On the split equality common fixed point problem for quasi-nonexpansive multi-valued mappings in Banach spaces

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Abstract

The purpose of this paper is to study the split equality common fixed point problems of quasi-nonexpansive multi-valued mappings in the setting of Banach spaces. For solving this kind of problems, some new iterative algorithms are proposed. Under suitable conditions, some weak and strong convergence theorems for the sequences generated by the proposed algorithm are proved. The results presented in this paper are new which also improve and extend some recent results announced by some authors. ©2016 All rights reserved.

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1. Introduction

Let $C$ and $Q$ be two nonempty closed convex subsets of real Hilbert spaces $H_1$ and $H_2$, respectively. The split feasibility problem (SFP) can be formulated as

$$\text{find } x \in C \text{ such that } Ax \in Q, \quad (1.1)$$
where $A : H_1 \rightarrow H_2$ is a bounded linear operator. The split feasibility problem (SFP) in finitely dimensional spaces was firstly introduced by Censor and Elfving [4] for modeling inverse problems which arise from phase retrievals and in medical image reconstruction [2]. The SFP has attracted much attention because of its applications in modeling inverse problems, radiation therapy treatment planning and signal processing [3–6]. Some methods have been proposed to solve split feasibility problems in [13–18, 19].

Assume that SFP (1.1) is consistent, it is not hard to see that the solution set of SFP (1.1) (i.e., $\{x \in C : Ax \in Q\}$) is closed and convex. The SFP can be solved by the CQ algorithm, which was firstly proposed by Byrne [2]:

$$x_{k+1} = P_C(I - \gamma A^* (I - P_Q) A)x_k, \quad k \geq 1,$$

where $\gamma \in (0, \frac{2}{\|A\|^2})$ with $\lambda$ being the spectral radius of the operator $A^* A$, $P_C$ and $P_Q$ are the metric projections from $H_1$ onto $C$ and from $H_2$ onto $Q$, respectively.

If $C$ and $Q$ are sets of fixed points of two nonlinear mappings, respectively, and $C$ and $Q$ are nonempty closed convex subsets, then $q$ is said to be a split common fixed point for the two nonlinear mappings. That is, the split common fixed point problem (SCFP) for mappings $S$ and $T$ is to find a point $q \in H_1$ with the property:

$$q \in C := F(S) \quad \text{and} \quad Aq \in Q := F(T),$$

where $F(S)$ and $F(T)$ denote the sets of fixed points of $S$ and $T$, respectively.

Since each nonempty closed convex subset of a Hilbert space is the set of fixed points of its projection, so the split common fixed point problem can be considered as a generalization of the split feasibility problem and the convex feasibility problem. The split common fixed point problem was introduced by Moudafi [10] in 2010. In [10], Moudafi proposed an iteration scheme and obtained a weak convergence theorem of the split common fixed point problem for demicontractive mappings in the setting of two Hilbert spaces. Since then, the split common fixed point problems of other nonlinear mappings in the setting of two Hilbert spaces have been studied by some authors, see, for instance, [7, 8, 10, 11, 13–14, 20].

Recently, Moudafi [12] proposed the split equality problem (SEP):

$$\text{find } x \in C \text{ and } y \in Q \text{ such that } Ax = By,$$

where $A : H_1 \rightarrow H_3$ and $B : H_2 \rightarrow H_3$ are two bounded linear operators, $C$ and $Q$ are two nonempty closed convex subsets of $H_1$ and $H_2$, respectively. We use $\Gamma$ to denote the set of solution of SEP (1.3), that is, $\Gamma = \{(p, q) : p \in C, q \in Q, Ap = Bq\}$.

It is obvious that if $B = I$ and $H_3 = H_2$, then SEP (1.3) can be reduced to SFP (1.1). The split equality problem (1.2) allows asymmetric and partial relations between the variables $x$ and $y$. The interest is to cover many situations such as decomposition methods for PDEs, applications in game theory, intensity-modulated radiation therapy. In decision sciences, this allows one to consider agents who interplay only via some components of their decision variables.

