary conditions, Eqs. (1.2) and (1.3), we have

$$
\begin{gather*}
\frac{\partial F_{1}}{\partial y\left(x_{1}\right)}+\frac{\partial F_{2}}{\partial y\left(x_{1}\right)}+\frac{\partial F_{3}}{\partial y\left(x_{1}\right)}=\sigma\left(x_{1}\right) y^{\prime}\left(x_{1}\right)=\frac{\sigma\left(x_{1}\right)}{h_{1}}\left[\alpha-\sum_{i=1}^{3} k_{i} y\left(x_{i}\right)-\sum_{i=2}^{3} h_{i} y^{\prime}\left(x_{i}\right)\right],  \tag{3.5}\\
\frac{\partial F_{1}}{\partial y\left(x_{3}\right)}+\frac{\partial F_{2}}{\partial y\left(x_{3}\right)}+\frac{\partial F_{3}}{\partial y\left(x_{3}\right)}=-\sigma\left(x_{3}\right) y^{\prime}\left(x_{3}\right)=-\frac{\sigma\left(x_{3}\right)}{n_{3}}\left[\beta-\sum_{i=1}^{3} m_{i} y\left(x_{i}\right)+\sum_{i=1}^{2} n_{i} y^{\prime}\left(x_{i}\right)\right] . \tag{3.6}
\end{gather*}
$$

The integrability condition for identification of $F_{i}(i=1,2,3)$ requires

$$
\begin{align*}
\frac{\partial}{\partial y\left(x_{i}\right)} \frac{\partial F_{k}}{\partial y\left(x_{j}\right)} & =\frac{\partial}{\partial y\left(x_{j}\right)} \frac{\partial F_{k}}{\partial y\left(x_{i}\right)},  \tag{3.7}\\
\frac{\partial}{\partial y^{\prime}\left(x_{i}\right)} \frac{\partial F_{k}}{\partial y^{\prime}\left(x_{j}\right)} & =\frac{\partial}{\partial y^{\prime}\left(x_{j}\right)} \frac{\partial F_{k}}{\partial y^{\prime}\left(x_{i}\right)},  \tag{3.8}\\
\frac{\partial}{\partial y\left(x_{i}\right)} \frac{\partial F_{k}}{\partial y^{\prime}\left(x_{j}\right)} & =\frac{\partial}{\partial y^{\prime}\left(x_{j}\right)} \frac{\partial F_{k}}{\partial y\left(x_{i}\right)}, \tag{3.9}
\end{align*}
$$

where $i, j, k=1,2,3$. For example, for $j=1, i=3$ and $k=1$, from Eq. (3.7), it requires that

$$
-\frac{\sigma\left(x_{1}\right) k_{3}}{h_{1}}=\frac{\sigma\left(x_{3}\right) m_{1}}{n_{3}} .
$$

To show the identification of $F_{i}(i=1,2,3)$, we consider a simple case of the boundary conditions:

$$
\begin{gather*}
y^{\prime}\left(x_{1}\right)=\alpha_{1}, \\
y^{\prime}\left(x_{3}\right)+\lambda y^{\prime}\left(x_{2}\right)=\beta_{1} . \tag{3.10}
\end{gather*}
$$

Setting

$$
\frac{\partial F_{2}}{\partial y\left(x_{1}\right)}=\frac{\partial F_{3}}{\partial y\left(x_{1}\right)}=0,
$$

in Eq. (3.5), $F_{1}$ can be identified, which reads

$$
F_{1}=\sigma\left(x_{1}\right) \alpha_{1} y\left(x_{1}\right) .
$$

By setting

$$
\begin{gathered}
\frac{\partial F_{1}}{\partial y\left(x_{3}\right)}=\frac{\partial F_{2}}{\partial y\left(x_{3}\right)}=0, \\
\frac{\partial F_{1}}{\partial y^{\prime}\left(x_{3}\right)}=\frac{\partial F_{2}}{\partial y^{\prime}\left(x_{3}\right)}=0,
\end{gathered}
$$

in Eq. (3.6) and Eq. (3.4), respectively, and by using the boundary condition, Eq. (3.10), we have

$$
\frac{\partial F_{3}}{\partial y\left(x_{3}\right)}=-\sigma\left(x_{3}\right) y^{\prime}\left(x_{3}\right)=-\sigma\left(x_{3}\right)\left[\beta_{1}-\lambda y^{\prime}\left(x_{2}\right)\right] .
$$

We, therefore, can identify $F_{3}$ as follows

$$
F_{3}=-\sigma\left(x_{3}\right)\left[\beta_{1}-\lambda y^{\prime}\left(x_{2}\right)\right] y\left(x_{3}\right) .
$$

From Eqs.(3.2) and (3.3), and using the above identified results, we have

$$
\begin{gathered}
\frac{\partial F_{2}}{\partial y\left(x_{2}\right)}=0, \\
\frac{\partial F_{2}}{\partial y^{\prime}\left(x_{2}\right)}=-\frac{\partial F_{3}}{\partial y^{\prime}\left(x_{2}\right)}=-\sigma\left(x_{3}\right) \lambda y\left(x_{3}\right) .
\end{gathered}
$$

We, therefore, identify $F_{2}$ as follows

$$
F_{2}=-\sigma\left(x_{3}\right) \lambda y\left(x_{3}\right) y^{\prime}\left(x_{2}\right) .
$$

The variational formulation reads

$$
\begin{aligned}
J(y)= & \int_{x_{1}}^{x_{2}}\left\{\frac{1}{2} \sigma(x) y^{\prime 2}-\frac{1}{2} \sigma(x) q(x) y^{2}-\sigma(x) f(x) y\right\} d x \\
& +\sigma\left(x_{1}\right) \alpha_{1} y\left(x_{1}\right)-\sigma\left(x_{3}\right) \lambda y\left(x_{3}\right) y^{\prime}\left(x_{2}\right)-\sigma\left(x_{3}\right)\left[\beta_{1}-\lambda y^{\prime}\left(x_{2}\right)\right] y\left(x_{3}\right) .
\end{aligned}
$$

## 4. Discussion and conclusions

The integral factor, $\sigma(x)$, defined in Eq. (2.4), is of great importance, it affects the boundary conditions of the three-point boundary value problem. The identification of integral boundary in the variational formulation requires the integrability conditions, that is given in Eqs. (3.7)-(3.9). A variational formulation reveals the existence and uniqueness of the solutions of a three-point boundary value problem, and it also suggests some suitable boundary conditions for a practical problem. The present theory can be easily extended to multiple point boundary value problems.

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