In order to solve SEP (1.3), Moudafi [12] proposed the following alternating CQ-algorithm (ACQA) and relaxed alternating CQ-algorithm (RACQA), i.e.,

$$\text{ACQA : } \begin{cases} x_{k+1} = P_C(x_k - \gamma_k A^* (Ax_k - By_k)), \\ y_{k+1} = P_Q(y_k + \gamma_k B^* (Ax_k - By_k)), \end{cases}$$

and

$$\text{RACQA : } \begin{cases} x_{k+1} = P_C(x_k - \gamma_k A^* (Ax_k - By_k)), \\ y_{k+1} = P_Q(y_k + \beta B^* (Ax_k - By_k)), \end{cases}$$

under appropriate conditions, the author proved that the iterative schemes above converge weakly to a solution of the SEP (1.3).

**Definition 1.1.** Let $E$ be a real Banach space and $S : E \rightarrow CB(E)$ be a multi-valued mapping. $S$ is said to be

1) nonexpansive, if $H(Sx, Sy) \leq \|x - y\|$, for all $x, y \in E$;
2) quasi-nonexpansive, if $F(S) \neq \emptyset$ and $H(Sx, Sz) \leq \|x - z\|$, for all $x \in E$ and $z \in F(S)$,
where $F(S)$ denotes the fixed points set of $S$, the Hausdorff metric on $CB(E)$ (which stands for the collection of all nonempty closed bounded subsets of $E$) is indicated by

$$H(C,D) = \max\{\sup_{x \in C} d(x,D), \sup_{y \in D} d(y,C)\}, C,D \in CB(E),$$

where $d(x,D) = \inf_{y \in D} ||x - y||$.

Recently, Wu et al. [10] proposed an iterative algorithm to study the convergence results of split equality common fixed point problem for quasi-nonexpansive multi-valued mappings in Hilbert spaces, and obtained the following result.

**Theorem 1.2** (Theorem 2.3 of [10]). Let $H_1, H_2, H_3$ be Hilbert spaces, $A : H_1 \to H_3$, $B : H_2 \to H_3$ be two bounded linear operators, $R_1 : H_1 \to CB(H_1)$ and $R_2 : H_2 \to CB(H_2)$ be two quasi-nonexpansive multi-valued mappings, $C = F(R_1)$, $Q = F(R_2)$. Suppose that $0 < \lim inf_{n \to \infty} \alpha_n \leq \lim sup_{n \to \infty} \alpha_n < 1$ and $R_1, R_2$ are demi-closed at the origin, the sequence $\{w_n\}$ is generated by

$$w_{n+1} = \alpha_n(I - G^*G)w_n + (1 - \alpha_n)v_n, \quad v_n \in R(w_n - G^*Gw_n),$$

(1.4)

where $\{\alpha_n\} \subseteq (0,1)$ and $\gamma \in (0, \frac{2}{\rho(G^*G)})$ with $\rho(G^*G)$ being the spectral radius of the self-adjoint operator $G^*G$ on $H$. Define $G : H \to H_3$ by $G = [A, -B]$, $R : H_1 \times H_2 \to H_1 \times H_2$ by

$$G = \begin{pmatrix} R_1 & 0 \\ 0 & R_2 \end{pmatrix}.$$

Then the sequence $\{w_n\}$ defined by (1.4) converges weakly to a solution of SEP (1.3). In addition, if $R_1, R_2$ are semi-compact, then the sequence $\{w_n\}$ converges strongly to a solution of SEP (1.3).

Very recently, in [13], Tang et al. proposed an iteration method to approximate a solution of the SCFP [12] for strict pseudocontractive mapping and asymptotically nonexpansive mappings in the setting of two Banach spaces, and obtained the strong and weak convergence theorems of iteration scheme proposed.

Naturally, the facts above remain us the following question:

**Can the convergence theorems for a solution of the split equality common fixed point problem for quasi-nonexpansive multi-valued mapping be obtained in Banach spaces?**

In this paper, we propose the following iterative algorithm to approximate a split equality common fixed point of quasi-nonexpansive multi-valued mappings in Banach spaces. For any $x_0 \in E_1$ and $y_0 \in E_2$, the sequence $\{(x_n, y_n)\}$ is generated by

$$\begin{cases} u_n \in S_1(x_n - \gamma J_1^{-1}A^*J_3(Ax_n - By_n)), \\ v_n \in S_2(y_n + \gamma J_2^{-1}B^*J_3(Ax_n - By_n)), \\ y_{n+1} = (1 - \beta_n)v_n + \beta_n(x_n + \gamma J_2^{-1}B^*J_3(Ax_n - By_n)), \\ x_{n+1} = (1 - \beta_n)u_n + \beta_n(x_n - \gamma J_1^{-1}A^*J_3(Ax_n - By_n)), \end{cases}$$

where $E_1, E_2, E_3$ are three Banach spaces, $A : E_1 \to E_3$, $B : E_2 \to E_3$ are two bounded linear operators, $S_1 : E_1 \to CB(E_1)$, $S_2 : E_2 \to CB(E_2)$ are two quasi-nonexpansive multi-valued mappings and $C = F(S_1)$, $Q = F(S_2)$. In the rest of this paper, we still denote the set of solutions of SEP (1.3) by $\Gamma = \{(x,y) \in E_1 \times E_2, Ax = By, x \in C, y \in D\}$. Under some mild conditions, we obtain the strong and weak convergence of the iterative scheme above in Banach spaces.

2. Preliminaries

Throughout this paper, the set of fixed points of $S$ is denoted by $F(S)$ and the strong convergence and weak convergence of a sequence $\{x_n\}$ to a point $x \in E$ is denoted by $x_n \to x$ and $x_n \rightharpoonup x$, respectively. Let $E$ be a real Banach space with the dual $E^*$. The normalized duality mapping $J : E \to 2^{E^*}$ is defined by

$$Jx = \{f \in E^* : \langle x, f \rangle = ||x||^2 = ||f||^2\}, \quad x \in E,$$
where $\langle \cdot, \cdot \rangle$ is the generalized duality pairing between $E$ and $E^*$.

A Banach space $E$ is said to be strictly convex, if $\frac{\|x+y\|}{2} < 1$ for all $x, y \in U = \{ z \in E : \|z\| = 1 \}$ with $x \neq y$.

A Banach space $E$ is said to be uniformly convex, if for each $\varepsilon \in (0, 2]$, there exists $\delta > 0$ such that $\frac{\|x+y\|}{2} \leq 1 - \delta$ for all $x, y \in U$ with $\|x-y\| > \varepsilon$.

A Banach space $E$ is said to be smooth, if the limit $\lim_{t \to 0} \frac{\|tx + ty\| - \|x\|}{t}$ exists for all $x, y \in U$. A Banach space $E$ is said to be uniformly smooth, if $\frac{\rho_E(t)}{t} \to 0$ as $t \to 0$, where the modulus of smoothness $\rho_E : [0, \infty) \to [0, \infty)$ is defined by

$$\rho_E(t) = \sup \left\{ \frac{(\|x+y\| + \|x-y\|)}{2} - 1 : x \in U, \|y\| \leq t \right\}.$$ 

A Banach space $E$ is said to be $p$-uniformly smooth (let $p > 1$ be a fixed number), if there exists a constant $c > 0$ such that $\rho_E(t) \leq ct^p$ for all $t > 0$.

**Remark 2.1 (9).** The basic properties of Banach space $E$ are as follows:

1. A uniformly convex Banach space is strictly convex and reflexive.
2. If $E$ is a smooth, reflexive and strictly convex Banach space, then the normalized duality mapping $J$ from $E$ to $2E^*$ is single-valued, one-to-one, and surjective.
3. If $E$ is an uniformly smooth Banach space, then the normalized duality mapping $J$ is uniformly continuous on every bounded subset of $E$.
4. A Banach space $E$ is uniformly smooth, if and only if its dual $E^*$ is uniformly convex.
5. Each uniformly convex Banach space $E$ has the Kadec-Klee property, i.e., $x_n \to u \in E$ and $\|x_n\| \to \|u\|$ imply $x_n \to u$.
6. It is common knowledge that every $p$-uniformly smooth Banach space is uniformly smooth.

**Lemma 2.2 (17).** Let $E$ be a uniformly convex Banach space. For any given number $r > 0$, there exists a continuous strictly increasing function $g : [0, \infty) \to [0, \infty)$, $g(0) = 0$ such that

$$\|tx + (1-t)y\|^2 \leq t\|x\|^2 + (1-t)\|y\|^2 - t(1-t)g(\|x-y\|)$$

for all $x, y \in E$ with $\|x\| \leq r$, $\|y\| \leq r$ and $t \in [0, 1]$.

**Lemma 2.3 (17).** Let $E$ be a 2-uniformly smooth Banach space with the best smoothness constant $k > 0$. Then the following inequality holds:

$$\|x+y\|^2 \leq \|x\|^2 + 2\langle y, Jx \rangle + 2\|ky\|^2, \quad x, y \in E.$$

**Definition 2.4 (16).** A multi-valued mapping $S : E \to CB(E)$ is said to be demi-closed at zero, if for any $\{x_n\} \subseteq E$ such that $x_n \to x$ and $d(x_n, Sx_n) \to 0$, then $x \in Sx$.

**Definition 2.5 (16).** Let $E$ be a Banach space. A multi-valued mapping $S : E \to CB(E)$ is said to be semi-compact, if for any bounded sequence $\{x_n\} \subseteq E$ such that $d(x_n, Sx_n) \to 0$, there exists a subsequence $\{x_{n_j}\}$ of $\{x_n\}$ such that $x_{n_j} \to x \in E$.

3. Main results

**Theorem 3.1.** Let $E_1, E_2$ be real uniformly convex and 2-uniformly smooth Banach spaces with the best smoothness constant $k \in (0, \frac{1}{\sqrt{2}})$, $E_3$ be a real Banach space, $S_1 : E_1 \to CB(E_1)$ and $S_2 : E_2 \to CB(E_2)$ be two quasi-nonexpansive multi-valued mappings, respectively. Let $A : E_1 \to E_3$ and $B : E_2 \to E_3$ be two bounded linear operators. For any $(x_0, y_0) \in E_1 \times E_2$, the sequence $\{(x_n, y_n)\}$ is generated by
So, it follows from (3.1) and (3.2) that
\[\begin{align*}
A & = \{t \in S_1 \mid t = (1 - \beta_n)u_n + \beta_n(x_n - \gamma J_1^{-1}A^*J_3(Ax_n - By_n)) \}, \\
v_n & = S_2(y_n + \gamma J_2^{-1}B^*J_3(Ax_n - By_n)), \\
\|x_n - t\|^2 & = \|\beta_n(t_n - x) + (1 - \beta_n)(u_n - x)\|^2 \\
& \leq \beta_n\|t_n - x\|^2 + (1 - \beta_n)\|u_n - x\|^2 - \beta_n(1 - \beta_n)g(\|t_n - u_n\|) \\
& \leq \beta_n\|t_n - x\|^2 + (1 - \beta_n)H(S_1 t_n, S_1 x) - \beta_n(1 - \beta_n)g(\|t_n - u_n\|) \\
& \leq \beta_n\|t_n - x\|^2 + (1 - \beta_n)\|t_n - x\|^2 - \beta_n(1 - \beta_n)g(\|t_n - u_n\|) \\
& = \|t_n - x\|^2 - \beta_n(1 - \beta_n)g(\|t_n - u_n\|). 
\end{align*}\]

Further, from Lemma 2.3 we have
\[\begin{align*}
\|t_n - x\|^2 & = \|x_n - \gamma J_1^{-1}A^*J_3(Ax_n - By_n) - x\|^2 \\
& = \|\gamma J_1^{-1}A^*J_3(Ax_n - By_n) + (x - x_n)\|^2 \\
& \leq \|\gamma J_1^{-1}A^*J_3(Ax_n - By_n)\|^2 + 2\gamma \langle x - x_n, J_1 J_1^{-1}A^*J_3(Ax_n - By_n) \rangle + 2k^2\|x - x_n\|^2 \\
& \leq \gamma^2 L\|Ax_n - By_n\|^2 + 2\gamma \langle Ax - Ax_n, J_3(Ax_n - By_n) \rangle + 2k^2\|x - x_n\|^2. 
\end{align*}\]

So, it follows from (3.1) and (3.2) that
\[\begin{align*}
\|x_n + x\|^2 & \leq \gamma^2 L\|Ax_n - By_n\|^2 + 2\gamma \langle Ax - Ax_n, J_3(Ax_n - By_n) \rangle \\
& + 2\gamma \langle Ax - Ax_n, J_3(Ax_n - By_n) \rangle + 2k^2\|x - x_n\|^2 - \beta_n(1 - \beta_n)g(\|t_n - u_n\|). 
\end{align*}\]

Similarly, we can get
\[\begin{align*}
\|y_n + y\|^2 & \leq \gamma^2 L\|Ax_n - By_n\|^2 + 2\gamma \langle By_n - B y, J_3(Ax_n - By_n) \rangle \\
& + 2\gamma \langle By_n - B y, J_3(Ax_n - By_n) \rangle + 2k^2\|y - y_n\|^2 - \beta_n(1 - \beta_n)g(\|w_n - v_n\|). 
\end{align*}\]

By adding (3.3) and (3.4), since Ax = By, we have
\[\begin{align*}
\|x_n + x\|^2 + \|y_n + y\|^2 & \leq 2\gamma^2 L\|Ax_n - By_n\|^2 + 2\gamma \langle Ax_n - By_n, J_3(Ax_n - By_n) \rangle \\
& + 2\gamma \langle Ax_n - By_n, J_3(Ax_n - By_n) \rangle + 2k^2\|x - x_n\|^2 + \|y - y_n\|^2 - \beta_n(1 - \beta_n)g(\|t_n - u_n\|) + g(\|w_n - v_n\|). 
\end{align*}\]

Now, set W_n(x, y) = \|x_n - x\|^2 + \|y_n - y\|^2, it follows (3.5) that
\[\begin{align*}
W_n(x, y) & \leq 2\gamma L\|Ax_n - By_n\|^2 + 2\gamma \langle Ax_n - By_n, J_3(Ax_n - By_n) \rangle \\
& + 2k^2\|x - x_n\|^2 + \|y - y_n\|^2 - \beta_n(1 - \beta_n)g(\|t_n - u_n\|) + g(\|w_n - v_n\|). 
\end{align*}\]
Since $0 < \gamma < \frac{1}{\max\{\lambda_A, \lambda_B\}}$, $L = \max\{\lambda_A, \lambda_B\}$ and $k \in (0, \frac{1}{\sqrt{2}})$, we can obtain

$$W_{n+1}(x, y) \leq 2k^2W_n(x, y) \leq W_n(x, y).$$

This implies that $\{W_n(x, y)\}$ is a non-increasing sequence, hence $\lim_{n \to \infty} W_n$ exists. From (3.6), we have

$$2\gamma(1 - \gamma L)\|Ax_n - By_n\|^2 + \beta_n(1 - \beta_n)[g(\|t_n - u_n\|) + g(\|w_n - v_n\|)]$$

$$\leq 2k^2W_n(x, y) - W_{n+1}(x, y) \leq W_n(x, y) - W_{n+1}(x, y).$$

Therefore, we can obtain

$$\lim_{n \to \infty} g(\|t_n - u_n\|) = 0, \quad \lim_{n \to \infty} g(\|w_n - v_n\|) = 0,$$

and

$$\lim_{n \to \infty} \|Ax_n - By_n\| = 0. \quad (3.7)$$

By Lemma 2.2, we have

$$\lim_{n \to \infty} \|t_n - u_n\| = 0 \quad \text{and} \quad \lim_{n \to \infty} \|w_n - v_n\| = 0. \quad (3.8)$$

Since

$$\|x_n - t_n\| = \|J_1(x_n - t_n)\| = \|\gamma A^*J_3(Ax_n - By_n)\| \leq \gamma \|A\| \|Ax_n - By_n\|,$$

and

$$\|y_n - w_n\| = \|J_2(y_n - w_n)\| = \|\gamma B^*J_3(Ax_n - By_n)\| \leq \gamma \|B\| \|Ax_n - By_n\|,$$

from (3.7), we may get

$$\lim_{n \to \infty} \|x_n - t_n\| = 0 \quad \text{and} \quad \lim_{n \to \infty} \|y_n - w_n\| = 0. \quad (3.9)$$

Now, we prove the conclusion (I).

Since $E_1$ and $E_2$ are uniformly convex, they are reflexive. On the other hand, since $\|x_n - x\|^2 \leq W_n(x, y)$, $\|y_n - y\|^2 \leq W_n(x, y)$ and $\lim_{n \to \infty} W_n$ exists, we know that $\{(x_n, y_n)\}$ is bounded. So we may assume that $(x^*, y^*)$ is weak cluster points of $\{(x_n, y_n)\}$. By (3.9), we know that $(x^*, y^*)$ also is weak cluster points of $\{(t_n, w_n)\}$. In addition, since $u_n \in S_1t_n$ and $v_n \in S_2w_n$, we have $d(t_n, S_1t_n) \leq \|t_n - u_n\|$ and $d(w_n, S_2w_n) \leq \|w_n - v_n\|$. So it follows from (3.8) that $\lim_{n \to \infty} d(t_n, S_1t_n) = 0$ and $\lim_{n \to \infty} d(w_n, S_2w_n) = 0$. Due to the demi-closed property of $S_1$ and $S_2$, we have $(x^*, y^*) \in C \times Q$, where $C := Fix(S_1), Q := Fix(S_2)$.

Since $A$ and $B$ are bounded linear operators, we know that $Ax^* - By^*$ is a weak cluster point of $\{Ax_n - By_n\}$. From the weakly lower semi-continuous property of the norm and (3.7), we get

$$\|Ax^* - By^*\| \leq \liminf_{n \to \infty} \|Ax_n - By_n\| = 0.$$

So, $Ax^* = By^*$. This implies $(x^*, y^*) \in \{(x, y) \in E_1 \times E_2, Ax = By\}$. Hence

$$(x^*, y^*) \in \{(x, y) \in E_1 \times E_2 : Ax = By, x \in C, y \in Q\}.$$

We now prove that $(x^*, y^*)$ is the unique weak cluster point of $\{(x_n, y_n)\}$. Let $(p, q)$ be another weak cluster point of $\{(x_n, y_n)\}$. Similarly, by the arguments above, we have $(p, q) \in \Gamma$, too. Notice that

$$W_n(x^*, y^*) = \|x_n - x^*\|^2 + \|y_n - y^*\|^2$$

$$= \|x_n - p\|^2 + 2\langle x_n - p, J_1(p - x^*) \rangle + \|p - x^*\|^2$$

$$+ \|y_n - q\|^2 + 2\langle y_n - q, J_2(q - x^*) \rangle + \|q - y^*\|^2.$$
\[ W_n(p, q) + 2(x_n - p, J_1(p - x^*)) + \|p - x^*\|^2 + 2(y_n - q, J_2(q - x^*)) + \|q - y^*\|^2. \]

Without loss of generality, we may assume that \(\{(x_n, y_n)\}\) converges weakly to \((p, q)\). In addition, we also assume that \(\lim_{n \to \infty} W_n(x^*, y^*) = W(x^*, y^*)\) and \(\lim_{n \to \infty} W_n(p, q) = W(p, q)\). Thus, from the equality above, we have

\[ W(x^*, y^*) = W(p, q) + \|p - x^*\|^2 + \|q - y^*\|^2. \]  \hspace{1cm} (3.10)

Similarly, we have

\[ W(p, q) = W(x^*, y^*) + \|p - x^*\|^2 + \|q - y^*\|^2. \]  \hspace{1cm} (3.11)

It follows from (3.10) and (3.11) that

\[ \|p - x^*\|^2 + \|q - y^*\|^2 = 0, \]

which means that \((p, q) = (x^*, y^*)\). The proof of conclusion (I) is completed.

Next, we prove (II). Due to \(S_1, S_2\) are semi-compact, \(\{(x_n, y_n)\}\) is bounded and \(\lim_{n \to \infty} d(t_n, S_1 t_n) = 0\) and \(\lim_{n \to \infty} d(w_n, S_2 w_n) = 0\), there exists subsequence \(\{(t_{n_j}, w_{n_j})\}\) such that \(\{(t_{n_j}, w_{n_j})\}\) converges strongly to \((u^*, v^*)\). So, from the facts that \(\lim_{n \to \infty} \|x_n - t_n\| = 0\) and \(\lim_{n \to \infty} \|y_n - w_n\| = 0\), and \(\{(x_n, y_n)\}\) converges weakly to \((x^*, y^*)\), we know that \((u^*, v^*) = (x^*, y^*)\). In addition, due to the definition of \(\{(t_{n_j}, w_{n_j})\}\) and

\[ \|x_{n_j} - x^*\| = \|x_{n_j} - t_{n_j} + t_{n_j} - x^*\| \leq \|\gamma J_1^{-1} A^* J_3(A x_{n_j} - B y_{n_j})\| + \|t_{n_j} - x^*\| \leq \gamma \|A\| \|A x_{n_j} - B y_{n_j}\| + \|t_{n_j} - x^*\|, \]

and

\[ \|y_{n_j} - y^*\| = \|y_{n_j} - w_{n_j} + w_{n_j} - y^*\| \leq \|\gamma J_2^{-1} B^* J_3(A x_{n_j} - B y_{n_j})\| + \|w_{n_j} - y^*\| \leq \gamma \|B\| \|A x_{n_j} - B y_{n_j}\| + \|w_{n_j} - y^*\|, \]

we obtain that \(\lim_{n \to \infty} \|x_{n_j} - x^*\| = 0\) and \(\lim_{n \to \infty} \|y_{n_j} - y^*\| = 0\).

On the other hand, since \(W_n(x, y) = \|x - x\|^2 + \|y_n - y\|^2\) for any \((x, y) \in \Omega\), we know that \(\lim_{n \to \infty} W_n(x^*, y^*) = 0\). From Conclusion (I), we know that \(\lim_{n \to \infty} W_n(x^*, y^*) = 0\). Therefore, \(\lim_{n \to \infty} W_n(x^*, y^*) = 0\). From the facts that \(0 \leq \|x_n - x^*\| \leq W_n\) and \(0 \leq \|y_n - y^*\| \leq W_n\), we can obtain that \(\lim_{n \to \infty} \|x_n - x^*\| = 0\) and \(\lim_{n \to \infty} \|y_n - y^*\| = 0\). This completes the proof of the conclusion (II).

For quasi-nonexpansive single-valued mappings, similar to the proofs in Theorem 3.1, we can obtain the following result.

**Theorem 3.2.** Let \(E_1, E_2\) be real uniformly convex and 2-uniformly smooth Banach spaces with the best smoothness constant \(k \in (0, \frac{1}{\sqrt{2}}]\), \(E_3\) be a real Banach space, and \(S_1 : E_1 \to E_1\) and \(S_2 : E_2 \to E_2\) be two quasi-nonexpansive single-valued mappings, respectively. Let \(A : E_1 \to E_3\) and \(B : E_2 \to E_3\) be two bounded linear operators. For any \(x_0 \in E_1\) and \(y_0 \in E_2\), the sequence \(\{(x_n, y_n)\}\) is generated by

\[
\begin{cases}
u_n = S_1(x_n - \gamma J_1^{-1} A^* J_3(A x_n - B y_n)), \\
u_n = S_2(y_n + \gamma J_2^{-1} B^* J_3(A x_n - B y_n)), \\
y_{n+1} = (1 - \beta_n) v_n + \beta_n (x_n + \gamma J_2^{-1} B^* J_3(A x_n - B y_n)), \\
x_{n+1} = (1 - \beta_n) u_n + \beta_n (x_n - \gamma J_1^{-1} A^* J_3(A x_n - B y_n)),
\end{cases}
\]

where \(S_1, S_2\) are demi-closed at zero, \(\{\beta_n\} \subseteq (0, 1)\) satisfying \(\liminf_{n \to \infty} \beta_n (1 - \beta_n) > 0\), \(0 < \gamma < \frac{1}{\max(\lambda_A, \lambda_B)}\) and \(\lambda_A, \lambda_B\) stand for the spectral radius of \(A^* A\) and \(B^* B\), respectively. If \(\Gamma = \{(x^*, y^*) \in E_1 \times E_2 : A x^* = B y^*, x^* \in C, y^* \in D\} \neq \emptyset\), where \(C \coloneqq \text{Fix}(S_1), Q \coloneqq \text{Fix}(S_2)\), then
(I) the sequence \( \{ (x_n, y_n) \} \) converges weakly to a solution \( (x^*, y^*) \in \Gamma \) of SEP \((1.3)\);

(II) In addition, if \( S_1, S_2 \) are semi-compact, then the sequence \( \{ (x_n, y_n) \} \) converges strongly to a solution \( (x^*, y^*) \in \Gamma \) of SEP \((1.3)\).

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References


